

**Math 310, Fall 2015**  
**Instructor: Chris Skalit**  
**Exam 1**

Write your **FULL NAME** and **UIN** in all of your answer books. Show **ALL** work.

1. (20 points) Find all solutions to the following system of linear equations:

$$\begin{array}{rccccrcr} 2x_1 & + & x_2 & & & = & 0 \\ 2x_1 & + & 2x_2 & & & = & 2 \\ 3x_1 & + & 2x_2 & + & x_3 & = & 2 \\ 4x_1 & & & + & 3x_3 & = & -1 \end{array}$$

**Solution:** The augmented matrix for this system is

$$B = \left[ \begin{array}{ccc|c} 2 & 1 & 0 & 0 \\ 2 & 2 & 0 & 2 \\ 3 & 2 & 1 & 2 \\ 4 & 0 & 3 & -1 \end{array} \right]. \text{ Since } \text{rref } B = \left[ \begin{array}{ccc|c} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right], \text{ we have } x_1 = -1, x_2 = 2, \text{ and } x_3 = 1 \text{ as our unique solution.}$$

2. Let  $A = \begin{bmatrix} 2 & 0 & 4 & 6 \\ 1 & 1 & -1 & -1 \\ 4 & 2 & 2 & 4 \end{bmatrix}$ .

- (a) (10 points) Find all  $\mathbf{x} \in \mathbb{R}^4$  such that  $A\mathbf{x} = \mathbf{0}$ . Write your solution in vector parametric form.

**Solution:** Recall that if  $B = \text{rref } A$ , we have  $B\mathbf{x} = \mathbf{0}$  if and only if  $A\mathbf{x} = \mathbf{0}$ . Since

$$B = \text{rref } A = \begin{bmatrix} 1 & 0 & 2 & 3 \\ 0 & 1 & -3 & -4 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \text{ we see that in the homogeneous system}$$

$$\begin{bmatrix} 1 & 0 & 2 & 3 \\ 0 & 1 & -3 & -4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$x_1 = -2x_3 - 3x_4$  and  $x_2 = 3x_3 + 4x_4$  with  $x_3$  and  $x_4$  free. We can therefore write our solutions as

$$\mathcal{S} = \left\{ \begin{bmatrix} -2x_3 - 3x_4 \\ 3x_3 + 4x_4 \\ x_3 \\ x_4 \end{bmatrix} : x_3, x_4 \in \mathbb{R} \right\} = \left\{ x_3 \begin{bmatrix} -2 \\ 3 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -3 \\ 4 \\ 0 \\ 1 \end{bmatrix} : x_3, x_4 \in \mathbb{R} \right\}$$

- (b) (5 points) If  $\mathbf{b} = \begin{bmatrix} 2 \\ 2 \\ 6 \end{bmatrix}$ , use your solution to part (a) to find all solutions to  $A\mathbf{x} = \mathbf{b}$ .

**Hint:** Note that  $\mathbf{x}_0 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$  is a solution.

**Solution:** Recall that all solutions  $\mathbf{w}$  to  $A\mathbf{x} = \mathbf{b}$  are of the form  $\mathbf{w} = \mathbf{x}_0 + \mathbf{v}$  where  $\mathbf{v}$  is a solution to the homogeneous system  $A\mathbf{x} = \mathbf{0}$ . Thus our solution set is

$$\mathcal{S} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -2 \\ 3 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -3 \\ 4 \\ 0 \\ 1 \end{bmatrix} : x_3, x_4 \in \mathbb{R} \right\}$$

- (c) (5 points) Does there exist a  $\mathbf{v} \in \mathbb{R}^3$  such that the linear system  $A\mathbf{x} = \mathbf{v}$  is **inconsistent**? Explain why or why not.

**Solution:** We know that  $A\mathbf{x} = \mathbf{v}$  is consistent for all  $\mathbf{v} \in \mathbb{R}^3$  if and only if the columns of  $A$  span  $\mathbb{R}^3$ . This, however, is equivalent to saying that every ROW of rref  $A$  contains a pivot. Since this is not the case, we know that we can find a  $\mathbf{v}$  for which  $A\mathbf{x} = \mathbf{v}$  is inconsistent.

3. (a) (5 points) Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be a linear map defined via  $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} x + 2y \\ y - x \\ 3x \end{bmatrix}$ .

Write down the matrix  $H$  such that  $T(\mathbf{x}) = H\mathbf{x}$  for all  $\mathbf{x} \in \mathbb{R}^2$ .

**Solution:** The columns of  $H$  are just  $T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right)$  and  $T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right)$ . Thus,  $H = \begin{bmatrix} 1 & 2 \\ -1 & 1 \\ 3 & 0 \end{bmatrix}$ .

- (b) (10 points) Let  $S : \mathbb{R}^3 \rightarrow \mathbb{R}^4$  be defined by  $S(\mathbf{x}) = B\mathbf{x}$  where  $B = \begin{bmatrix} 3 & 3 & -3 \\ -2 & 0 & 1 \\ 0 & 0 & 2 \\ 2 & 1 & -1 \end{bmatrix}$ .

Determine whether  $S$  is one-to-one and/or onto. Justify your answer.

**Solution:** rref  $B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ . Since there is a pivot in every column,  $S$  is one-to-one. Since there isn't a pivot in every row,  $S$  is NOT onto.

- (c) (10 points) Let  $Q : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a linear transformation such that

$$Q\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad Q\left(\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

Compute  $Q\left(\begin{bmatrix} 5 \\ 1 \end{bmatrix}\right)$ . **Hint:** It will be helpful (and good for partial credit) to first

find constants  $a, b \in \mathbb{R}$  such that  $\begin{bmatrix} 5 \\ 1 \end{bmatrix} = a \begin{bmatrix} 1 \\ 2 \end{bmatrix} + b \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ .

**Solution:** Finding  $a$  and  $b$  amounts to solving the system

$$\begin{aligned} a + b &= 5 \\ 2a - b &= 1 \end{aligned}$$

and we see that  $a = 2$  and  $b = 3$ . We now compute

$$Q\left(\begin{bmatrix} 5 \\ 1 \end{bmatrix}\right) = Q\left(2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ -1 \end{bmatrix}\right) = 2Q\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) + 3Q\left(\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right) = \begin{bmatrix} 8 \\ 3 \end{bmatrix}$$

4. (a) (7 points) Compute the matrix product or explain why the product is undefined.

(i)  $\begin{bmatrix} 1 & 2 \\ -1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 0 \end{bmatrix}$

**Solution:**

$$\begin{bmatrix} 1 & 2 \\ -1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 0 \end{bmatrix} = \begin{bmatrix} 7 & 2 \\ -1 & -2 \\ 4 & 2 \end{bmatrix}$$

(ii)  $\begin{bmatrix} 1 & 2 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ -1 & 0 \\ 1 & 1 \end{bmatrix}$

**Solution:** Undefined. The number of columns of the matrix on the left is not equal to the number of rows of the matrix on the right.

(b) (13 points) Let  $D = \begin{bmatrix} -1 & -1 & 0 \\ 2 & 1 & 0 \\ 5 & 1 & 1 \end{bmatrix}$ . Find  $D^{-1}$  (if it exists).

**Solution:** We set  $E = \left[ \begin{array}{ccc|ccc} -1 & -1 & 0 & 1 & 0 & 0 \\ 2 & 1 & 0 & 0 & 1 & 0 \\ 5 & 1 & 1 & 0 & 0 & 1 \end{array} \right]$  and compute

$$\text{rref } E = \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & -2 & -1 & 0 \\ 0 & 0 & 1 & -3 & -4 & 1 \end{array} \right]. \text{ Thus, } D^{-1} = \begin{bmatrix} 1 & 1 & 0 \\ -2 & -1 & 0 \\ -3 & -4 & 1 \end{bmatrix}.$$

(c) (5 points) Are the columns of  $D$  linearly independent? Why or why not?

**Solution:** Since  $D$  is invertible, its columns are linearly independent.

5. (10 points) Let  $C = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 3 & 1 \end{bmatrix}$ . Compute the  $LU$  decomposition of  $C$ . That is, find

matrices of the form  $L = \begin{bmatrix} 1 & 0 & 0 \\ * & 1 & 0 \\ * & * & 1 \end{bmatrix}$  and  $U = \begin{bmatrix} * & * & * \\ 0 & * & * \\ 0 & 0 & * \end{bmatrix}$  such that  $C = LU$ .

**Solution:** We begin by reducing  $C$  to an upper-triangular matrix  $U$ :

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 3 & 1 \end{bmatrix} \xrightarrow{R2 \rightarrow R2 - R1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 3 & 1 \end{bmatrix} \xrightarrow{R3 \rightarrow R3 - 3R2} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = U$$

We now take the  $3 \times 3$  identity matrix and apply the inverse of these operations in the reverse order:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R3 \rightarrow R3 + 3R2} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 3 & 1 \end{bmatrix} \xrightarrow{R2 \rightarrow R2 + R1} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 3 & 1 \end{bmatrix} = L$$