

**Math 310 (35180), Fall 2015**  
**Instructor: Chris Skalit**  
**Quiz 8**

Name: \_\_\_\_\_ UIN: \_\_\_\_\_

1. (4 points) Let  $V$  be a vector space with bases  $\mathcal{A} = \{\mathbf{u}_1, \mathbf{u}_2\}$  and  $\mathcal{B} = \{\mathbf{v}_1, \mathbf{v}_2\}$ . Suppose that

$$\mathbf{u}_1 = \mathbf{v}_1 - \mathbf{v}_2 \quad \mathbf{u}_2 = \mathbf{v}_1 - 2\mathbf{v}_2$$

Find the change of coordinates matrix  $P_{\mathcal{A} \rightarrow \mathcal{B}}$  from  $\mathcal{A}$  to  $\mathcal{B}$  and compute the change of coordinates matrix  $P_{\mathcal{B} \rightarrow \mathcal{A}}$  from  $\mathcal{B} \rightarrow \mathcal{A}$ .

**Solution:** We have the basis vectors of  $\mathcal{A}$  written in terms of  $\mathcal{B}$ , so we can write down

$$P_{\mathcal{A} \rightarrow \mathcal{B}} = [[\mathbf{u}_1]_{\mathcal{B}} \quad [\mathbf{u}_2]_{\mathcal{B}}] = \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}$$

The other change of coordinates matrix is just the inverse:

$$P_{\mathcal{B} \rightarrow \mathcal{A}} = (P_{\mathcal{A} \rightarrow \mathcal{B}})^{-1} = \begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix}$$

2. (3 points) Let  $A = \begin{bmatrix} 2 & 1 & 2 \\ 0 & 1 & 0 \\ 1 & 1 & 3 \end{bmatrix}$ . Compute the characteristic polynomial and find all eigenvalues of  $A$ .

**Solution:**  $P_A(t) = \det(A - tI) = \det \left( \begin{bmatrix} 2-t & 1 & 2 \\ 0 & 1-t & 0 \\ 1 & 1 & 3-t \end{bmatrix} \right)$ . By expanding the determinant along the second row, we have

$$P_A(t) = (1-t)[(2-t)(3-t) - 2] = (1-t)[t^2 - 5t + 4] = (1-t)(1-t)(4-t).$$

Hence, our eigenvalues are 1 (with an algebraic multiplicity of two) and 4 (with an algebraic multiplicity of one).

3. (3 points) Let  $B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ . Compute the eigenspace  $E_1$  corresponding to the eigenvalue 1.

**Solution:**  $E_1 = \text{Nul}(A - 1I) = \text{Nul}\left(\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}\right) = \text{Nul}\left(\begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}\right)$ . In other words,  $E_1$  is just the solution set of the homogeneous system

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

so  $x_1 = -x_2$ ,  $x_3 = 0$ , and  $x_2$  is free. Hence,

$$E_1 = \left\{ \begin{bmatrix} -x_2 \\ x_2 \\ 0 \end{bmatrix} : x_2 \in \mathbb{R} \right\} = \text{span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \right\}.$$