

**Math 442 - Differential Geometry of Curves and Surfaces**  
**Challenge Problems**

Version 2009-03-30  
David Dumas

- (C1) Describe all curves on the unit sphere with constant torsion. Are any of them closed? (Hint: Begin with the case  $\tau = 0$ .)
- (C2) Generalize the Frenet frame and the Frenet equations to  $\mathbb{R}^4$  as follows.

Let  $\alpha : I \rightarrow \mathbb{R}^3$  be a differentiable curve (not necessarily parameterized by arc length) such that for all  $t \in I$ , the vectors  $(\alpha'(t), \alpha''(t), \alpha'''(t))$  form a basis of  $\mathbb{R}^3$ .

- (a) Apply the Gram-Schmidt algorithm to this basis to obtain an orthonormal basis; show that the Frenet vectors, curvature, and torsion all appear as part of this calculation.
- (b) Now suppose  $\alpha : I \rightarrow \mathbb{R}^4$  is a differentiable curve. Use the results of (a) to generalize the Frenet frame to this case, obtaining an orthonormal basis of  $\mathbb{R}^4$  adapted to the curve. Find three curvature-like functions that play the same role as  $\kappa, \tau$  in the 3-dimensional case, and write the four Frenet differential equations that the frame vectors obey.
- (C3) Let  $\alpha : I \rightarrow \mathbb{R}^3$  be a differentiable curve parameterized by arc length, with curvature  $\kappa_\alpha(s) \neq 0$  and torsion  $\tau_\alpha(s)$ . For each  $s \in I$ , let  $\beta(s)$  denote the center of the osculating circle of  $\alpha$  at  $\alpha(s)$ .
- (a) Compute the speed  $|\beta'(s)|$ , curvature  $\kappa_\beta(s)$ , and torsion  $\tau_\beta(s)$  of the curve  $\beta$ . (*Warning:  $s$  is not necessarily the arc length parameter for  $\beta$ !*)
- (b) Find a particular curve  $\alpha$  so that the new curve  $\beta$  is “the same”, i.e. related to  $\alpha$  by a rotation and/or translation.
- (C4) (a) Let  $\alpha : I \rightarrow \mathbb{R}^3$  be a differentiable curve that lies on the unit sphere (i.e.  $|\alpha(s)| = 1$  for all  $s \in I$ ). Show that  $\kappa(s) \geq 1$  for all  $s \in I$ .
- (b) Suppose instead that  $\alpha$  lies on the ellipsoid  $ax^2 + by^2 + cz^2 = 1$ , where  $a, b, c > 0$ . What is the minimum possible value for the curvature?
- (C5) Let  $\alpha : I \rightarrow \mathbb{R}^2$  be a differentiable plane curve with positive, increasing curvature (i.e.  $\kappa(s), \kappa'(s) > 0$ ).
- (a) Show that the osculating circles of  $\alpha$  are nested, meaning that if  $s' > s$ , then the osculating circle at  $\alpha(s')$  is contained in the osculating circle at  $\alpha(s)$ .
- (b) From (a) it follows that the osculating circles fill an open set  $U \subset \mathbb{R}^2$  that contains the trace of  $\alpha$ . Let  $V$  be the unit vector field in  $U$  that is tangent to these circles, and which always points counter-clockwise. Then each of the osculating circles is tangent to this  $V$ , as is the curve  $\alpha$  itself. Why is this surprising? What is going on?

*Hint: A curve whose tangent vector is always horizontal is a horizontal line. There is only one horizontal line through any given point.*

- (C6) For every natural number  $g$ , find a polynomial  $P_g(x, y, z)$  with the property that  $P_g^{-1}(1)$  is a regular surface in  $\mathbb{R}^3$  of genus  $g$ . (In particular, you should come up with some way to recognize the genus of a closed surface in  $\mathbb{R}^3$ .)

- (C7) What is the minimum degree of a polynomial  $P(x, y, z)$  such that  $P^{-1}(1)$  is a regular surface of positive genus?
- (C8) Let  $f(x, y)$  be a smooth function of two variables. How can you use  $f$  and its derivatives to determine whether or not  $z = f(x, y)$  is (locally) a ruled surface? (Your condition should be *pointwise*, meaning that you are not allowed to compare values or derivatives at different points. Hint: If  $(x_0, y_0)$  is a local maximum or local minimum, then the graph cannot be ruled.)
- (C9) Let  $\alpha(\theta)$  and  $\beta(\theta)$  denote a pair of circles in  $\mathbb{R}^3$  parameterized with constant speed by  $\theta \in [0, 2\pi]$ . (Note that a circle in  $\mathbb{R}^3$  is defined as the set of all points in a plane that lie a fixed distance from some point in that plane.) Describe the scroll generated by  $\alpha$  and  $\beta$  in a way that does not depend on a parameterization, e.g. find a function  $F(x, y, z)$  so that the scroll consists of points satisfying  $F(x, y, z) = 0$ .
- (C10) Consider the parabola  $P = \{y = x^2\}$  in the plane. Let  $p(s)$  denote an arc length parameterization of  $P$  with  $p(0) = (0, 0)$  and  $p'(0) = (1, 0)$ . Let  $T(s)$  be the tangent line to  $P$  at  $p(s)$ . For any  $s \in \mathbb{R}$ , apply a rotation and translation so that  $p(s)$  is sent to  $(s, 0)$  and  $T(s)$  becomes the  $x$  axis; call the resulting parabola  $P(s)$ . We say  $P(s)$  is the result of *rolling  $P$  along the  $x$  axis*.
- Given a point  $q$  in  $\mathbb{R}^2$ , we can form a path  $q(s)$  by applying the same rotation and translation to  $q$  as is used to transform  $P$  into  $P(s)$ . (Think of  $q$  as being “rigidly attached” to  $P$ , so it moves as  $P$  rolls.) Show that if  $q = (0, 1/4)$ , then  $q(s)$  is a catenary.
- (C11) Find a parameterization of the path traced out by one focus of an elliptical object as it rolls along the  $x$  axis without slipping. Your parameterization may need to use functions defined in terms of integrals that cannot be evaluated explicitly.
- (C12) Show that the surface of rotation of the curve described in the previous problem has constant mean curvature.
- (C13) Show that any embedded curve in  $\mathbb{R}^2$  with closed image is a flow line of a vector field. That is, let  $\alpha : [0, 1] \rightarrow \mathbb{R}^2$  be an injective differentiable map with  $\alpha'(t) \neq 0$  for  $t \in [0, 1]$ . Show that there is a vector field  $W$  defined on a neighborhood of  $\alpha([0, 1])$  such that  $\alpha([0, 1])$  is a flow line of  $W$ . (*The local version of this problem is P9 on the weekly problem list.*)
- (C14) Let  $S \subset \mathbb{R}^3$  be a regular surface with no umbilic points, and let  $\alpha : I \rightarrow S$  be a line of curvature of  $S$  corresponding to the principal curvature function  $k_1$ . Consider  $\alpha$  as a space curve and calculate its curvature in terms of  $k_1$ ,  $k_2$ , and their covariant derivatives.