## Chain Rule

One Independent Variable  $z = z(x, y), \quad x = x(t), \quad y = y(t)$  $\frac{dz}{dt} = \frac{\partial z}{\partial x}\frac{dx}{dt} + \frac{\partial z}{\partial y}\frac{dy}{dt}$  **Two Independent Variables**   $z = z(x, y), \quad x = x(s, t), \quad y = y(s, t)$   $\frac{\partial z}{\partial s} = \frac{\partial z}{\partial x}\frac{\partial x}{\partial s} + \frac{\partial z}{\partial y}\frac{\partial y}{\partial s}$  $\frac{\partial z}{\partial t} = \frac{\partial z}{\partial x}\frac{\partial x}{\partial t} + \frac{\partial z}{\partial y}\frac{\partial y}{\partial t}$ 

## Implicit Differentiation

If F(x, y) = 0 and  $F_y \neq 0$  then

$$\frac{dy}{dx} = -\frac{F_x}{F_y}$$

Gradient

Two Dimensions	Three Dimensions
$\nabla f(x,y) = \langle f_x(x,y), f_y(x,y) \rangle$	$\nabla f(x, y, z) = \langle f_x(x, y, z), f_y(x, y, z), f_z(x, y, z) \rangle$

#### **Directional Derivative**

f differentiable at (a, b) and **u** a unit vector,

$$D_{\mathbf{u}}f(a,b) = \nabla f(a,b) \cdot \mathbf{u}$$

# Tangent Plane of level surface F(x, y, z) = 0 at (a, b, c)

$$F_x(a, b, c)(x - a) + F_y(a, b, c)(x - b) + F_z(a, b, c)(x - c) = 0$$

of function z = f(x, y) at point (a, b, f(a, b))

$$z = f_x(a,b)(x-a) + f_y(a,b)(y-b) + f(a,b)$$

## Second Derivative Test

Let  $D(x,y) = f_{xx}f_{yy} - f_{xy}^2$ .

- 1. If D(a,b) > 0 and  $f_{xx}(a,b) < 0$ , then f has a local max at (a,b).
- 2. If D(a,b) > 0 and  $f_{xx}(a,b) > 0$ , then f has a local min at (a,b).
- 3. If D(a,b) < 0, then f has a saddle point at (a,b).
- 4. If D(a, b) = 0, then the test is inconclusive.

#### Lagrange Multipliers

f is optimization function, g is the constraint, f and g are differentiable with  $\nabla g(x, y) \neq 0$ on the curve g(x, y) = 0. To locate maximum and minimum values of f subject to the constraint g(x, y) = 0:

1. Solve for x, y and  $\lambda$ :

$$\nabla f(x,y) = \lambda \nabla g(x,y)$$
 and  $g(x,y) = 0$ 

2. Among the values (x, y) from step 1, calculate the max and min.

**Note:** For three dimensions, solve  $\nabla f(x, y, z) = \lambda \nabla g(x, y, z)$  and g(x, y, z) = 0.

### **Double Integrals in Rectangular Coordinates**

R is region bounded below and above by y = g(x) and y = h(x), respectively, and on the left and right by the lines x = a and x = b, respectively. If f is continuous on R then

$$\iint\limits_R f(x,y) \ dA = \int_a^b \int_{g(x)}^{h(x)} f(x,y) \ dy \ dx$$

R is region bounded on the left and right by x = g(y) and x = h(y), respectively, and below and above by the lines y = c and y = d, respectively. If f is continuous on R then

$$\iint\limits_R f(x,y) \ dA = \int_c^d \int_{g(y)}^{h(y)} f(x,y) \ dx \ dy$$

## **Double Integral in Polar Coordinates**

f is continuous in  $R = \{(r, \theta) : 0 \le g(\theta) \le r \le h(\theta), \alpha \le \theta \le \beta\}$ . Then

$$\iint\limits_{R} f(r,\theta) \ dA = \int_{\alpha}^{\beta} \int_{g(\theta)}^{h(\theta)} f(r,\theta) r \, dr \, d\theta$$

## Triple Integral in Rectangular Coordinates

f continuous in  $D = \{(x, y, z) : a \le x \le b, g(x) \le y \le h(x), G(x, y) \le z \le H(x, z)\}$ 

$$\iiint_{D} f(x,y) \ dV = \int_{a}^{b} \int_{g(x)}^{h(x)} \int_{G(x,y)}^{H(x,y)} f(x,y,z) \ dx \ dy \ dz$$

## Triple Integral in Cylindrical Coordinates

 $f \text{ continuous in } D = \{(r, \theta, z) : g(\theta) \le r \le h(\theta), \ \alpha \le \theta \le \beta, \ G(x, y) \le z \le H(x, z)\}$ 

$$\iiint\limits_{D} f(x,y) \ dV = \int_{\alpha}^{\beta} \int_{g(\theta)}^{h(\theta)} \int_{G(r\cos\theta, r\sin\theta)}^{H(r\cos\theta, r\sin\theta)} f(r,\theta,z) \ dz \ r \ dr \ d\theta$$

Triple Integral in Spherical Coordinates f continuous in  $D = \{(\rho, \varphi, \theta) : g(\varphi, \theta) \le \rho \le h(\varphi, \theta), a \le \varphi \le b, \alpha \le \theta \le \beta\}$ 

$$\iiint_{D} f(x,y) \ dV = \int_{\alpha}^{\beta} \int_{a}^{b} \int_{g(\varphi,\theta)}^{h(\varphi,\theta)} f(\rho,\varphi,\theta) \rho^{2} \sin\varphi \, d\rho \, d\varphi \, d\theta$$

Note:

$$\rho^2 = x^2 + y^2 + z^2$$
  $x = \rho \sin \varphi \cos \theta$   $y = \rho \sin \varphi \sin \theta$   $z = \rho \cos \varphi$