

## 1 Vector Spaces- 9-27-06

A set  $V$  is called a vector space if:

I. For each  $x, y \in V$ ,  $x + y$  is an element of  $V$ .

(Addition)

II. For each  $x \in V$  and  $a \in \mathbb{R}$ ,  $ax$  is an element of  $V$ .

(Multiplication by scalar)

The two operations satisfy the following laws:

A1.  $x + y = y + x$ , commutative law

A2.  $(x + y) + z = x + (y + z)$ , associative law

A3.  $x + 0 = x$  for each  $x$ , neutral element  $0$

A4.  $x + (-x) = 0$ , unique anti element

A5.  $a(x + y) = ax + ay$  for each  $x, y$ , distributive law

A6.  $(a + b)x = ax + bx$ , distributive law

A7.  $(ab)x = a(bx)$ , distributive law

A8.  $1x = x$ .

corollary:  $0x = 0$  neutral element:

$0x = (0 + 0)x = 0x + 0x \Rightarrow$

$0 = 0x - 0x = (0x + 0x) - 0x = 0x$ .

Examples:

1.  $\mathbb{R}$  - Real Line
2.  $\mathbb{R}^2$  = Plane
3.  $\mathbb{R}^3$  - Three dimensional space
4.  $\mathbb{R}^n$  -  $n$ -dimensional space
5.  $\mathbb{R}^{m \times n}$  - Space of  $m \times n$  matrices
6. Spaces of upper triangular, lower triangular and diagonal matrices
7.  $\mathcal{P}_n$  - Space of polynomials of degree less than  $n$ :  
 $\mathcal{P}_n := \{p(x) = a_{n-1}x^{n-1} + a_{n-2}x^{n-2} + \dots + a_1x + a_0\}$ .
8.  $C[a, b]$  - Space of continuous functions on the interval  $[a, b]$ .

Note. The examples 1 - 7 are finite dimensional vector spaces. 8 - is infinite dimensional vector space.

Note. In this course all vector spaces are finite dimensional and isomorphic to  $\mathbb{R}^n$  (or  $\mathbb{C}^n$  as in Chapter 6).

### Additional Properties of Vector Spaces

Use the vector space axioms to prove these three properties.

(i)  $0x = 0$ .

(ii)  $x + y = 0$  implies  $y = -x$ .

(iii)  $(-1)x = -x$ .

**Proof of (i):** Axioms A6 and A8 tell us that

$$x = 1x = (1 + 0)x = 1x + 0x = x + 0x. \text{ Thus}$$

$$-x + x = -x + (x + 0x) = (-x + x) + 0x \text{ (A2).}$$

Thus  $0 = 0 + 0x = 0x$ , proving (i).

**Proof of (ii):** Suppose  $x + y = 0$ . Then

$$-x = -x + 0 = -x + (x + y).$$

Therefore,  $-x = (-x + x) + y = 0 + y = y$  by A1, A2, A3, and A4.

**Proof of (iii):** From part (i) and A6, we know that

$$0 = 0x = (1 + (-1))x = 1x + (-1)x.$$

Thus by A8,  $x + (-1)x = 0$ .

So from part (ii), this tells us that  $(-1)x = -x$ .

## §3.2 Subspaces

Let  $V$  be a vector space. A subset  $W$  of  $V$  is called a subspace of  $V$  if the following three conditions hold:

- (i)  $W$  is nonempty,
- (ii) for any  $x, y \in W \Rightarrow x + y \in W$ ,
- (iii) for any  $x \in W, a \in \mathbb{R} \Rightarrow ax \in W$ .

Equivalently:  $W \subset V$  is a subspace  $\iff W$  is a vector space with respect to the addition and the multiplication by a scalar defined in  $V$ .

In other words,  $W$  is a vector space by itself!

Note: The zero vector  $0 \in W$  always.

Proof: By (i) we know  $W$  is nonempty, so it contains a vector. (We'll call this vector  $x$ .) By (iii), we know that  $0x \in W$ . But  $0x = 0$ , so  $0 \in W$ .

Every vector space  $V$  has the following two "non-proper" subspaces:

1.  $V$ .
2. The trivial subspace consisting of the zero element:  
 $W = \{0\}$ .

### Examples of subspaces

1. Subspaces of the plane  $\mathbb{R}^2$ :

- the whole space, ● lines through the origin\*,
- the trivial subspace =  $\{0\}$ .

\*Remember, we think of vectors as segments from the origin to an endpoint. Thus by a "line," we mean the **set of vectors** whose **endpoints** lie on the line.

2. Subspaces of 3-dimensional space  $\mathbb{R}^3$ :

- the whole space, ● planes through the origin,
- lines through the origin, ● the trivial subspace.

(Read many more examples in the text.)

Note: If we already know that  $V$  is a subspace, then to show that  $W \subset V$  is a subspace only requires showing  $W$  is: (i) nonempty, (ii) closed under scalar multiplication, and (iii) closed under addition.

We DON'T have to check all 8 axioms, because we know the axioms already held for everything in the bigger space  $V$ !

So what's NOT a subspace?

One example: A line that does not go through the origin.

Important example of a subspace:

### The **nullspace**

Let  $A \in \mathbb{R}^{m \times n}$ . The **nullspace** of  $A$ , denoted  $N(A)$ , is a subspace of  $\mathbb{R}^n$  consisting of all vectors  $x \in \mathbb{R}^n$  such that  $Ax = 0$ .

Why is  $N(A)$  a subspace?

- $0 \in N(A)$ , so it is nonempty.
- For  $x \in N(A)$  and  $\alpha \in \mathbb{R}$ ,  
 $A(\alpha x) = \alpha Ax = \alpha 0 = 0$ . Thus  $\alpha x \in N(A)$ .
- For  $x, y \in N(A)$ , then  
 $A(x + y) = Ax + Ay = 0 + 0 = 0$ .  
Thus  $x + y \in N(A)$ .

Find  $N(A)$  for  $A = \begin{pmatrix} 1 & 0 & -1 & 1 \\ 0 & 1 & 2 & -1 \end{pmatrix}$ .

$$N(\mathbf{A}) = \alpha \begin{pmatrix} 1 \\ -2 \\ 1 \\ 0 \end{pmatrix} + \beta \begin{pmatrix} -1 \\ 1 \\ 0 \\ 1 \end{pmatrix}$$

In general, to find  $N(\mathbf{A})$ , row reduce  $\mathbf{A}$  first.

SUMMARY for finding Nullspace

- Row Reduce.
- Find Free variables.
- Solve for Dependent variables in terms of free variables.
- Put answer in set notation.

## 2 Linear combination & span 9-29-06

Let  $\mathbf{v}_1, \dots, \mathbf{v}_k \in \mathbf{V}$  and  $a_1, \dots, a_k \in \mathbb{R}$ .

The vector  $a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + \dots + a_k\mathbf{v}_k$

is called a **linear combination** of  $\mathbf{v}_1, \dots, \mathbf{v}_k$ .

The set of **all** linear combinations of  $\mathbf{v}_1, \dots, \mathbf{v}_k$  is called the **span** of  $\mathbf{v}_1, \dots, \mathbf{v}_k$  and denoted by  $\text{span}(\mathbf{v}_1, \dots, \mathbf{v}_k)$ .

Note:  $\text{span}(\mathbf{v}_1, \dots, \mathbf{v}_k)$  is a linear subspace of  $\mathbf{V}$ .

Fact: All subspaces in a finite dimensional vector space can be written as  $\text{span}(\mathbf{v}_1, \dots, \mathbf{v}_k)$  for some corresponding vectors  $\mathbf{v}_1, \dots, \mathbf{v}_k$ .

Examples:

1. Any line through the origin in **1**, **2**, or **3** dimensional space is spanned by any nonzero vector on the line.
2. Any plane through the origin in **2** or **3** dimensional space is spanned by any two nonzero vectors not lying on a line, i.e. non collinear vectors.
3.  $\mathbb{R}^3$  spanned by any **3** non planar vectors.

The set  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  is a **spanning set** for  $V$  if and only if every vector in  $V$  can be written as a linear combination of  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ .

Example:  $\mathbb{R}^3$ . We define the standard vectors:

$$\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \mathbf{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

The set  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$  is a spanning set for  $\mathbb{R}^3$ .

The set  $\left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$  is not a spanning set for  $\mathbb{R}^3$ .