

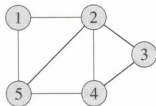
Computer Algorithms I, Spring 2020

Graphs review, breadth-first search

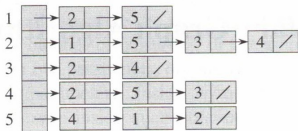
March 30, April 1

- ▶ review of basic graph concepts
- ▶ breadth-first search (BFS)

How to represent a graph?



(a)

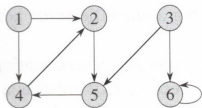


(b)

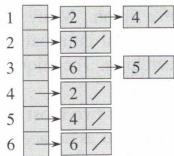
	1	2	3	4	5
1	0	1	0	0	1
2	1	0	1	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0

(c)

Figure 22.1 Two representations of an undirected graph. (a) An undirected graph G with 5 vertices and 7 edges. (b) An adjacency-list representation of G . (c) The adjacency-matrix representation of G .



(a)



(b)

	1	2	3	4	5	6
1	0	1	0	1	0	0
2	0	0	0	0	1	0
3	0	0	0	0	1	1
4	0	1	0	0	0	0
5	0	0	0	1	0	0
6	0	0	0	0	0	1

(c)

Graph basics

graphs: Appendix B.4 (pages 1168-1172), trees: Appendix B.5.1, B.5.2 (pages 1173-1177)

adjacency matrices - for **dense** graphs (e.g., all edges present - complete graph)

adjacency lists - for **sparse** graphs (e.g., $O(n)$ edges, note: large networks are sparse)

weights - edges can also have numbers assigned to them, e.g., distance, cost

notation of **attributes**: e.g., $u.color$ is the color of vertex u

path: $\langle a, b, c, d, e \rangle$: $(a, b), (b, c), (c, d), (d, e)$ are all edges of the graph

length of path: number of edges

shortest path between u and v : path of minimal length from u to v

distance of u and v : length of shortest path between them

Graph searches

for many graph algorithms we need to **process** the vertices by **visiting** them in some order

with an adjacency list, we could simply go through the array of vertices - but that is arbitrary

better solutions: visit the vertices in some “natural” order, related to the graph itself

two basic approaches: **BFS (breadth-first search)** and **DFS (depth-first search)**

these often serve as **skeletons** of graph algorithms

Breadth-first search

start with a vertex s , visit its neighbors, then the neighbors' neighbors, etc.

network models of processes on graph (perhaps several starting points, probabilities, ...)

vertices are initially **white** (“undiscovered”, “unprocessed”), then become **gray** (“discovered but not finished”, “under processing”) and finally **black** (“finished”, “completely processed”)

natural data structure: **queue, FIFO - first-in, first-out**

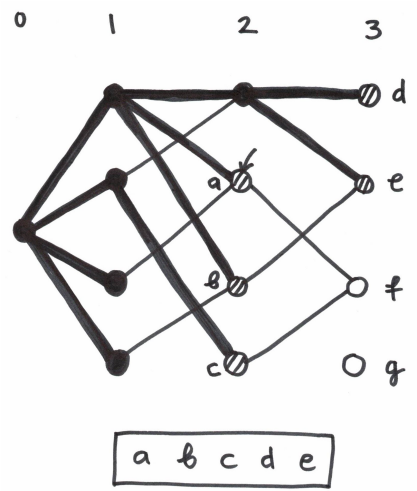
some time after a vertex is discovered, all its undiscovered neighbors become discovered

attributes: $u.color$, $u.d$, $u.\pi$

at the end of the algorithm $u.d$ is the distance of s from u , and $u.\pi$ is the predecessor of u on a shortest path from s to u

edges $(u.\pi, u)$ form a tree, the **breadth-first search tree** from s

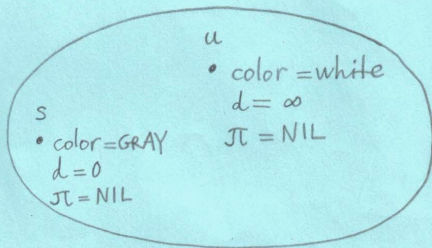
Breadth-first search example 1



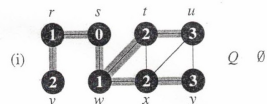
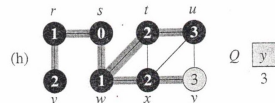
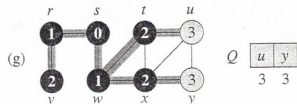
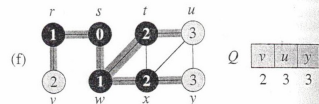
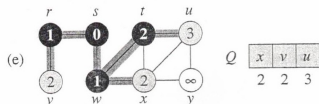
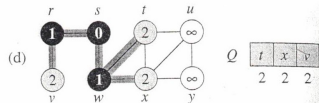
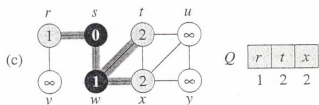
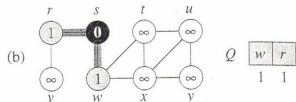
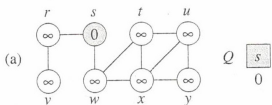
Breadth-first search algorithm

BFS(G, s)

```
1  for each vertex  $u \in G.V - \{s\}$ 
2       $u.color = \text{WHITE}$ 
3       $u.d = \infty$ 
4       $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11      $u = \text{DEQUEUE}(Q)$ 
12     for each  $v \in G.Adj[u]$ 
13         if  $v.color == \text{WHITE}$ 
14              $v.color = \text{GRAY}$ 
15              $v.d = u.d + 1$ 
16              $v.\pi = u$ 
17             ENQUEUE( $Q, v$ )
18      $u.color = \text{BLACK}$ 
```



Breadth-first search example II



Adjacency lists memory requirement

$G = (V, E)$ undirected graph (similar for directed graphs)

$deg(v)$: degree of vertex, number of its neighbors

size of array + combined size of linked lists

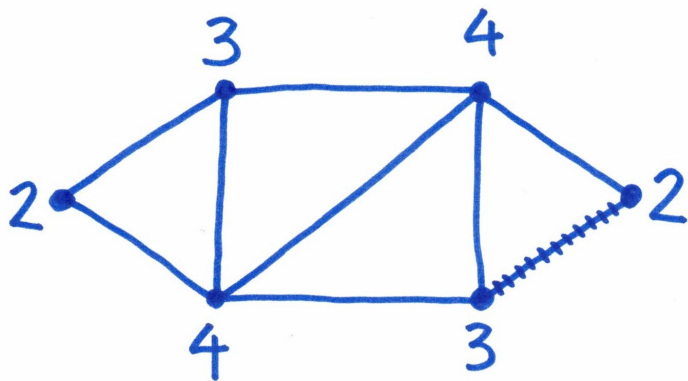
length of adjacency list of v : $deg(v)$

$$\sum_{v \in V} deg(v) = 2|E|$$

adjacency lists use memory $O(|V| + |E|)$

algorithms with running time $O(|V| + |E|)$ are **optimal**

Degrees



$$|E| = 9$$

Running time of BFS

lines 1 - 9 : $O(|V|)$

lines 11 - 18 : $O(deg(v))$

while loop : $O(\sum_{v \in V} deg(v)) = O(|E|)$

running time: $O(|V| + |E|)$

BFS and distances

$\delta(s, v)$: distance of s and v

v **reachable** from s : there is a path from s to v

Theorem

A vertex is reachable from s iff it is discovered. If v is reachable then at the end $v.d = \delta(s, v)$. The backward path from v to s through predecessors is a shortest path from s to v . Edges $(v.\pi, v)$ form a tree, the BFS tree.

note: d -values in queue: 5, 5, 5, 6, 6, 6, 6, 6

Proof outline

reachable \rightarrow discovered and $v.d = \delta(s, v)$

assume false: let v be a counterexample with $\delta(s, v)$ as small as possible, and consider a shortest path from s to v



$\delta(s, v) = \delta(s, u) + 1$ (optimal substructure!)

$u.d = \delta(s, u)$

when u is removed from the queue:

- ▶ v is white: $v.d = u.d + 1$ so $v.d = \delta(s, v)$, contradiction
- ▶ v is gray or black: it became grey when some w was removed from the queue before u , but then $v.d = w.d + 1 \leq u.d + 1 = \delta(s, u) + 1 = \delta(s, v)$, again contradiction