

LIB60BER

Gevrey solutions of hypergeometric systems

María Cruz Fernández Fernández

Universidad de Sevilla
Departamento de Álgebra

Jaca, June 25, 2009

Example:

$$X = \mathbb{C}, Y = \{0\}:$$

$$f = \sum_{m \geq 0} m! x^m$$

$$\rho_s(f) = \sum_{m \geq 0} \frac{1}{m!^{s-2}} x^m \text{ is convergent iff } s \geq 2.$$

Thus, f is a Gevrey series along $\{0\}$ at 0 with index 2.

Example:

$$X = \mathbb{C}, Y = \{0\}:$$

$$f = \sum_{m \geq 0} m! x^m$$

$$\rho_s(f) = \sum_{m \geq 0} \frac{1}{m!^{s-2}} x^m \text{ is convergent iff } s \geq 2.$$

Thus, f is a Gevrey series along $\{0\}$ at 0 with index 2.

Example:

$$X = \mathbb{C}, Y = \{0\}:$$

$$f = \sum_{m \geq 0} m! x^m$$

$$\rho_s(f) = \sum_{m \geq 0} \frac{1}{m!^{s-2}} x^m \text{ is convergent iff } s \geq 2.$$

Thus, f is a Gevrey series along $\{0\}$ at 0 with index 2.

Example:

$$X = \mathbb{C}, Y = \{0\}:$$

$$f = \sum_{m \geq 0} m! x^m$$

$$\rho_s(f) = \sum_{m \geq 0} \frac{1}{m!^{s-2}} x^m \text{ is convergent iff } s \geq 2.$$

Thus, f is a Gevrey series along $\{0\}$ at 0 with index 2.

Example:

$$X = \mathbb{C}, Y = \{0\}:$$

$$f = \sum_{m \geq 0} m! x^m$$

$$\rho_s(f) = \sum_{m \geq 0} \frac{1}{m!^{s-2}} x^m \text{ is convergent iff } s \geq 2.$$

Thus, f is a Gevrey series along $\{0\}$ at 0 with index 2.

Irregularity of \mathcal{D} -modules:

Let X be a complex manifold and $Y \subseteq X$ a smooth subvariety.

Denote $\mathcal{Q}_Y(s) := \mathcal{O}_{X|Y}(s)/\mathcal{O}_{X|Y}$, $s \geq 1$.

Definition (Mebkhout)

Let \mathcal{M} be a holonomic \mathcal{D}_X -module and Y a smooth subvariety of X . The irregularity complex of order s of \mathcal{M} , $1 \leq s \leq \infty$, with respect to Y is:

$$\mathrm{Irr}_Y^{(s)}(\mathcal{M}) := \mathbb{R}\mathrm{Hom}_{\mathcal{D}_X}(\mathcal{M}, \mathcal{Q}_Y(s))$$

If $s = +\infty$, it is called the irregularity complex of \mathcal{M} with respect to Y , denoted by $\mathrm{Irr}_Y(\mathcal{M})$.

Irregularity of \mathcal{D} -modules:

Let X be a complex manifold and $Y \subseteq X$ a smooth subvariety.

Denote $\mathcal{Q}_Y(s) := \mathcal{O}_{X|Y}(s)/\mathcal{O}_{X|Y}$, $s \geq 1$.

Definition (Mebkhout)

Let \mathcal{M} be a holonomic \mathcal{D}_X -module and Y a smooth subvariety of X . The irregularity complex of order s of \mathcal{M} , $1 \leq s \leq \infty$, with respect to Y is:

$$\mathrm{Irr}_Y^{(s)}(\mathcal{M}) := \mathbb{R}\mathrm{Hom}_{\mathcal{D}_X}(\mathcal{M}, \mathcal{Q}_Y(s))$$

If $s = +\infty$, it is called the irregularity complex of \mathcal{M} with respect to Y , denoted by $\mathrm{Irr}_Y(\mathcal{M})$.

Irregularity of \mathcal{D} -modules:

Let X be a complex manifold and $Y \subseteq X$ a smooth subvariety.

Denote $Q_Y(s) := \mathcal{O}_{X|Y}(s)/\mathcal{O}_{X|Y}$, $s \geq 1$.

Definition (Mebkhout)

Let \mathcal{M} be a holonomic \mathcal{D}_X -module and Y a smooth subvariety of X . The irregularity complex of order s of \mathcal{M} , $1 \leq s \leq \infty$, with respect to Y is:

$$\mathrm{Irr}_Y^{(s)}(\mathcal{M}) := \mathbb{R}\mathrm{Hom}_{\mathcal{D}_X}(\mathcal{M}, Q_Y(s))$$

If $s = +\infty$, it is called the irregularity complex of \mathcal{M} with respect to Y , denoted by $\mathrm{Irr}_Y(\mathcal{M})$.

Irregularity of \mathcal{D} -modules:

Let X be a complex manifold and $Y \subseteq X$ a smooth subvariety.

Denote $Q_Y(s) := \mathcal{O}_{X|Y}(s)/\mathcal{O}_{X|Y}$, $s \geq 1$.

Definition (Mebkhout)

Let \mathcal{M} be a holonomic \mathcal{D}_X -module and Y a smooth subvariety of X . The irregularity complex of order s of \mathcal{M} , $1 \leq s \leq \infty$, with respect to Y is:

$$\mathrm{Irr}_Y^{(s)}(\mathcal{M}) := \mathbb{R}\mathrm{Hom}_{\mathcal{D}_X}(\mathcal{M}, Q_Y(s))$$

If $s = +\infty$, it is called the irregularity complex of \mathcal{M} with respect to Y , denoted by $\mathrm{Irr}_Y(\mathcal{M})$.

Irregularity of \mathcal{D} -modules:

\mathcal{M} holonomic \mathcal{D} -module, Y smooth hypersurface

Theorem (Mebkhout)

$\text{Irr}_Y^{(s)}(\mathcal{M})$ is a *perverse sheaf* on Y , for all $1 \leq s \leq +\infty$. Moreover, $\{\text{Irr}_Y^{(s)}(\mathcal{M})\}_{s \geq 1}$ is an increasing filtration of $\text{Irr}_Y(\mathcal{M})$.

Definition (Mebkhout)

$s > 1$ is an analytic slope of \mathcal{M} along Y if s is a gap in the Gevrey filtration $\{\text{Irr}_Y^{(s)}(\mathcal{M})\}_{s \geq 1}$.

Irregularity of \mathcal{D} -modules:

\mathcal{M} holonomic \mathcal{D} -module, Y smooth hypersurface

Theorem (Mebkhout)

$\text{Irr}_Y^{(s)}(\mathcal{M})$ is a *perverse sheaf* on Y , for all $1 \leq s \leq +\infty$. Moreover, $\{\text{Irr}_Y^{(s)}(\mathcal{M})\}_{s \geq 1}$ is an increasing filtration of $\text{Irr}_Y(\mathcal{M})$.

Definition (Mebkhout)

$s > 1$ is an analytic slope of \mathcal{M} along Y if s is a gap in the Gevrey filtration $\{\text{Irr}_Y^{(s)}(\mathcal{M})\}_{s \geq 1}$.

Irregularity of \mathcal{D} -modules:

\mathcal{M} holonomic \mathcal{D} -module, Y smooth hypersurface

Theorem (Mebkhout)

$\text{Irr}_Y^{(s)}(\mathcal{M})$ is a *perverse sheaf* on Y , for all $1 \leq s \leq +\infty$. Moreover, $\{\text{Irr}_Y^{(s)}(\mathcal{M})\}_{s \geq 1}$ is an increasing filtration of $\text{Irr}_Y(\mathcal{M})$.

Definition (Mebkhout)

$s > 1$ is an *analytic slope* of \mathcal{M} along Y if s is a gap in the Gevrey filtration $\{\text{Irr}_Y^{(s)}(\mathcal{M})\}_{s \geq 1}$.

Irregularity of \mathcal{D} -modules:

Y. Laurent defined algebraic slopes of a coherent \mathcal{D} -module along smooth subvarieties of X of any codimension.

Comparison Theorem of the slopes (Laurent-Mebkhout)

Y smooth hypersurface, \mathcal{M} holonomic \mathcal{D}_X -module, then:

algebraic slopes = analytic slopes

Irregularity of \mathcal{D} -modules:

Y. Laurent defined algebraic slopes of a coherent \mathcal{D} -module along smooth subvarieties of X of any codimension.

Comparison Theorem of the slopes (Laurent-Mebkhout)

Y smooth hypersurface, \mathcal{M} holonomic \mathcal{D}_X -module, then:

algebraic slopes = analytic slopes

Irregularity of \mathcal{D} -modules:

Y. Laurent defined algebraic slopes of a coherent \mathcal{D} -module along smooth subvarieties of X of any codimension.

Comparison Theorem of the slopes (Laurent-Mebkhout)

Y smooth hypersurface, \mathcal{M} holonomic \mathcal{D}_X -module, then:

algebraic slopes = analytic slopes

Definition

- Gel'fand, Graev, Kapranov, Zelevinsky (1987-1994).

Associated with a pair (A, β) , where

- $A = (a_1 \cdots a_n)$, $a_i \in \mathbb{Z}^d$, $\text{rank}(A) = d \leq n$, $\beta \in \mathbb{C}^d$.
- GZK, Adolphson: They are holonomic \mathcal{D} -modules.

Definition

- Gel'fand, Graev, Kapranov, Zelevinsky (1987-1994).

Associated with a pair (A, β) , where

- $A = (a_1 \cdots a_n)$, $a_i \in \mathbb{Z}^d$, $\text{rank}(A) = d \leq n$, $\beta \in \mathbb{C}^d$.
- GZK, Adolphson: They are holonomic \mathcal{D} -modules.

Definition

- Gel'fand, Graev, Kapranov, Zelevinsky (1987-1994).

Associated with a pair (A, β) , where

- $A = (a_1 \cdots a_n)$, $a_i \in \mathbb{Z}^d$, $\text{rank}(A) = d \leq n$, $\beta \in \mathbb{C}^d$.
- GZK, Adolphson: They are holonomic \mathcal{D} -modules.

Definition

- Gel'fand, Graev, Kapranov, Zelevinsky (1987-1994).

Associated with a pair (A, β) , where

- $A = (a_1 \cdots a_n)$, $a_i \in \mathbb{Z}^d$, $\text{rank}(A) = d \leq n$, $\beta \in \mathbb{C}^d$.
- GZK, Adolphson: They are holonomic \mathcal{D} -modules.

Definition

Toric ideal: $I_A = \langle \partial^{u^+} - \partial^{u^-} : u \in \ker A \cap \mathbb{Z}^n \rangle \subseteq \mathbb{C}[\partial]$.

Euler operators: $E_i = \sum_{j=1}^n a_{ij} x_j \partial_j$, $i = 1, \dots, d$.

Hypergeometric \mathcal{D} -module:

$$\mathcal{M}_A(\beta) := \frac{\mathcal{D}}{\mathcal{D}I_A + \mathcal{D}\langle E_1 - \beta_1, \dots, E_d - \beta_d \rangle}$$

Example:

$A = (1, 2)$, $I_A = \langle \partial_1^2 - \partial_2 \rangle$, $E - \beta = x_1 \partial_1 + 2x_2 \partial_2 - \beta$

$\mathcal{M}_A(\beta) = \mathcal{D}_{\mathbb{C}^2} / (\mathcal{D}_{\mathbb{C}^2} I_A + \mathcal{D}_{\mathbb{C}^2} (E - \beta))$

Definition

Toric ideal: $I_A = \langle \partial^{u^+} - \partial^{u^-} : u \in \ker A \cap \mathbb{Z}^n \rangle \subseteq \mathbb{C}[\partial]$.

Euler operators: $E_i = \sum_{j=1}^n a_{ij} x_j \partial_j$, $i = 1, \dots, d$.

Hypergeometric \mathcal{D} -module:

$$\mathcal{M}_A(\beta) := \frac{\mathcal{D}}{\mathcal{D}I_A + \mathcal{D}\langle E_1 - \beta_1, \dots, E_d - \beta_d \rangle}$$

Example:

$A = (1, 2)$, $I_A = \langle \partial_1^2 - \partial_2 \rangle$, $E - \beta = x_1 \partial_1 + 2x_2 \partial_2 - \beta$

$\mathcal{M}_A(\beta) = \mathcal{D}_{\mathbb{C}^2} / (\mathcal{D}_{\mathbb{C}^2} I_A + \mathcal{D}_{\mathbb{C}^2} (E - \beta))$

Definition

Toric ideal: $I_A = \langle \partial^{u^+} - \partial^{u^-} : u \in \ker A \cap \mathbb{Z}^n \rangle \subseteq \mathbb{C}[\partial]$.

Euler operators: $E_i = \sum_{j=1}^n a_{ij} x_j \partial_j$, $i = 1, \dots, d$.

Hypergeometric \mathcal{D} -module:

$$\mathcal{M}_A(\beta) := \frac{\mathcal{D}}{\mathcal{D}I_A + \mathcal{D}\langle E_1 - \beta_1, \dots, E_d - \beta_d \rangle}$$

Example:

$A = (1, 2)$, $I_A = \langle \partial_1^2 - \partial_2 \rangle$, $E - \beta = x_1 \partial_1 + 2x_2 \partial_2 - \beta$

$\mathcal{M}_A(\beta) = \mathcal{D}_{\mathbb{C}^2} / (\mathcal{D}_{\mathbb{C}^2} I_A + \mathcal{D}_{\mathbb{C}^2} (E - \beta))$

Definition

Toric ideal: $I_A = \langle \partial^{u^+} - \partial^{u^-} : u \in \ker A \cap \mathbb{Z}^n \rangle \subseteq \mathbb{C}[\partial]$.

Euler operators: $E_i = \sum_{j=1}^n a_{ij} x_j \partial_j$, $i = 1, \dots, d$.

Hypergeometric \mathcal{D} -module:

$$\mathcal{M}_A(\beta) := \frac{\mathcal{D}}{\mathcal{D}I_A + \mathcal{D}\langle E_1 - \beta_1, \dots, E_d - \beta_d \rangle}$$

Example:

$A = (1, 2)$, $I_A = \langle \partial_1^2 - \partial_2 \rangle$, $E - \beta = x_1 \partial_1 + 2x_2 \partial_2 - \beta$

$\mathcal{M}_A(\beta) = \mathcal{D}_{\mathbb{C}^2} / (\mathcal{D}_{\mathbb{C}^2} I_A + \mathcal{D}_{\mathbb{C}^2} (E - \beta))$

Definition

Toric ideal: $I_A = \langle \partial^{u^+} - \partial^{u^-} : u \in \ker A \cap \mathbb{Z}^n \rangle \subseteq \mathbb{C}[\partial]$.

Euler operators: $E_i = \sum_{j=1}^n a_{ij} x_j \partial_j$, $i = 1, \dots, d$.

Hypergeometric \mathcal{D} -module:

$$\mathcal{M}_A(\beta) := \frac{\mathcal{D}}{\mathcal{D}I_A + \mathcal{D}\langle E_1 - \beta_1, \dots, E_d - \beta_d \rangle}$$

Example:

$A = (1, 2)$, $I_A = \langle \partial_1^2 - \partial_2 \rangle$, $E - \beta = x_1 \partial_1 + 2x_2 \partial_2 - \beta$

$\mathcal{M}_A(\beta) = \mathcal{D}_{\mathbb{C}^2} / (\mathcal{D}_{\mathbb{C}^2} I_A + \mathcal{D}_{\mathbb{C}^2} (E - \beta))$

Γ -series (Gel'fand-Zelevinsky-Kapranov; Saito-Sturmfels-Takayama)

- $v = (v_1, \dots, v_n) \in \mathbb{C}^n$:
- $[v]_u := \prod_{i=1}^n \prod_{j=1}^{u_i} (v_i - j + 1)$.

$$\phi_v := \sum_{u \in N_v} \frac{[v]_{u_-}}{[v+u]_{u_+}} x^{v+u} \in x^v \mathbb{C}[[x_1^{\pm 1}, \dots, x_n^{\pm 1}]]$$

where $N_v \subseteq \ker A \cap \mathbb{Z}^n$.

Problem: to find v that guaranties that ϕ_v is a Gevrey solution of $\mathcal{M}_A(\beta)$ along a coordinate subspace Y .

Γ -series (Gel'fand-Zelevinsky-Kapranov; Saito-Sturmfels-Takayama)

- $v = (v_1, \dots, v_n) \in \mathbb{C}^n$:
- $[v]_u := \prod_{i=1}^n \prod_{j=1}^{u_i} (v_i - j + 1)$.

$$\phi_v := \sum_{u \in N_v} \frac{[v]_{u_-}}{[v+u]_{u_+}} x^{v+u} \in x^v \mathbb{C}[[x_1^{\pm 1}, \dots, x_n^{\pm 1}]]$$

where $N_v \subseteq \ker A \cap \mathbb{Z}^n$.

Problem: to find v that guaranties that ϕ_v is a Gevrey solution of $\mathcal{M}_A(\beta)$ along a coordinate subspace Y .

Γ -series (Gel'fand-Zelevinsky-Kapranov; Saito-Sturmfels-Takayama)

- $v = (v_1, \dots, v_n) \in \mathbb{C}^n$:
- $[v]_u := \prod_{i=1}^n \prod_{j=1}^{u_i} (v_i - j + 1)$.

$$\phi_v := \sum_{u \in N_v} \frac{[v]_{u_-}}{[v+u]_{u_+}} x^{v+u} \in x^v \mathbb{C}[[x_1^{\pm 1}, \dots, x_n^{\pm 1}]]$$

where $N_v \subseteq \ker A \cap \mathbb{Z}^n$.

Problem: to find v that guaranties that ϕ_v is a Gevrey solution of $\mathcal{M}_A(\beta)$ along a coordinate subspace Y .

Γ -series (Gel'fand-Zelevinsky-Kapranov; Saito-Sturmfels-Takayama)

- $v = (v_1, \dots, v_n) \in \mathbb{C}^n$:
- $[v]_u := \prod_{i=1}^n \prod_{j=1}^{u_i} (v_i - j + 1)$.

$$\phi_v := \sum_{u \in N_v} \frac{[v]_{u_-}}{[v+u]_{u_+}} x^{v+u} \in x^v \mathbb{C}[[x_1^{\pm 1}, \dots, x_n^{\pm 1}]]$$

where $N_v \subseteq \ker A \cap \mathbb{Z}^n$.

Problem: to find v that guaranties that ϕ_v is a Gevrey solution of $\mathcal{M}_A(\beta)$ along a coordinate subspace Y .

Γ -series (Gel'fand-Zelevinsky-Kapranov; Saito-Sturmfels-Takayama)

- $v = (v_1, \dots, v_n) \in \mathbb{C}^n$:
- $[v]_u := \prod_{i=1}^n \prod_{j=1}^{u_i} (v_i - j + 1)$.

$$\phi_v := \sum_{u \in N_v} \frac{[v]_{u_-}}{[v+u]_{u_+}} x^{v+u} \in x^v \mathbb{C}[[x_1^{\pm 1}, \dots, x_n^{\pm 1}]]$$

where $N_v \subseteq \ker A \cap \mathbb{Z}^n$.

Problem: to find v that guaranties that ϕ_v is a Gevrey solution of $\mathcal{M}_A(\beta)$ along a coordinate subspace Y .

Hypergeometric \mathcal{D} -modules and some well-known results

Theorem (Gel'fand-Zelevinsky-Kapranov, Adolphson)

$$\Delta_A = \text{convex-hull}(0, a_1, \dots, a_n) \subseteq \mathbb{R}^d$$

If β is very generic, the holonomic rank of $\mathcal{M}_A(\beta)$ is

$$\text{vol}_{\mathbb{Z}A}(\Delta_A) := \frac{d! \text{vol}(\Delta_A)}{[\mathbb{Z}^d : \mathbb{Z}A]}.$$

Theorem (Schulze-Walther)

Combinatorial description of the (algebraic) slopes of $\mathcal{M}_A(\beta)$ along coordinate subspaces Y at $0 \in Y$ under the assumptions:

- 1 $\mathbb{Z}A = \mathbb{Z}^d$.
- 2 A is *pointed*, i.e. a_1, \dots, a_n lie in a single open half-space (equivalently, $\mathcal{V}(I_A)$ passes through the origin).

Hypergeometric \mathcal{D} -modules and some well-known results

Theorem (Gel'fand-Zelevinsky-Kapranov, Adolphson)

$$\Delta_A = \text{convex-hull}(0, a_1, \dots, a_n) \subseteq \mathbb{R}^d$$

If β is very generic, the holonomic rank of $\mathcal{M}_A(\beta)$ is

$$\text{vol}_{\mathbb{Z}A}(\Delta_A) := \frac{d! \text{vol}(\Delta_A)}{[\mathbb{Z}^d : \mathbb{Z}A]}.$$

Theorem (Schulze-Walther)

Combinatorial description of the (algebraic) slopes of $\mathcal{M}_A(\beta)$ along coordinate subspaces Y at $0 \in Y$ under the assumptions:

- 1 $\mathbb{Z}A = \mathbb{Z}^d$.
- 2 A is *pointed*, i.e. a_1, \dots, a_n lie in a single open half-space (equivalently, $\mathcal{V}(I_A)$ passes through the origin).

Hypergeometric \mathcal{D} -modules and some well-known results

Theorem (Gel'fand-Zelevinsky-Kapranov, Adolphson)

$$\Delta_A = \text{convex-hull}(0, a_1, \dots, a_n) \subseteq \mathbb{R}^d$$

If β is very generic, the holonomic rank of $\mathcal{M}_A(\beta)$ is

$$\text{vol}_{\mathbb{Z}A}(\Delta_A) := \frac{d! \text{vol}(\Delta_A)}{[\mathbb{Z}^d : \mathbb{Z}A]}.$$

Theorem (Schulze-Walther)

Combinatorial description of the (algebraic) slopes of $\mathcal{M}_A(\beta)$ along coordinate subspaces Y at $0 \in Y$ under the assumptions:

- 1 $\mathbb{Z}A = \mathbb{Z}^d$.
- 2 A is *pointed*, i.e. a_1, \dots, a_n lie in a single open half-space (equivalently, $\mathcal{V}(I_A)$ passes through the origin).

Hypergeometric \mathcal{D} -modules and some well-known results

Theorem (Gel'fand-Zelevinsky-Kapranov, Adolphson)

$$\Delta_A = \text{convex-hull}(0, a_1, \dots, a_n) \subseteq \mathbb{R}^d$$

If β is very generic, the holonomic rank of $\mathcal{M}_A(\beta)$ is

$$\text{vol}_{\mathbb{Z}A}(\Delta_A) := \frac{d! \text{vol}(\Delta_A)}{[\mathbb{Z}^d : \mathbb{Z}A]}.$$

Theorem (Schulze-Walther)

Combinatorial description of the (algebraic) slopes of $\mathcal{M}_A(\beta)$ along coordinate subspaces Y at $0 \in Y$ under the assumptions:

- 1 $\mathbb{Z}A = \mathbb{Z}^d$.
- 2 A is *pointed*, i.e. a_1, \dots, a_n lie in a single open half-space (equivalently, $\mathcal{V}(I_A)$ passes through the origin).

Results

Let Y be a coordinate hyperplane. Reordering the variables:
 $Y = \{x_n = 0\}$. $A' = (a_1 \cdots a_{n-1})$.

For η a facet of $\Delta_{A'}$, denote H_η the unique hyperplane with
 $a_i \in H_\eta, \forall i \in \eta$.

Theorem 1

The slopes of $\mathcal{M}_A(\beta)$ along Y at any point $p \in Y$ are:

$$\{s > 1 : a_n/s \in H_\eta, \text{ for certain facet } \eta \text{ of } \Delta_{A'}\}$$

Moreover, all the slopes occur as the Gevrey index of certain formal solutions along Y that we will explicitly construct.

Results

Let Y be a coordinate hyperplane. Reordering the variables:
 $Y = \{x_n = 0\}$. $A' = (a_1 \cdots a_{n-1})$.

For η a facet of $\Delta_{A'}$, denote H_η the unique hyperplane with
 $a_i \in H_\eta, \forall i \in \eta$.

Theorem 1

The slopes of $\mathcal{M}_A(\beta)$ along Y at any point $p \in Y$ are:

$$\{s > 1 : a_n/s \in H_\eta, \text{ for certain facet } \eta \text{ of } \Delta_{A'}\}$$

Moreover, all the slopes occur as the Gevrey index of certain formal solutions along Y that we will explicitly construct.

Results

Let Y be a coordinate hyperplane. Reordering the variables:
 $Y = \{x_n = 0\}$. $A' = (a_1 \cdots a_{n-1})$.

For η a facet of $\Delta_{A'}$, denote H_η the unique hyperplane with
 $a_i \in H_\eta, ; \forall i \in \eta$.

Theorem 1

The slopes of $\mathcal{M}_A(\beta)$ along Y at any point $p \in Y$ are:

$$\{s > 1 : a_n/s \in H_\eta, \text{ for certain facet } \eta \text{ of } \Delta_{A'}\}$$

Moreover, all the slopes occur as the Gevrey index of certain formal solutions along Y that we will explicitly construct.

Results

Let Y be a coordinate hyperplane. Reordering the variables:
 $Y = \{x_n = 0\}$. $A' = (a_1 \cdots a_{n-1})$.

For η a facet of $\Delta_{A'}$, denote H_η the unique hyperplane with
 $a_i \in H_\eta, ; \forall i \in \eta$.

Theorem 1

The slopes of $\mathcal{M}_A(\beta)$ along Y at any point $p \in Y$ are:

$$\{s > 1 : a_n/s \in H_\eta, \text{ for certain facet } \eta \text{ of } \Delta_{A'}\}$$

Moreover, all the slopes occur as the Gevrey index of certain formal solutions along Y that we will explicitly construct.

Results

Let Y be a coordinate hyperplane. Reordering the variables:
 $Y = \{x_n = 0\}$. $A' = (a_1 \cdots a_{n-1})$.

For η a facet of $\Delta_{A'}$, denote H_η the unique hyperplane with
 $a_i \in H_\eta, ; \forall i \in \eta$.

Theorem 1

The slopes of $\mathcal{M}_A(\beta)$ along Y at any point $p \in Y$ are:

$$\{s > 1 : a_n/s \in H_\eta, \text{ for certain facet } \eta \text{ of } \Delta_{A'}\}$$

Moreover, all the slopes occur as the Gevrey index of certain formal solutions along Y that we will explicitly construct.

Results

$$\tau \subseteq \{1, \dots, n\}, \quad Y_\tau := \{x_i = 0 : i \notin \tau\}.$$

$$\Delta_\tau := \text{convex-hull}(0, a_i : i \in \tau).$$

Theorem 2

For all $\beta \in \mathbb{C}^d$ and for generic points $p \in Y_\tau$:

$$\dim_{\mathbb{C}} \text{Hom}_{\mathcal{D}}(\mathcal{M}_A(\beta), \mathcal{O}_{\widehat{X|Y_\tau}})_p \geq \text{vol}_{\mathbb{Z}A}(\Delta_\tau)$$

More precisely, for all $s \in \mathbb{R}$,

$$\dim_{\mathbb{C}} \text{Hom}_{\mathcal{D}}(\mathcal{M}_A(\beta), \mathcal{O}_{X|Y_\tau}(s))_p \geq \sum_{\eta \subseteq \tau} \text{vol}_{\mathbb{Z}A}(\Delta_\eta)$$

where η varies between the facets of Δ_τ such that
 $a_i/s \in H_\eta \cup H_\eta^-, \forall i \notin \tau$.

Moreover, equality holds for very generic parameters $\beta \in \mathbb{C}^d$.

Results

$\tau \subseteq \{1, \dots, n\}$, $Y_\tau := \{x_i = 0 : i \notin \tau\}$.
 $\Delta_\tau := \text{convex-hull}(0, a_i : i \in \tau)$.

Theorem 2

For all $\beta \in \mathbb{C}^d$ and for generic points $p \in Y_\tau$:

$$\dim_{\mathbb{C}} \text{Hom}_{\mathcal{D}}(\mathcal{M}_A(\beta), \mathcal{O}_{\widehat{X|Y_\tau}})_p \geq \text{vol}_{\mathbb{Z}A}(\Delta_\tau)$$

More precisely, for all $s \in \mathbb{R}$,

$$\dim_{\mathbb{C}} \text{Hom}_{\mathcal{D}}(\mathcal{M}_A(\beta), \mathcal{O}_{X|Y_\tau}(s))_p \geq \sum_{\eta \subseteq \tau} \text{vol}_{\mathbb{Z}A}(\Delta_\eta)$$

where η varies between the facets of Δ_τ such that
 $a_i/s \in H_\eta \cup H_\eta^-, \forall i \notin \tau$.

Moreover, equality holds for very generic parameters $\beta \in \mathbb{C}^d$.

Results

$\tau \subseteq \{1, \dots, n\}$, $Y_\tau := \{x_i = 0 : i \notin \tau\}$.
 $\Delta_\tau := \text{convex-hull}(0, a_i : i \in \tau)$.

Theorem 2

For all $\beta \in \mathbb{C}^d$ and for generic points $p \in Y_\tau$:

$$\dim_{\mathbb{C}} \text{Hom}_{\mathcal{D}}(\mathcal{M}_A(\beta), \mathcal{O}_{\widehat{X|Y_\tau}})_p \geq \text{vol}_{\mathbb{Z}A}(\Delta_\tau)$$

More precisely, for all $s \in \mathbb{R}$,

$$\dim_{\mathbb{C}} \text{Hom}_{\mathcal{D}}(\mathcal{M}_A(\beta), \mathcal{O}_{X|Y_\tau}(s))_p \geq \sum_{\eta \subseteq \tau} \text{vol}_{\mathbb{Z}A}(\Delta_\eta)$$

where η varies between the facets of Δ_τ such that
 $a_i/s \in H_\eta \cup H_\eta^-, \forall i \notin \tau$.

Moreover, equality holds for very generic parameters $\beta \in \mathbb{C}^d$.

Results

$\tau \subseteq \{1, \dots, n\}$, $Y_\tau := \{x_i = 0 : i \notin \tau\}$.
 $\Delta_\tau := \text{convex-hull}(0, a_i : i \in \tau)$.

Theorem 2

For all $\beta \in \mathbb{C}^d$ and for generic points $p \in Y_\tau$:

$$\dim_{\mathbb{C}} \text{Hom}_{\mathcal{D}}(\mathcal{M}_A(\beta), \mathcal{O}_{\widehat{X|Y_\tau}})_p \geq \text{vol}_{\mathbb{Z}A}(\Delta_\tau)$$

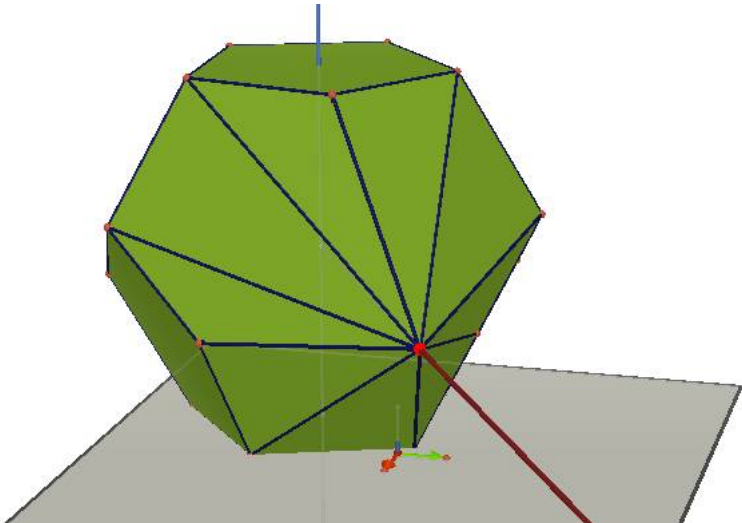
More precisely, for all $s \in \mathbb{R}$,

$$\dim_{\mathbb{C}} \text{Hom}_{\mathcal{D}}(\mathcal{M}_A(\beta), \mathcal{O}_{X|Y_\tau}(s))_p \geq \sum_{\eta \subseteq \tau} \text{vol}_{\mathbb{Z}A}(\Delta_\eta)$$

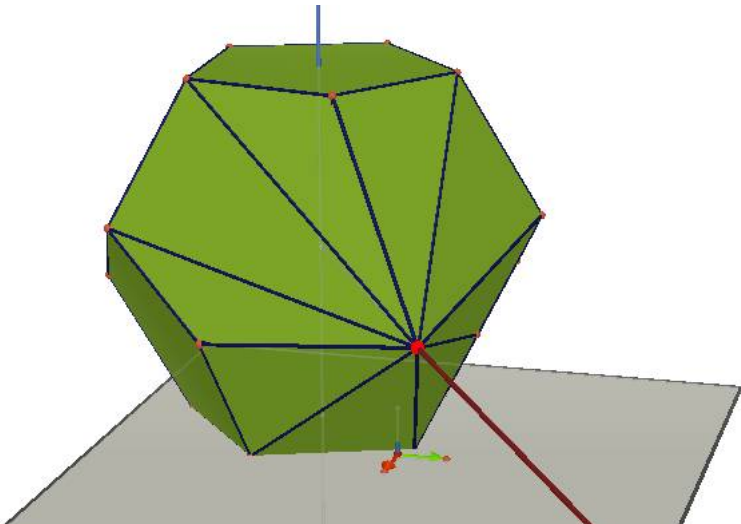
where η varies between the facets of Δ_τ such that
 $a_i/s \in H_\eta \cup H_\eta^-, \forall i \notin \tau$.

Moreover, equality holds for very generic parameters $\beta \in \mathbb{C}^d$.

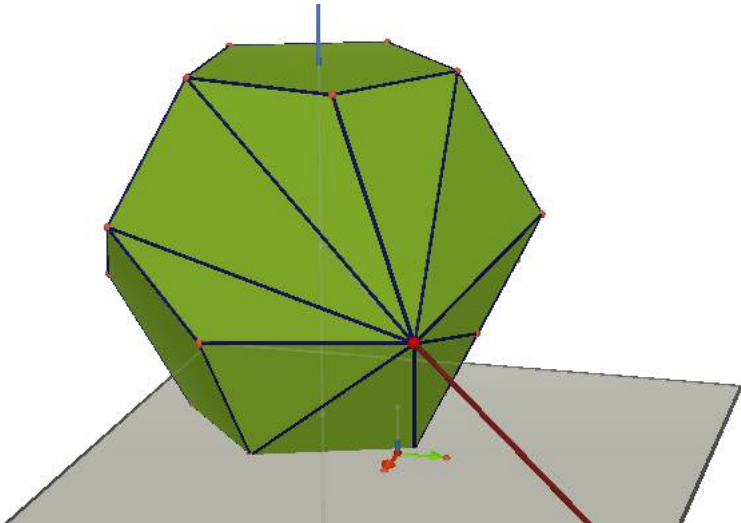
The moving point is a_n/s where s varies in $[1, +\infty)$



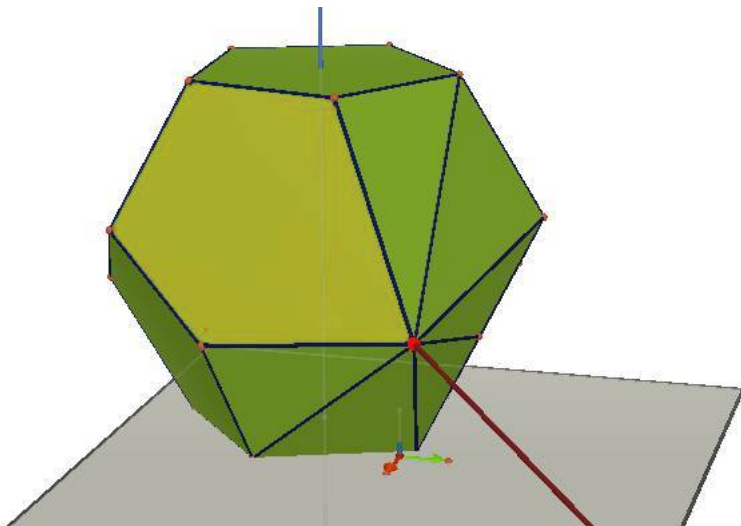
The moving point is a_n/s where s varies in $[1, +\infty)$



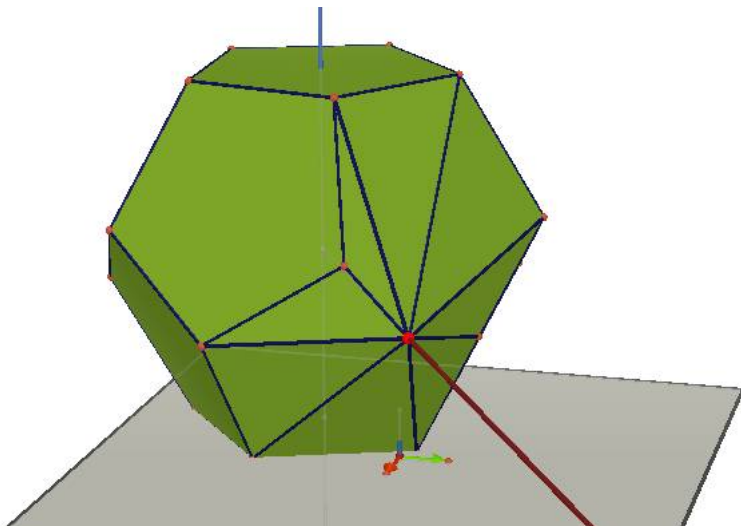
The moving point is a_n/s where s varies in $[1, +\infty)$



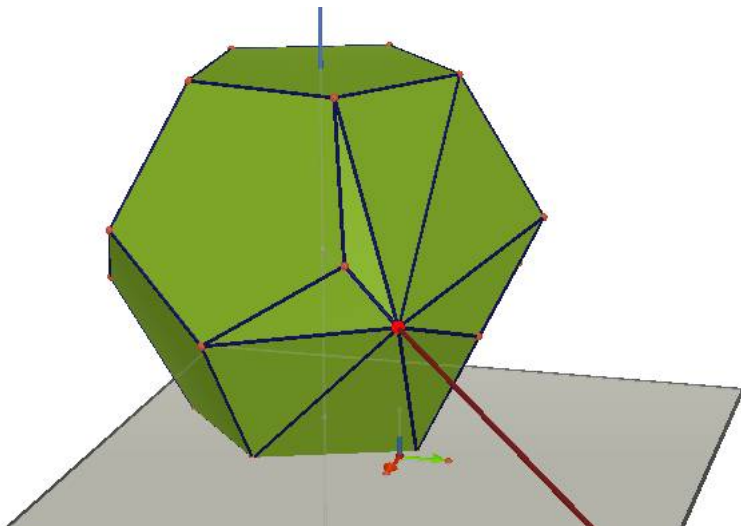
The moving point is a_n/s where s varies in $[1, +\infty)$



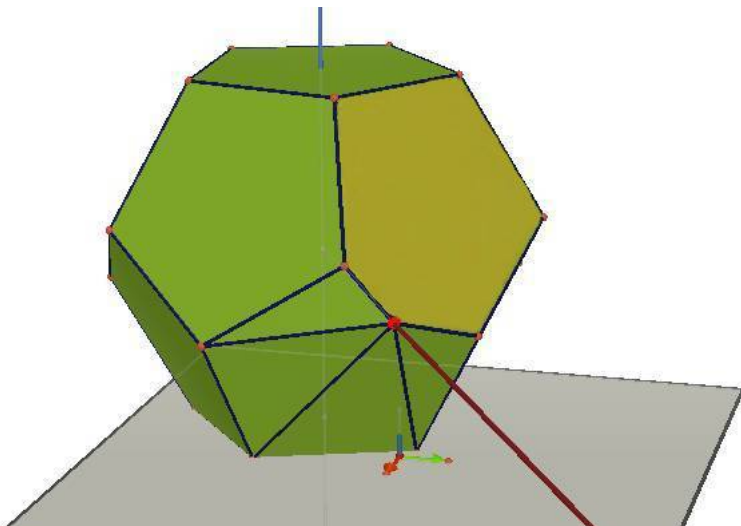
The moving point is a_n/s where s varies in $[1, +\infty)$



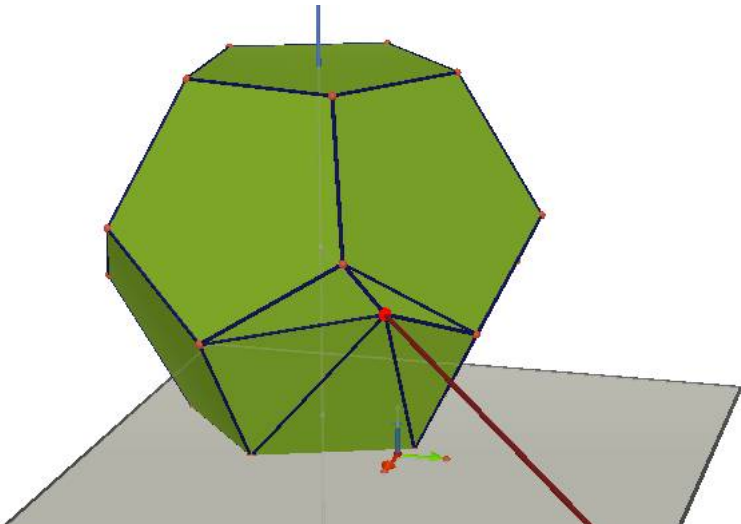
The moving point is a_n/s where s varies in $[1, +\infty)$



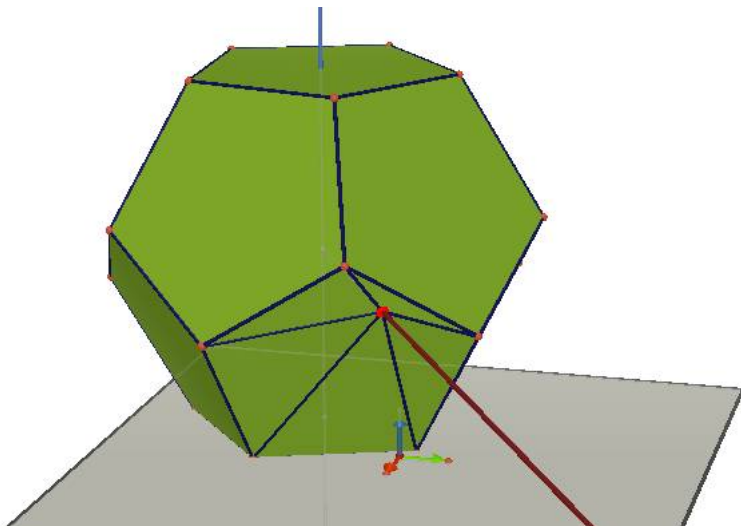
The moving point is a_n/s where s varies in $[1, +\infty)$



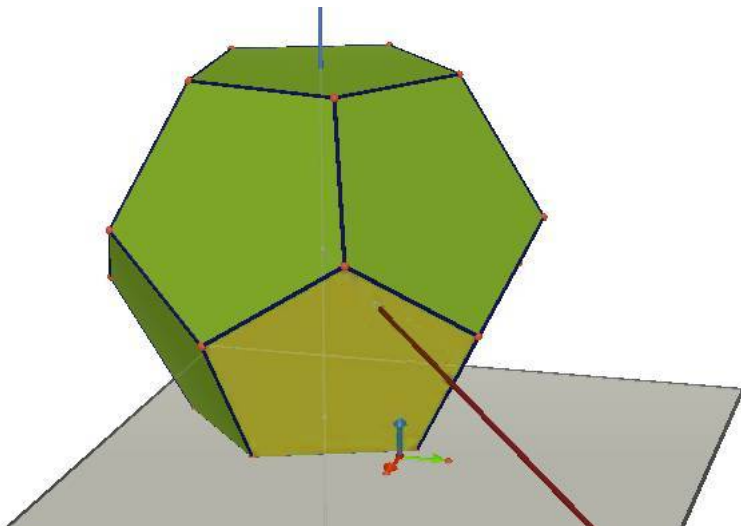
The moving point is a_n/s where s varies in $[1, +\infty)$



The moving point is a_n/s where s varies in $[1, +\infty)$



The moving point is a_n/s where s varies in $[1, +\infty)$



Gevrey solutions of $\mathcal{M}_A(\beta)$ associated with a simplex

A simplex of A is: $\sigma \subseteq \{1, \dots, n\}$, with cardinal d and $\det(A_\sigma) \neq 0$.

Reordering the variables, $\sigma = \{1, \dots, d\}$.

Consider $v^k = (A_\sigma^{-1}(\beta - \sum_{i \notin \sigma} k_i a_i), k)$ with $k = (k_i)_{i \notin \sigma} \in \mathbb{Z}^{n-d}$.
 It is clear that $Av^k = \beta$.

Gevrey solutions of $\mathcal{M}_A(\beta)$ associated with a simplex

A simplex of A is: $\sigma \subseteq \{1, \dots, n\}$, with cardinal d and $\det(A_\sigma) \neq 0$.

Reordering the variables, $\sigma = \{1, \dots, d\}$.

Consider $v^k = (A_\sigma^{-1}(\beta - \sum_{i \notin \sigma} k_i a_i), k)$ with $k = (k_i)_{i \notin \sigma} \in \mathbb{Z}^{n-d}$.
 It is clear that $Av^k = \beta$.

Gevrey solutions of $\mathcal{M}_A(\beta)$ associated with a simplex

A simplex of A is: $\sigma \subseteq \{1, \dots, n\}$, with cardinal d and $\det(A_\sigma) \neq 0$.

Reordering the variables, $\sigma = \{1, \dots, d\}$.

Consider $v^k = (A_\sigma^{-1}(\beta - \sum_{i \notin \sigma} k_i a_i), k)$ with $k = (k_i)_{i \notin \sigma} \in \mathbb{Z}^{n-d}$.
 It is clear that $Av^k = \beta$.

Gevrey solutions of $\mathcal{M}_A(\beta)$ associated with a simplex

Set $\Lambda_{\mathbf{k}} := \{\mathbf{k} + \mathbf{m} = (k_i + m_i)_{i \in \bar{\sigma}} \in \mathbb{N}^{n-d} : \sum_{i \in \bar{\sigma}} a_i m_i \in \mathbb{Z} A_{\sigma}\}$.

The series $\varphi_{\mathbf{k}}$:

$$\sum_{\mathbf{k} + \mathbf{m} \in \Lambda_{\mathbf{k}}} \frac{[A_{\sigma}^{-1}(\beta - \sum_{i \notin \sigma} k_i a_i)]_{(A_{\sigma}^{-1}(\sum_{i \notin \sigma} m_i a_i))_+} X_{\sigma}^{A_{\sigma}^{-1}(\beta - \sum_{i \notin \sigma} (k_i + m_i) a_i)} X_{\bar{\sigma}}^{\mathbf{k} + \mathbf{m}}}{[A_{\sigma}^{-1}(\beta - \sum_{i \notin \sigma} (k_i + m_i) a_i)]_{(A_{\sigma}^{-1}(\sum_{i \notin \sigma} m_i a_i))_-} (\mathbf{k} + \mathbf{m})!}$$

is a Gevrey solution of $\mathcal{M}_A(\beta)$ along $\{x_i = 0 : a_i \in H_{\sigma}^+\}$ of order $s = \max\{|A_{\sigma}^{-1} a_i| : a_i \in H_{\sigma}^+\}$.

Gevrey solutions of $\mathcal{M}_A(\beta)$ associated with a simplex

Set $\Lambda_{\mathbf{k}} := \{\mathbf{k} + \mathbf{m} = (k_i + m_i)_{i \in \bar{\sigma}} \in \mathbb{N}^{n-d} : \sum_{i \in \bar{\sigma}} a_i m_i \in \mathbb{Z} A_{\sigma}\}$.

The series $\varphi_{\mathbf{k}}$:

$$\sum_{\mathbf{k} + \mathbf{m} \in \Lambda_{\mathbf{k}}} \frac{[A_{\sigma}^{-1}(\beta - \sum_{i \notin \sigma} k_i a_i)]_{(A_{\sigma}^{-1}(\sum_{i \notin \sigma} m_i a_i))_+} x_{\sigma}^{A_{\sigma}^{-1}(\beta - \sum_{i \notin \sigma} (k_i + m_i) a_i)} x_{\bar{\sigma}}^{\mathbf{k} + \mathbf{m}}}{[A_{\sigma}^{-1}(\beta - \sum_{i \notin \sigma} (k_i + m_i) a_i)]_{(A_{\sigma}^{-1}(\sum_{i \notin \sigma} m_i a_i))_-} (\mathbf{k} + \mathbf{m})!}$$

is a Gevrey solution of $\mathcal{M}_A(\beta)$ along $\{x_i = 0 : a_i \in H_{\sigma}^+\}$ of order $s = \max\{|A_{\sigma}^{-1} a_i| : a_i \in H_{\sigma}^+\}$.

Gevrey solutions of $\mathcal{M}_A(\beta)$ associated with a simplex

Set $\Lambda_{\mathbf{k}} := \{\mathbf{k} + \mathbf{m} = (k_i + m_i)_{i \in \bar{\sigma}} \in \mathbb{N}^{n-d} : \sum_{i \in \bar{\sigma}} a_i m_i \in \mathbb{Z} A_{\sigma}\}$.

The series $\varphi_{\mathbf{k}}$:

$$\sum_{\mathbf{k} + \mathbf{m} \in \Lambda_{\mathbf{k}}} \frac{[A_{\sigma}^{-1}(\beta - \sum_{i \notin \sigma} k_i a_i)]_{(A_{\sigma}^{-1}(\sum_{i \notin \sigma} m_i a_i))_+} x_{\sigma}^{A_{\sigma}^{-1}(\beta - \sum_{i \notin \sigma} (k_i + m_i) a_i)} x_{\bar{\sigma}}^{\mathbf{k} + \mathbf{m}}}{[A_{\sigma}^{-1}(\beta - \sum_{i \notin \sigma} (k_i + m_i) a_i)]_{(A_{\sigma}^{-1}(\sum_{i \notin \sigma} m_i a_i))_-} (\mathbf{k} + \mathbf{m})!}$$

is a Gevrey solution of $\mathcal{M}_A(\beta)$ along $\{x_i = 0 : a_i \in H_{\sigma}^+\}$ of order $s = \max\{|A_{\sigma}^{-1} a_i| : a_i \in H_{\sigma}^+\}$.

Example

In general, if Y is a coordinate subspace with $\text{codim } Y > 1$, not every slope appear as the index of a Gevrey solution:

$$A = \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & -1 \end{pmatrix} \quad \beta = \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix}$$

$$I_A = \langle \partial_1^3 - \partial_2 \partial_3 \rangle.$$

$$Y = \{x_2 = x_3 = 0\}.$$

$s = 3/2$ is an algebraic slope of $\mathcal{M}_A(\beta)$ along Y (see Schulze-Walther). But s is the index of a Gevrey solution of $\mathcal{M}_A(\beta)$ (modulo convergent series) along Y if and only if $\beta_2 \in \mathbb{Z}$.

More details and results in the preprint:

Fernández-Fernández, M.C. *Irregular hypergeometric \mathcal{D} -modules*.
arXiv:0906.3478v1 [math.AG]

References

Adolphson, A. *A-hypergeometric functions and rings generated by monomials*. Duke Mathematical Journal 73 (1994), n° 2, p. 269-290.

Fernández-Fernández, M.C; Castro-Jiménez, F.J. *Gevrey solutions of the irregular hypergeometric system associated with an affine monomial curve*. To appear in Trans. Amer. Math. Soc.

Fernández-Fernández, M.C; Castro-Jiménez, F.J. *Gevrey solutions of irregular hypergeometric systems in two variables*. arXiv:0811.3390v1 [math.AG].

I.M. Gel'fand, A.V. Zelevinsky, M.M. Kapranov, *Hypergeometric functions and toral manifolds*. Funktsional Anal., 23 (1989), 2, 12-26.

References

Adolphson, A. *A-hypergeometric functions and rings generated by monomials*. Duke Mathematical Journal 73 (1994), n° 2, p. 269-290.

Fernández-Fernández, M.C; Castro-Jiménez, F.J. *Gevrey solutions of the irregular hypergeometric system associated with an affine monomial curve*. To appear in Trans. Amer. Math. Soc.

Fernández-Fernández, M.C; Castro-Jiménez, F.J. *Gevrey solutions of irregular hypergeometric systems in two variables*. arXiv:0811.3390v1 [math.AG].

I.M. Gel'fand, A.V. Zelevinsky, M.M. Kapranov, *Hypergeometric functions and toral manifolds*. Funktsional Anal., 23 (1989), 2, 12-26.

References

Adolphson, A. *A-hypergeometric functions and rings generated by monomials*. Duke Mathematical Journal 73 (1994), n° 2, p. 269-290.

Fernández-Fernández, M.C; Castro-Jiménez, F.J. *Gevrey solutions of the irregular hypergeometric system associated with an affine monomial curve*. To appear in Trans. Amer. Math. Soc.

Fernández-Fernández, M.C; Castro-Jiménez, F.J. *Gevrey solutions of irregular hypergeometric systems in two variables*. arXiv:0811.3390v1 [math.AG].

I.M. Gel'fand, A.V. Zelevinsky, M.M. Kapranov, *Hypergeometric functions and toral manifolds*. Funktsional Anal., 23 (1989), 2, 12-26.

References

Adolphson, A. *A-hypergeometric functions and rings generated by monomials*. Duke Mathematical Journal 73 (1994), n° 2, p. 269-290.

Fernández-Fernández, M.C; Castro-Jiménez, F.J. *Gevrey solutions of the irregular hypergeometric system associated with an affine monomial curve*. To appear in Trans. Amer. Math. Soc.

Fernández-Fernández, M.C; Castro-Jiménez, F.J. *Gevrey solutions of irregular hypergeometric systems in two variables*. arXiv:0811.3390v1 [math.AG].

I.M. Gel'fand, A.V. Zelevinsky, M.M. Kapranov, *Hypergeometric functions and toral manifolds*. Funktsional Anal., 23 (1989), 2, 12-26.

References

Laurent, Y., Mebkhout, Z. *Pentes algébriques et pentes analytiques d'un \mathcal{D} -module*. Annales Scientifiques de L'É.N.S. 4^e série, tome 32, n^o 1 (1999) p.39-69.

Mebkhout, Z. *Le théorème de positivité, le théorème de comparaison et le théorème d'existence de Riemann*. Séminaires et Congrès 8 (2004), 163-310.

Saito, M., Sturmfels, B., Takayama, N.; *Gröbner Deformations of Hypergeometric Differential Equations*. Algorithms and Computation in Mathematics 6. Springer.

Schulze, M., Walther, U.; *Irregularity of hypergeometric systems via slopes along coordinate subspaces*. Duke Mathematical Journal 142, 3 (2008), 465-509.

References

Laurent, Y., Mebkhout, Z. *Pentes algébriques et pentes analytiques d'un \mathcal{D} -module*. Annales Scientifiques de L'É.N.S. 4^e série, tome 32, n° 1 (1999) p.39-69.

Mebkhout, Z. *Le théorème de positivité, le théorème de comparaison et le théorème d'existence de Riemann*. Séminaires et Congrès 8 (2004), 163-310.

Saito, M., Sturmfels, B., Takayama, N.; *Gröbner Deformations of Hypergeometric Differential Equations*. Algorithms and Computation in Mathematics 6. Springer.

Schulze, M., Walther, U.; *Irregularity of hypergeometric systems via slopes along coordinate subspaces*. Duke Mathematical Journal 142, 3 (2008), 465-509.

References

Laurent, Y., Mebkhout, Z. *Pentes algébriques et pentes analytiques d'un \mathcal{D} -module*. Annales Scientifiques de L'É.N.S. 4^e série, tome 32, n^o 1 (1999) p.39-69.

Mebkhout, Z. *Le théorème de positivité, le théorème de comparaison et le théorème d'existence de Riemann*. Séminaires et Congrès 8 (2004), 163-310.

Saito, M., Sturmfels, B., Takayama, N.; *Gröbner Deformations of Hypergeometric Differential Equations*. Algorithms and Computation in Mathematics 6. Springer.

Schulze, M., Walther, U.; *Irregularity of hypergeometric systems via slopes along coordinate subspaces*. Duke Mathematical Journal 142, 3 (2008), 465-509.

References

Laurent, Y., Mebkhout, Z. *Pentes algébriques et pentes analytiques d'un \mathcal{D} -module*. Annales Scientifiques de L'É.N.S. 4^e série, tome 32, n° 1 (1999) p.39-69.

Mebkhout, Z. *Le théorème de positivité, le théorème de comparaison et le théorème d'existence de Riemann*. Séminaires et Congrès 8 (2004), 163-310.

Saito, M., Sturmfels, B., Takayama, N.; *Gröbner Deformations of Hypergeometric Differential Equations*. Algorithms and Computation in Mathematics 6. Springer.

Schulze, M., Walther, U.; *Irregularity of hypergeometric systems via slopes along coordinate subspaces*. Duke Mathematical Journal 142, 3 (2008), 465-509.