

# Variation on the skein relation

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**Theorem (H.-O.-M.-F.-L.-Y.-P.-T.)** There exists a unique invariant  $I : \mathcal{L} \rightarrow \mathbb{C}(t, x)$  such that

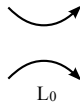
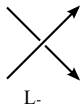
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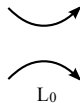
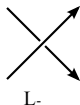


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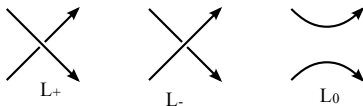
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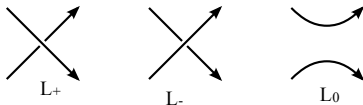


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**Corollary**  $\widetilde{\text{Skein}}(\mathcal{L})$  is of dimension 1.



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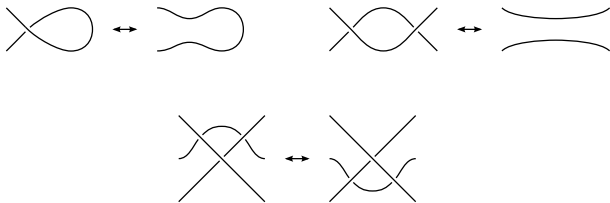
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**Example 2: Singular links.**

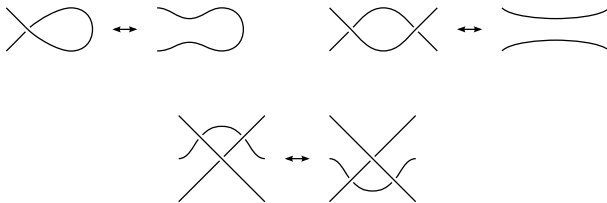
Links that admit singular crossings



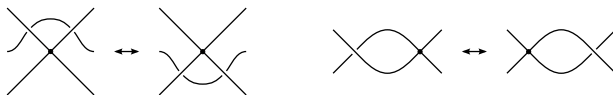
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## Singular Reidemeister moves (Kauffman)



### Example 3: Virtual links (Kauffman)

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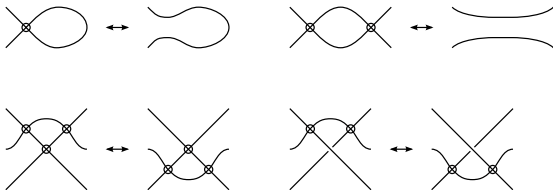


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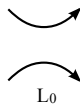
### Virtual Reidemeister moves (Kauffman)



**Definition** Let  $\mathcal{L}$  be a knot-like category.

The **Skein module** of  $\mathcal{L}$ , denoted by  $\text{Skein}(\mathcal{L})$ , is the quotient of  $\mathbb{C}(x, t)[\mathcal{L}]$  by the relations

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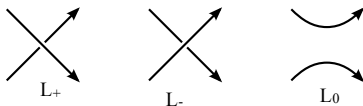




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**Note:** The space  $\widetilde{\text{Skein}}(\mathcal{L})$  of invariants  $I : \mathcal{L} \rightarrow \mathbb{C}(x, t)$  which satisfies the skein relation is

$$L(\text{Skein}(\mathcal{L}), \mathbb{C}(x, t))$$

**Skein relation:**

$$t^{-1} \cdot I(L_+) - t \cdot I(L_-) = x \cdot I(L_0)$$

**Theorem (Przytycki)** Let  $F$  be a surface and let  $\mathcal{L}$  the category of links in  $F \times I$ .

$\text{Skein}(\mathcal{L})$  is an algebra.

It is isomorphic to the symmetric tensor algebra  $SC(x, t)[\hat{\pi}^0]$ .

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**Theorem (P, Rabenda)** Let  $\mathcal{L}$  be the category of singular links in the sphere.

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It is isomorphic to  $\mathbb{C}(x, t)[X, Y]$ .

**Question** Let  $\mathcal{L}$  be the category of virtual links in the sphere.  
Determine  $\text{Skein}(\mathcal{L})$ .

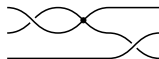
**Goal now:** To present an approach to the study of skein modules  
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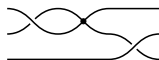
Treat the case of singular links.

**BUT** the tools exist for many other categories (links in 3-manifolds, virtual links, so on).

- Definition** A **singular braid** is a  $n$ -tuple  $\beta = (b_1, \dots, b_n)$ ,  $b_i : [0, 1] \rightarrow \mathbb{R}^2 \times [0, 1]$ , such that
- ▶  $b_i(0) = (i, 0, 0)$ ,  $b_i(1) = (\chi(i), 0, 0)$ , where  $\chi \in \text{Sym}_n$ ;
  - ▶  $b_i(t) = (*, *, t)$ ;
  - ▶  $b_1 \cup \dots \cup b_n$  has finitely many singularities (ordinary double points).



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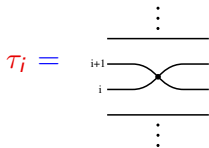
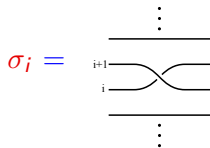


The set of singular braids form a monoid,  $SB_n$ .

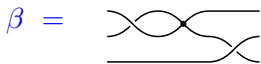


**Observation**  $SB_n$  is generated by  $\sigma_1^{\pm 1}, \dots, \sigma_{n-1}^{\pm 1}, \tau_1, \dots, \tau_{n-1}$ ,

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**Definition** From a singular braid  $\beta$  one can construct a closed braid,  $\hat{\beta}$ .



**Theorem (Alexander, Birman)** Every singular link is a closed singular braid.

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**Definition** Set  $\sqcup SB = \sqcup_{n=1}^{+\infty} SB_n$ .

$(\alpha, n), (\beta, m) \in \sqcup SB$  are connected by a **Markov move** if either

- ▶  $n = m$ ,  $\alpha = \gamma_1\gamma_2$ ,  $\beta = \gamma_2\gamma_1$ , where  $\gamma_1, \gamma_2 \in SB_n$ ; or
- ▶  $n = m + 1$  and  $\alpha = \beta\sigma_n^{\pm 1}$ ; or
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**Theorem (Markov, Gemein)** Let  $(\alpha, n), (\beta, m) \in \sqcup SB$ . We have  $\hat{\alpha} = \hat{\beta}$  if and only if  $(\alpha, n)$  and  $(\beta, m)$  are connected by finitely many Markov moves.

**Definition** The singular Hecke algebra, denoted by  $\mathcal{H}(SB_n)$ , is the quotient of  $\mathbb{C}(q)[SB_n]$  by the relations

$$\sigma_i^2 = (q - 1)\sigma_i + q, \quad i = 1, \dots, n - 1.$$

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Observe that the inclusion  $SB_n \subset SB_{n+1}$  gives rise to a homomorphism  $\iota_n : \mathcal{H}(SB_n) \rightarrow \mathcal{H}(SB_{n+1})$ .



**Definition** The Markov module (of singular braids), denoted by  $\text{Markov}(\sqcup SB)$ , is the quotient of

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by the relations

- ▶  $ab = ba$  for all  $a, b \in \mathcal{H}(SB_n)$  and all  $n \geq 1$ ;
- ▶  $a = \iota_n(a)$  for all  $a \in \mathcal{H}(SB_n)$  and all  $n \geq 1$ ;
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**Theorem (Folklore, P, Rabenda)** Let  $\mathcal{L}$  be the category of singular links. Then  $\text{Skein}(\mathcal{L})$  is isomorphic to  $\text{Markov}(\sqcup SB)$ .