

Expression Trees and the Heap

- 1 Binary Expression Trees
 - evaluating expressions
 - splitting strings in operators and operands
- 2 C++ Binary Tree of Strings
 - header files
 - defining the methods
- 3 the Heap or Priority Queue
 - a heap of integer numbers
 - the heap ADT and algorithms to push and pop
 - our class Heap with STL vector

MCS 360 Lecture 25
Introduction to Data Structures
Jan Verschelde, 11 March 2020

Expression Trees and the Heap

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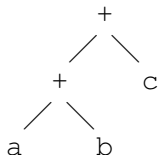
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Binary Expression Trees

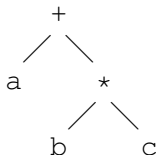
Expression trees store the evaluation order:

$a+b+c$



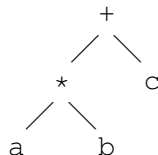
$= (a+b)+c$

$a+b*c$



$= a+(b*c)$

$a*b+c$



$= (a*b)+c$

As the children store the operands,
we first evaluate the expressions at the children.

running the program I

```
$ /tmp/strtrees
```

```
Give expression : a+b+c
```

```
your expression : a+b+c
```

```
the expression tree :
```

```
+
```

```
  +
```

```
    a
```

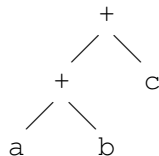
```
    b
```

```
  c
```

```
postfix : ab+c+
```

```
$
```

a+b+c

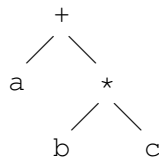


= (a+b)+c

running the program II

```
$ /tmp/strtree
Give expression : a+b*c
your expression : a+b*c
the expression tree :
+
  a
  *
    b
    c
postfix : abc*+
$
```

a+b*c

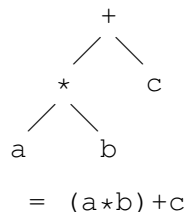


= a+(b*c)

running the program III

```
$ /tmp/strtreetree
Give expression : a*b+c
your expression : a*b+c
the expression tree :
+
 *
  a
  b
  c
postfix : ab*c+
$
```

$a*b+c$



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expressions as strings

We consider expressions with symbolic operands.

"a+b+c" is split into "a", "+", "b", "+", "c"

We split a string into a vector of strings.

Recall:

- `find()` method on string,
- `push_back()` method on vector.

splitting strings

```
vector<string> split ( string e, string op )
{
    vector<string> r;
    int i = 0;
    if(e.find(op,i) == string::npos)
        r.push_back(e);
    else
    {
        int k;
        do
        {
            k = e.find(op,i);
            r.push_back(e.substr(i,k-i));
            r.push_back(e.substr(k,1)); i = k+1;
        }
        while(!(e.find(op,i) == string::npos));
        r.push_back(e.substr(k+1));
    }
    return r;
}
```

splitting twice

We can split first on "+", then on "*".

```
$ /tmp/split
give expression : a+b*c
your expression : a+b*c
after split :
a
+
b*c
after second split :
a + ( b * c )
$
```

Instead of using a vector of strings,
the split is executed recursively with a tree.

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a node

```
#ifndef __TREE_NODE_H__
#define __TREE_NODE_H__
#include <string>

struct Node
{
    std::string data; // operator or operand
    Node *left;       // pointer to left branch
    Node *right;      // pointer to right branch

    Node(const std::string& s,
         Node* left_ptr = NULL,
         Node* right_ptr = NULL) :
        data(s), left(left_ptr), right(right_ptr) {}

    virtual ~Node() {}
};
#endif
```

mcs360_binary_expression_tree.h

```
#ifndef __MCS360_BINARY_EXPRESSION_TREE_H__
#define __MCS360_BINARY_EXPRESSION_TREE_H__

#include "mcs360_binary_expression_node.h"

namespace mcs360_binary_expression_tree
{
    class Tree
    {
    private:

        Node *root;  // data member

        // construct tree from a node
        Tree(Node *r) : root(r) {}
    };
}
```

public constructor methods

```
public:
```

```
Tree() : root(NULL) {}
```

```
Tree(const std::string& s,  
      const Tree& left = Tree(),  
      const Tree& right = Tree() ) :  
    root(new Node(s, left.root, right.root)) {}
```

Note: a tree is a pointer to a node,
though a client of `Tree` does not see the `Node` type.

other public methods

```
Tree get_left() const; // returns left child
// precondition: not is_left_null()
Tree get_right() const; // returns right child
// precondition: not is_right_null();
```

```
bool is_left_null() const;
// true if left child is null
bool is_right_null() const;
// true if right child is null
```

```
std::string get_data() const;
// returns data at node
```

```
void insert(std::string e);
void insert(std::string e, std::string op);
```

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selectors

```
#include "mcs360_binary_expression_tree.h"

namespace mcs360_binary_expression_tree
{
    Tree Tree::get_left() const {
        return Tree(root->left);
    }
    Tree Tree::get_right() const {
        return Tree(root->right);
    }
    bool Tree::is_left_null() const {
        return (root->left == NULL);
    }
    bool Tree::is_right_null() const {
        return (root->right == NULL);
    }
    std::string Tree::get_data() const {
        return root->data;
    }
}
```

the method `insert()`

```
void Tree::insert(std::string e)
{
    this->insert(e, "+");
}

void Tree::insert(std::string e, std::string op)
{
    using std::string;

    if(e.rfind(op) == string::npos)
    {
        if(op == "*")
            root = new Node(e);
        else
        {
            Tree S;
            S.insert(e, "*");
            root = S.root;
        }
    }
}
```

insert() continued

```
else
{
    int k = e.rfind(op);
    Tree L;
    L.insert(e.substr(0,k));
    Tree R;
    R.insert(e.substr(k+1));
    root = new Node(e.substr(k,1),L.root,R.root);
}
```

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the Heap

A *complete* binary tree is a *heap* if

- 1 the root is the largest element; and
- 2 the subtrees are also heaps.

If the root is largest, we have a *max* heap.

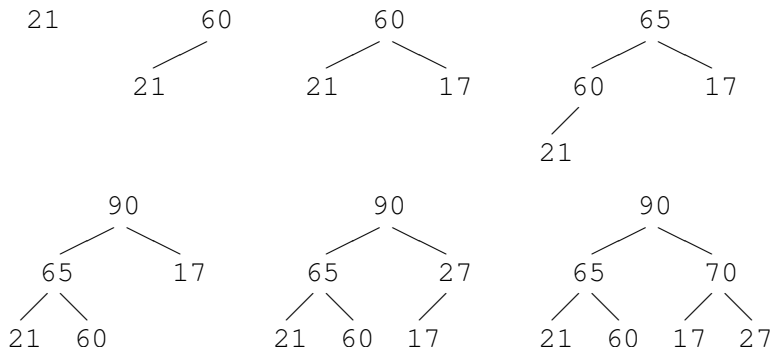
If the root is smallest, we have a *min* heap.

The root is called the *top* of the heap.

The *bottom* of the heap is the rightmost element at the deepest level of the tree.

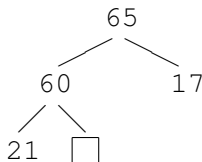
storing integer numbers

pushing 21 60 17 65 90 27 70



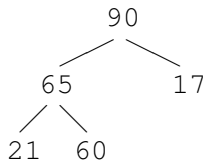
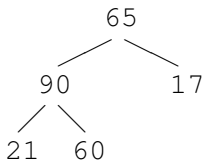
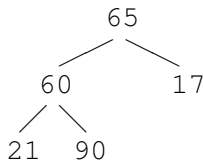
swapping numbers

Insert 90 into:



The bottom is 21, the box marks the new bottom.

As long as child is larger than parent, we swap:



Important: #swaps is bounded by depth of the tree.

If n numbers on heap, then `push()` is $O(\log_2(n))$.

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the heap ADT

```
abstract <typename T> heap;  
/* A heap is a complete binary tree where the data  
   at a node is larger than any element in the subtrees. */  
  
abstract bool empty ( heap h );  
postcondition: true if the heap is empty,  
               false if the heap is not empty.  
  
abstract T top ( heap h );  
precondition: not empty(h);  
postcondition: top(h) is the largest element in the heap;  
  
abstract T bottom ( heap h );  
precondition: not empty(h);  
postcondition: bottom(h) is the bottom element of the heap;
```

the heap ADT continued

We push to the bottom and pop from the top.

```
abstract T push ( heap h, T item );  
postcondition: push(h) inserts the item  
               in the heap h, maintaining the property  
               of the heap with the item added.
```

```
abstract T pop ( heap h );  
precondition: not empty(h);  
postcondition: removes top(h) from the  
               heap h, maintaining the property of  
               the heap with the item removed.
```

pushing and popping an item into a heap

The algorithm to push an item into a heap:

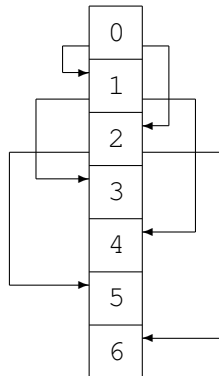
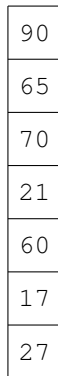
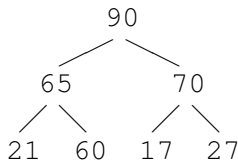
```
place the item at the new bottom
while the item is larger than the parent do
    swap the item with the parent.
```

The algorithm to pop an item from a heap:

```
remove the item, replace it with the bottom B
while B has larger children do
    swap B with its larger child.
```

The cost of the algorithm is linear in the depth of the tree,
or equivalently, logarithmic in the number of items stored.

storing heap as vector



For node at p : left child is at $2p + 1$, right child is at $2p + 2$.
Parent of node at p is at $(p - 1)/2$.

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a class Heap in the file `mcs360_integer_heap.h`

```
#ifndef __MCS360_INTEGER_HEAP_H__
#define __MCS360_INTEGER_HEAP_H__

#include<vector>
#include<string>

namespace mcs360_integer_heap
{
    class Heap
    {
    private:

        std::vector<int> h;

        int index_to_bottom;
```

public methods

public:

```
Heap(); // creates empty heap
```

```
int size() const;  
// returns the size of the heap
```

```
int top() const;  
// returns the top of the heap
```

```
int bottom() const;  
// returns the bottom of the heap
```

```
void push ( int n );  
// pushes n to the heap
```

```
#include "mcs360_integer_heap.h"

namespace mcs360_integer_heap
{
    Heap::Heap() {
        index_to_bottom = -1;
    }
    int Heap::size() const {
        return index_to_bottom+1;
    }
    int Heap::top() const {
        return h[0];
    }
    int Heap::bottom() const {
        return h[index_to_bottom];
    }
}
```


the method `push()`

```
void Heap::push( int n )
{
    if(h.size() > this->size())
        h[++index_to_bottom] = n;
    else
    {
        h.push_back(n);
        index_to_bottom++;
    }
    swap_from_bottom(index_to_bottom);
}
```

swapping elements

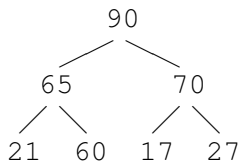
A private function member for `push()`:

```
void Heap::swap_from_bottom( int p )
{
    if(p == 0) return;

    int parent = (p-1)/2;
    if(h[parent] < h[p])
    {
        int t = h[p];
        h[p] = h[parent];
        h[parent] = t;
        swap_from_bottom(parent);
    }
}
```

converting to string

To write



the heap as vector: 90 65 70 21 60 17 27

the heap as tree:

90

65

21

60

70

17

27

writing to string

```
std::string Heap::to_tree_string( int k, int p )
{
    using std::ostringstream;
    ostringstream s;

    for(int i=0; i<k; i++) s << "  ";
    s << h[p] << std::endl;

    int left = 2*p+1;
    if(left > index_to_bottom) return s.str();
    s << to_tree_string(k+1,left);

    int right = 2*p+2;
    if(right > index_to_bottom) return s.str();
    s << to_tree_string(k+1,right);
    return s.str();
}
```

Summary + Exercises

Introduced expression trees and started §8.5 on the heap.

Exercises:

- 1 Describe the changes needed to the binary expression trees program to deal with subtraction and division. How would you handle brackets and nesting?
- 2 Implement the changes of the previous exercise.
- 3 Generate a random sequence of 10 numbers and draw the evolution of the tree (also for every swap) when pushing the numbers onto a heap.
- 4 Define an exception `EmptyHeap` to be thrown when `top()` or `bottom()` is applied to an empty heap.