

Linear Programming

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Outline of the Lecture

1. Linear Optimization Problems
2. A Geometric View on Linear Programming
3. Standard Form for a Linear Minimization
4. Application: The Diet Problem
5. The Simplex Algorithm - the idea
6. Using `linprog` in MATLAB
7. Duality Theory

1. Optimization Problems

maximize profit

subject to

$$E(\mathbf{x}) = \mathbf{a} \quad \text{equalities}$$

$$I(\mathbf{x}) \leq \mathbf{b} \quad \text{inequalities}$$

minimize cost

subject to

$$E(\mathbf{x}) = \mathbf{a}$$

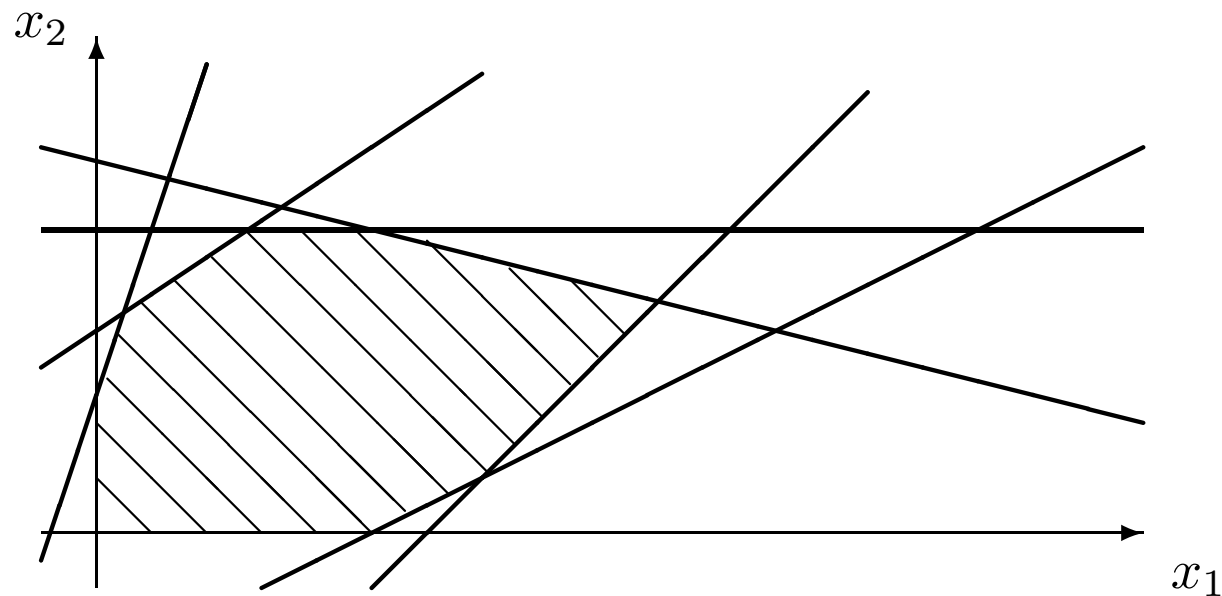
$$I(\mathbf{x}) \geq \mathbf{b}$$

A Linear Programming problem is an optimization problem

- with one linear objective function; and
- all the constraints (equalities and inequalities) are linear.

2. A Geometric View on Linear Programming

The linear constraints define a polyhedron:



- polyhedron is nonempty: problem is *feasible*
- polyhedron is bounded: problem is *well-posed*

3. Standard Form for a Linear Minimization

consider $\min \mathbf{c}^T \mathbf{x}$ $\mathbf{c}, \mathbf{x} \in \mathbb{R}^n$
subject to $A\mathbf{x} \geq \mathbf{b}$ $A \in \mathbb{R}^{m \times n}, \mathbf{b} \in \mathbb{R}^m$

slack variables $\mathbf{z} \in \mathbb{R}^m$: $A\mathbf{x} \geq \mathbf{b}$ becomes $A\mathbf{x} - \mathbf{z} = \mathbf{b}, \mathbf{z} \geq \mathbf{0}$

splitting $\mathbf{x} = \mathbf{x}^+ - \mathbf{x}^-$, $\mathbf{x}^+ \geq \mathbf{0}, \mathbf{x}^- \geq \mathbf{0}$:

$$\min [\mathbf{c} \quad -\mathbf{c} \quad \mathbf{0}] \begin{bmatrix} \mathbf{x}^+ \\ \mathbf{x}^- \\ \mathbf{z} \end{bmatrix}$$

$$\text{subject to } [A \quad -A \quad -I] \begin{bmatrix} \mathbf{x}^+ \\ \mathbf{x}^- \\ \mathbf{z} \end{bmatrix} = \mathbf{b}, \quad \begin{bmatrix} \mathbf{x}^+ \\ \mathbf{x}^- \\ \mathbf{z} \end{bmatrix} \geq \mathbf{0}$$

4. Application: the Diet Problem

Problem: plan healthy but economical meals.

nutritional elements	food quantities				minimum requirements
	x_1	x_2	\cdots	x_n	
1	a_{11}	a_{12}	\cdots	a_{1n}	c_1
2	a_{21}	a_{22}	\cdots	a_{2n}	c_2
\vdots	\vdots	\vdots	\ddots	\vdots	\vdots
m	a_{m1}	a_{m2}	\cdots	a_{mn}	c_m
price	p_1	p_2	\cdots	p_n	

Solve a linear programming problem (typically $m > n$) :

$$\min p_1x_1 + p_2x_2 + \cdots + p_nx_n$$

$$\text{subject to } a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n \geq c_i, \quad i = 1, 2, \dots, m$$

5. The Simplex Algorithm

Idea: move from one vertex to another vertex,
improving the objective value in each move.

Step 0: Bring the problem in standard form:

$$\min \mathbf{c}^T \mathbf{x} \text{ subject to } A\mathbf{x} = \mathbf{b}, \mathbf{x} \geq \mathbf{0}.$$

Step 1: Find one feasible point.

Step 2: Find one feasible *vertex* point.

Step 3: Move to vertex with improved objective value,
repeat until at optimum.

6. Using linprog in MATLAB

- MATLAB has an optimization toolbox
type `help toolbox\optim` to see an overview
- type `help linprog` for information
about the use of the simplex algorithm in MATLAB :

`x = linprog(f,A,b)` solves

$$\min_x f' * x \quad \text{subject to} \quad A * x \leq b$$

`x`

- for the diet problem: $A * x \geq c \Leftrightarrow -A * x \leq -c$

7. Every LP problem has a dual problem

$$\max \sum_{j=1}^n c_j x_j$$

subject to

$$\begin{cases} \sum_{j=1}^n a_{ij} x_j \leq b_i, & i=1,2,\dots,m \\ x_j \geq 0, & j=1,2,\dots,n \end{cases}$$

$$\min \sum_{i=1}^m b_i y_i$$

subject to

$$\begin{cases} \sum_{j=1}^n a_{ij} y_j \geq c_j, & j=1,2,\dots,n \\ y_i \geq 0, & i=1,2,\dots,m \end{cases}$$

economic interpretation :

x_j : level of activity j

c_j : unit profit of activity j

b_i : amount available of resource i

a_{ij} : amount of resource i consumed by each unit of activity j

y_i : contribution to profit per unit of resource i