

Computing Primary Decompositions

Dimension of an Ideal

computing the largest independent set

Computing the Radical of an Ideal

reduction to zero dimensional ideals

Projections

on the geometry of elimination

Putting it all together

subroutines and a recursive algorithm

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- 4 Putting it all together
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MCS 563 Lecture 35
Analytic Symbolic Computation
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dimension of an ideal

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Let I be an ideal in $\mathbb{K}[\mathbf{x}]$ and consider \mathbf{x} as a set.

For $\mathbf{u} \subset \mathbf{x}$ we say that

$$\mathbf{u} \text{ independent mod } I \text{ if } I \cap \mathbb{K}[\mathbf{u}] = \{0\},$$

if I contains no nonzero polynomials with variables only in \mathbf{u} .

Then the dimension of the ideal I is

$$\dim(I) = \max\{ \#\mathbf{u} \mid \mathbf{u} \subset \mathbf{x}, \mathbf{u} \text{ is independent mod } I \}.$$

Geometrically and algebraically, $\dim(I)$ is

- the largest dimension of the associated primes of I .
- the degree of the Hilbert polynomial of I .

using Gröbner bases

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To compute the dimension:

$\dim(I) = 0$: given a Gröbner basis G for any term order $>$
check if for all $x_i \in \mathbf{x}$ there is a $g \in G$ such that
 $LT_{>}(g) = x_i^d$ for some $d > 0$.

$\dim(I) > 0$: consider a pure lexicographical order $>_{\text{lex}}$ and
compute $\dim(I)$ as the size of S ,
 S is the left basic set of I with respect to $>_{\text{lex}}$.

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The *left basic set* S is defined recursively as $S = S_n$ with

$$S_0 = \emptyset \text{ and}$$

$$S_{k+1} = \begin{cases} S_k \cup \{x_k\} & \text{if } S_k \cup \{x_k\} \text{ is strongly independent} \\ S_k & \text{otherwise.} \end{cases}$$

mod I with respect to $>_{\text{lex}}$,

To define the notion of strong independence,
we need to refine the definition of independence.

strong independence

For disjoint subsets \mathbf{u} and \mathbf{v} of \mathbf{x} , consider

$$\mathbb{K}[\mathbf{u}/\mathbf{v}] = \{ f \in \mathbb{K}[\mathbf{u} \cup \mathbf{v}] \mid f \neq 0 \text{ and } \text{LT}(f) \in \mathbb{K}[\mathbf{u}] \}.$$

If $\mathbb{K}[\mathbf{u}/\mathbf{v}] \cap I = \emptyset$,

then \mathbf{u} is independent mod I with respect to \mathbf{v} .

If $\mathbf{v} = \emptyset$, then the clause “with respect to” drops to coincide with the earlier notion of independence.

We say that \mathbf{u} is *strongly independent* mod I

if \mathbf{u} is independent mod I with respect to $\mathbf{x} \setminus \mathbf{u}$ (so \mathbf{v} is the complement of \mathbf{u} in \mathbf{x}).

Strong independence implies independence, but not otherwise as the following example shows. Let $I = \langle x_2 - x_1 \rangle$ be an ideal in $\mathbb{K}[x_1, x_2]$, $x_2 > x_1$, $\mathbf{u} = \{x_2\}$, then \mathbf{u} is independent mod I but not strongly independent.

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Algorithm (Left Basic Set)

Input: Gröbner basis $G_{>\text{lex}}$ for I in $\mathbb{K}[\mathbf{x}]$, $1 \notin G$.

Output: S is the left basic set of I .

$S := \emptyset$; $\mathbf{u} := \mathbf{x}$;

repeat

 take $y \in \mathbf{u}$;

$\mathbf{u} := \mathbf{u} \setminus \{y\}$;

$\mathbf{t} := S \cup \{y\}$;

 if $\{\mathbf{t}^{\mathbf{a}} \mid \mathbf{a} \in \mathbb{N}^{\#\mathbf{t}}\} \cap \text{LT}_{>\text{lex}}(G) = \emptyset$ then

$S := \mathbf{t}$;

 end if;

until $\mathbf{u} = \emptyset$.

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Seidenberg's Lemma

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We assume that the coefficient field \mathbb{K} is perfect.

A field \mathbb{K} is *perfect* if every irreducible polynomial does not have multiple zeroes in the algebraic closure of \mathbb{K} .

Theorem 1

\mathbb{K} is perfect is equivalent to:

a nonconstant $f \in \mathbb{K}[\mathbf{x}]$ is square free $\Leftrightarrow \gcd(f, f') = 1$.

Lemma (Seidenberg's Lemma)

Let I be a zero dimensional ideal in $\mathbb{K}[\mathbf{x}]$ and $I \cap \mathbb{K}[x_i] = \langle f_i \rangle$, for $i = 1, 2, \dots, n$. Let $g_i = \sqrt{f_i} = \frac{f_i}{\gcd(f_i, f'_i)}$, the square free part of f_i . Then

$$\sqrt{I} = \langle I, g_1, g_2, \dots, g_n \rangle.$$

an algorithm

Algorithm (Radical)

Input: I ideal in $\mathbb{K}[\mathbf{x}]$.Output: \sqrt{I} . $\bar{P} := \langle 1 \rangle$;

repeat

 find $g \in \bar{P} \setminus \sqrt{I}$; if no such g exists then

leave loop;

else

 $J := I : g^\infty$; $\mathbf{u} :=$ maximal independent set mod J ; contract $\sqrt{J\mathbb{K}(\mathbf{u})[\mathbf{x} \setminus \mathbf{u}]}$ to $\mathbb{K}[\mathbf{x}]$; $\bar{P} := \bar{P} \cap (\sqrt{J\mathbb{K}(\mathbf{u})[\mathbf{x} \setminus \mathbf{u}]} \cap \mathbb{K}[\mathbf{x}])$;

end if;

end repeat;

 $\sqrt{I} := \bar{P}$.

recall the Shape Lemma

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We say that a zero dimensional ideal I is in general position if for a lexicographical ordering on the variables, the reduced Gröbner basis brings the ideal in shape lemma representation:

$$I = \langle x_1 - f_1(x_n), x_2 - f_2(x_n), \dots, x_{n-1} - f_{n-1}(x_n), f_n(x_n) \rangle,$$

for $f_i \in \mathbb{K}[x_n]$, $i = 1, 2, \dots, n$.

To compute the primary decomposition it then suffices to factor the last polynomial in $\mathbb{K}[\mathbf{x}]$.

zero dimensional case

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Let $I \subset \mathbb{Q}[x_1, x_2, \dots, x_n]$ be a zero dimensional ideal in general position. Assume G is a minimal Gröbner basis with respect to the lexicographical term ordering induced by $x_1 > x_2 > \dots > x_n$ and $f = I \cap \mathbb{K}[x_n]$.

If $f = f_1^{\rho_1} f_2^{\rho_2} \dots f_s^{\rho_s}$ is the factorization of f into irreducible factors, then the minimal primary decomposition of I is

$$I = \bigcap_{k=1}^s \langle I, f_k^{\rho_k} \rangle.$$

A random coordinate transformation brings an ideal in general position.

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elimination = projection

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A term order on $\mathbb{K}[\mathbf{u}, \mathbf{t}]$ eliminates \mathbf{u} : $\text{in}(f) \in \mathbb{K}[\mathbf{t}] \Rightarrow f \in \mathbb{K}[\mathbf{t}]$.

For a radical ideal, the algebraic elimination corresponds to the geometric projection of the zero set $V(I)$ with coordinates in (\mathbf{u}, \mathbf{t}) onto the \mathbf{t} -space.

Birational projections help to decide if an ideal is prime.

Suppose I contains an element f which is linear in x_1 , then

$$f(x_1, x_2, \dots, x_n) = g(x_2, \dots, x_n)x_1 + h(x_2, \dots, x_n).$$

If g is a nonzero divisor on I , then for a point

$$\mathbf{p} = (p_1, \mathbf{p}_2) \in V(I), \text{ we have } p_1 = -h(\mathbf{p}_2)/g(\mathbf{p}_2).$$

So for any solution in all n coordinates, there is unique corresponding point in $n - 1$ coordinates, and so we may decompose the ideal first in $n - 1$ variables, lifting afterwards this decomposition to n variables.

using elimination ideals

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Proposition

Let I be an ideal in $\mathbb{K}[\mathbf{x}]$. Suppose $f = gx_1 + h$ where x_1 is not involved in g and h . Moreover, g is a nonzero divisor modulo I . Denote the elimination ideal by

$I_1 = I \cap \mathbb{K}[x_2, \dots, x_n]$. Then

- 1 $I = (\langle I_1, gx_1 + h \rangle : g^\infty)$
- 2 I is prime $\Leftrightarrow I_1$ is prime
- 3 I is primary $\Leftrightarrow I_1$ is primary
- 4 Any irredundant primary decomposition of I_1 lifts to an irredundant primary decomposition of I .

Although I_1 has one fewer variable, it may be more complicated than I .

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Subroutines to compute a primary decomposition are

`saturation(I, f)` returns k and $(I : f^k) = (I : f^\infty)$;

`independentSet(I)` returns a maximal independent set
of I .

`flattener(I, t)` with $\mathbf{t} = \text{independentSet}(I)$
returns the pair $h, \text{in}_{\mathbf{u}}(I)$;

`equidimensionalPD(I, t, h)` with $h = \text{flattener}(I, \mathbf{t})$
returns the list of pairs (P, Q) , where Q is
 P -primary.

Algorithm (PDsplit)

Input: an ideal I .

Output: list of primary ideals Q_i : $I = \bigcap_{i=1}^s Q_i$.

$f := \text{SplittingPolynomial}(I)$;

if $f = \emptyset$ then

 return I ;

else

$(d, I_1) := \text{saturation}(I, f)$;

$I_2 := I_1 + \langle f^d \rangle$;

 return $\text{PDsplit}(I_1) \cup \text{PDsplit}(I_2)$;

end if.

fighting redundancy

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Methods to fight redundancy are given by

Lemma

If $(I : f^\infty) = I$ and $(I : g^\infty) = (I : g^d)$, then

$$I = (I : g^\infty) \cap ((I + \langle g^d \rangle) : f^\infty).$$

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Consider a general 3-by-3 matrix.

The ideal of all adjacent 2-by-2 minors has 4 associated primes, one of which is embedded.

Using Singular:

```
> ring R = 0,
. (x11,x12,x13,x21,x22,x23,x31,x32,x33), dp;
> ideal A233 =
.   x11*x22 - x12*x21, x12*x23 - x13*x22,
.   x21*x32 - x22*x31, x22*x33 - x23*x32;
> LIB "primdec.lib";
> primdecGTZ(A233);
```

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Consider a general 3-by-3 matrix.

The ideal of all adjacent 2-by-2 minors has 4 associated primes, one of which is embedded.

Using Macaulay 2:

```
i1 : R = QQ[x11,x12,x13,x21,x22,x23,x31,x32,x33]
i2 : I = ideal(
      x11*x22 - x12*x21, x12*x23 - x13*x22,
      x21*x32 - x22*x31, x22*x33 - x23*x32)
i3 : primaryDecomposition I
```

Summary + Exercises

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We looked at some algorithms for primary decompositions.

Exercises:

- 1 The paper of Decker, Greuel, and Pfister of 1998 contains many benchmark examples. Choose at least three examples at random and compare the performance of Macaulay 2 with Singular on those examples.