

S-polynomials

eliminating the leading term
Buchberger's criterion and algorithm

Wavelet Design

construct wavelet filters

Proof of the Buchberger Criterion

two lemmas
proof of the Buchberger criterion
termination and elimination

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- 2 **Wavelet Design**
construct wavelet filters
- 3 **Proof of the Buchberger Criterion**
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termination and elimination

MCS 563 Lecture 6
Analytic Symbolic Computation
Jan Verschelde, 24 January 2011

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The leading term of a polynomial f is denoted by $LT(f)$.

Any term is the product of a coefficient and a monomial, the leading monomial of is denoted by $LM(f)$.

$LCM(\mathbf{x}^a, \mathbf{x}^b)$ is the least common multiple of \mathbf{x}^a and \mathbf{x}^b .

To eliminate the leading term of two nonzero polynomials p and q , we compute an S-polynomial ($S =$ Subtraction):

$$S(p, q) = \frac{LCM(LM(p), LM(q))}{LT(p)} \cdot p - \frac{LCM(LM(p), LM(q))}{LT(q)} \cdot q.$$

If p and q belong to the same ideal I , then $S(p, q) \in I$.

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to $p = xy + 1$ and $q = y^2 - 1$ using $>_{\text{lex}}$ leads to

$$\begin{aligned} S(p, q) &= \frac{\text{LCM}(xy, y^2)}{xy} (xy + 1) - \frac{\text{LCM}(xy, y^2)}{y^2} (y^2 - 1) \\ &= y(xy + 1) - x(y^2 - 1), \text{ as } \text{LCM}(xy, y^2) = xy^2 \\ &= x + y \end{aligned}$$

We used p and q to define an ideal I for which the result of the division algorithm depended on the order.

With $S(p, q) \in I$ we add leading terms to the basis for I .

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A set of polynomials g is a Gröbner basis for an ideal I if

- 1 $I = \langle g \rangle$ and
- 2 the leading terms of g generate the ideal of leading terms of the polynomials in I , i.e.: $\langle \text{LT}(g) \rangle = \langle \text{LT}(I) \rangle$.

Theorem (Buchberger's criterion)

A set $g = \{g_1, g_2, \dots, g_s\}$ is a Gröbner basis if and only if for all pairs g_i and g_j , $i \neq j$, the remainder of the division of $S(g_i, g_j)$ by g equals zero.

This criterion leads to an algorithm for a Gröbner basis.

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the Buchberger algorithm

The Buchberger algorithm to compute a Gröbner basis:

Input: $f = \{f_1, f_2, \dots, f_N\}$, $I = \langle f \rangle$.

Output: $g = \{g_1, g_2, \dots, g_s\}$, $\langle \text{LT}(I) \rangle = \langle \text{LT}(g) \rangle$.

$g := f$;

repeat

$h := g$;

 for each pair (p, q) , $p \neq q$, $p, q \in g$ do

$S := S(p, q)$;

$r :=$ remainder of S after division by g ;

 if $r \neq 0$

 then $g := g \cup \{S\}$;

 end if;

 end for;

until $g = h$.

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```

g := f;
repeat
  h := g;
  for each pair (p, q), p ≠ q, p, q ∈ g do
    S := S(p, q);
    r := remainder of S after division by g;
    if r ≠ 0
      then g := g ∪ {S};
    end if;
  end for;
until g = h.

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using Macaulay 2

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\$ M2

Macaulay2, version 1.3.1

with packages: ConwayPolynomials, Elimination, Inte
PrimaryDecomposition, ReesAlgebra, S

i1 : R = QQ[x,y,MonomialOrder => Lex];

i2 : I = ideal(x^2 + 1,x*y - 1);

o2 : Ideal of R

i3 : G = gens gb I

o3 = | y²+1 x+y |

We see that $\{y^2 + 1, x + y\}$ is a Gröbner basis for the ideal $\langle x^2 + 1, xy - 1 \rangle$ with the lexicographical order.

some more Gröbner basics

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Buchberger's algorithm generalizes Euclid's algorithm for the GCD and row reduction for linear systems.

With a Gröbner bases, the division algorithm solves the ideal membership problem.

A Gröbner basis g is called reduced if

- 1 the leading coefficient of every polynomial in g is 1; and
- 2 for all $p \in g$, no monomial of p lies in $\langle LT(g \setminus \{p\}) \rangle$.

Fixing a monomial order,
any nonzero ideal has a unique reduced Gröbner basis.

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filtering a signal

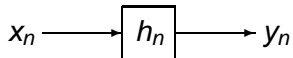
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A filter with input $\{x_n\}$ and output $\{y_n\}$ is completely determined by $\{h_n\}$, the impulse response.



With the convolution operator $*$, we compute

$$y = h * x = \sum_k x_k h_{n-k}.$$

Via the Z -transform, $Z(\{x_n\}) = \sum_n x_n z^{-n}$, $h * x$ becomes

$$Y(z) = H(z)X(z),$$

with $X(z) = Z(\{x_n\})$, $H(z) = Z(\{h_n\})$, and $Y(z) = Z(\{y_n\})$.

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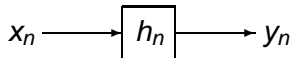
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The function $H(z)$ is called the transfer function of the filter.

We design a filter by determination of H .

Example of conditions on the transfer function:

- 1 $h_2 = h_3, h_1 = h_4;$
- 2 $(z + 1)^2$ divides $H(z);$
- 3 $\sum_n h_n h_{n-2k} = \delta(k),$
with $\delta(k) = 1$ if $k = 0, \delta(k) = 0$ if $k \neq 0.$

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a polynomial system

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$$\left\{ \begin{array}{l} h_0 + h_1 + h_2 + h_3 + h_4 + h_5 + h_6 + h_7 - 1 = 0 \\ h_2 h_0 + h_3 h_1 + h_4 h_2 + h_5 h_3 + h_6 h_4 + h_7 h_5 = 0 \\ h_6 h_2 + h_4 h_0 + h_5 h_1 + h_7 h_3 = 0 \\ h_6 h_0 + h_7 h_1 = 0 \\ h_0 - h_2 - 3h_4 - 5h_6 + 6h_7 + 4h_5 + 2h_3 = 0 \\ h_1 + 3h_3 + 5h_5 + 7h_7 - 6h_6 - 4h_4 - 2h_2 = 0 \\ h_2 - h_3 = 0 \\ h_1 - h_4 = 0 \end{array} \right.$$

Appending the equation

$$h_0 + h_1 + 2h_2 + 3h_3 + 4h_4 + 5h_5 + 6h_6 + 7h_7 - A = 0$$

leads to a more compact Gröbner basis.

Gröbner Bases

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elimination**Lemma 1**

Let $f_1, f_2, \dots, f_N \in \mathbb{C}[\mathbf{x}]$ be such that $\text{LM}(f_i) = \mathbf{x}^{\mathbf{a}}$, for all

$i = 1, 2, \dots, N$. Consider $f = \sum_{i=1}^N \gamma_i f_i$, for $\gamma_i \in \mathbb{C}$.

*If $\text{LM}(f) < \mathbf{x}^{\mathbf{a}}$, then f is a linear combination of the
S-polynomials $S(f_i, f_j)$, $1 \leq i \neq j \leq N$.*

Proof. Denote $\text{LT}(f_i) = c_i \mathbf{x}^{\mathbf{a}}$ for $c_i \in \mathbb{C} \setminus \{0\}$.

For all i, j : $\text{LM}(f_i) = \text{LM}(f_j)$: $S(f_i, f_j) = \frac{1}{c_i} f_i - \frac{1}{c_j} f_j$.

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$$\text{As } \text{LM}(f) < \mathbf{x}^{\mathbf{a}}: \sum_{i=1}^N \gamma_i \mathbf{c}_i = 0.$$

Using telescoping sums in case $N = 3$:

$$\begin{aligned} f &= \gamma_1 f_1 + \gamma_2 f_2 + \gamma_3 f_3 \\ &= \gamma_1 \mathbf{c}_1 \left(\frac{1}{\mathbf{c}_1} f_1 \right) + \gamma_2 \mathbf{c}_2 \left(\frac{1}{\mathbf{c}_2} f_2 \right) + \gamma_3 \mathbf{c}_3 \left(\frac{1}{\mathbf{c}_3} f_3 \right) \\ &= \gamma_1 \mathbf{c}_1 \left(\frac{1}{\mathbf{c}_1} f_1 - \frac{1}{\mathbf{c}_2} f_2 \right) + (\gamma_1 \mathbf{c}_1 + \gamma_2 \mathbf{c}_2) \left(\frac{1}{\mathbf{c}_2} f_2 - \frac{1}{\mathbf{c}_3} f_3 \right) \\ &\quad + (\gamma_1 \mathbf{c}_1 + \gamma_2 \mathbf{c}_2 + \gamma_3 \mathbf{c}_3) f_3 \\ &= \gamma_1 \mathbf{c}_1 S(f_1, f_2) + (\gamma_1 \mathbf{c}_1 + \gamma_2 \mathbf{c}_2) S(f_2, f_3), \end{aligned}$$

because $\gamma_1 \mathbf{c}_1 + \gamma_2 \mathbf{c}_2 + \gamma_3 \mathbf{c}_3 = 0$.

The extension for any N is clear. □

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Lemma 2

For any $p \in \mathbb{C}[\mathbf{x}]$ and $f = (f_1, f_2, \dots, f_N)$, $f_i \in \mathbb{C}[\mathbf{x}]$ for $i = 1, 2, \dots, N$ on input, the division algorithm terminates yielding

$$q_1, q_2, \dots, q_N, r \in \mathbb{C}[\mathbf{x}] : p = q_1 f_1 + q_2 f_2 + \dots + q_N f_N + r.$$

Moreover: $\text{LM}(p) = \max \left(\max_{k=1}^N (\text{LM}(q_k) \text{LM}(f_k)), \text{LM}(r) \right).$

Proof. We first show that the division algorithm terminates.

Observe that at each stage of the division algorithm we subtract from r (initialized with p), producing a sequence of polynomials $r_0 = p, r_1, r_2, \dots$

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To obtain r_{i+1} we subtract $\frac{LT(r_j)}{LT(f_k)}$ from r_i , so we have:
 $LM(r_{i+1}) < LM(r_i)$, for all i in the sequence.

This sequence must terminate for a monomial order $<$ where every set of monomials has a smallest element.

To show $LM(p) = \max \left(\max_{k=1}^N (LM(q_i)LM(f_i)), LM(r) \right)$, first recall that as the algorithm terminates: $LM(r) \leq LM(p)$.

To compute the q_i 's we collect terms $\frac{LT(r)}{LT(f_k)}$ where $\frac{LT(r)}{LT(f_k)} g_k$ cancels $LT(r)$.

Therefore: $LM(q_i)LM(f_i) \leq LM(p)$ and we are done. □

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Theorem (Buchberger's criterion)

A set $g = \{g_1, g_2, \dots, g_s\}$ is a Gröbner basis if and only if for all pairs g_i and g_j , $i \neq j$, the remainder of the division of $S(g_i, g_j)$ by g equals zero.

Proof. The \Rightarrow of the theorem follows from $S(g_i, g_j) \in \langle g \rangle$.

For the \Leftarrow direction, let $f \in I$. While we may write f in many ways, we choose this representation of f :

$$f = \sum_{i=1}^s h_i g_i, h_i \in \mathbb{C}[\mathbf{x}] \quad \text{for which} \quad \mathbf{x}^a = \max_{i=1}^s \text{LM}(h_i g_i)$$

is least. If $\text{LM}(f) = \mathbf{x}^a$, then $\text{LT}(f) \in \langle \text{LT}(g) \rangle$ and we are done. Otherwise, ...

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Otherwise we rewrite f into a representation

$$f = \sum_{i=1}^s \tilde{h}_i g_i, \tilde{h}_i \in \mathbb{C}[\mathbf{x}] \quad \text{where} \quad \max_{i=1}^s \text{LM}(\tilde{h}_i g_i) = \mathbf{x}^{\mathbf{a}},$$

contradicting our first choice ($\mathbf{x}^{\mathbf{a}}$ is least among all representations for f), leaving only $\text{LM}(f) = \mathbf{x}^{\mathbf{a}}$.

To derive the contradiction, take

$H = \{ i \mid g_i \in \mathcal{G} : \text{LM}(h_i g_i) = \mathbf{x}^{\mathbf{a}} \}$ and consider

$$p = \sum_{i \in H} \text{LT}(h_i) g_i.$$

We have $\text{LM}(\text{LT}(h_i) g_i) = \mathbf{x}^{\mathbf{a}}$, for all $i \in H$ and $\text{LM}(p) < \mathbf{x}^{\mathbf{a}}$, because $\text{LM}(f) < \mathbf{x}^{\mathbf{a}}$.

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applying Lemma 1

Application of Lemma 1 yields coefficients $c_{ij} \in \mathbb{C}$:

$$p = \sum_{i,j \in H, i \neq j} c_{ij} S(\text{LT}(h_i)g_i, \text{LT}(h_j)g_j).$$

As $\text{LCM}(\text{LM}(h_i g_i), \text{LM}(h_j g_j)) = \mathbf{x}^a$:

$$\begin{aligned} S(\text{LT}(h_i)g_i, \text{LT}(h_j)g_j) &= \frac{\mathbf{x}^a}{\text{LT}(h_i g_i)} h_i g_i - \frac{\mathbf{x}^a}{\text{LT}(h_j g_j)} h_j g_j \\ &= \frac{\mathbf{x}^a}{\text{LT}(g_i)} g_i - \frac{\mathbf{x}^a}{\text{LT}(g_j)} g_j \\ &= \frac{\mathbf{x}^a}{\mathbf{x}^b} S(g_i, g_j). \end{aligned}$$

where $\mathbf{x}^b = \text{LCM}(\text{LT}(g_i), \text{LT}(g_j))$.

The expression for $S(\text{LT}(h_i)g_i, \text{LT}(h_j)g_j)$ shows: if $S(g_i, g_j)$ reduces to 0, then also $S(\text{LT}(h_i)g_i, \text{LT}(h_j)g_j)$ reduces to 0.

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Collecting quotients from the division algorithm:

$$S(\text{LT}(h_i)g_i, \text{LT}(h_j)g_j) = \sum_{k=1}^s \tilde{h}_{ijk} g_k$$

where by the second formula of Lemma 2:

$$\begin{aligned} \max_{k=1}^s \text{LM}(\tilde{h}_{ijk} \text{LM}(g_k)) &= \text{LM}(S(\text{LT}(h_i)g_i, \text{LT}(h_j)g_j)) \\ &< \max(\text{LM}(h_i g_i) \text{LM}(h_j g_j)) = \mathbf{x}^a. \end{aligned}$$

Substituting the expressions back into g we get the representation for f which gives the contradiction. □

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Showing that this algorithm terminates also shows the Hilbert basis theorem, i.e.: any ideal has a finite basis.

The key observation is that as long as the repeat loop does not terminate, we augment g with a nonzero polynomial $S = S(p, q)$ for which $\text{LM}(S) < \text{LM}(p)$ and $\text{LM}(S) < \text{LM}(q)$, with respect to the term order $<$.

Compared to h , we thus have that $\langle \text{LT}(h) \rangle \subset \langle \text{LT}(g) \rangle$.

So as long as the loop runs, we create a chain of monomial ideals which cannot stretch for ever.

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Consider again a system of homogeneous linear equations. Applying row reduction to bring such a system into triangular form can be written in terms of taking S-polynomials.

For an ideal I in $\mathbb{C}[\mathbf{x}]$, $\mathbf{x} = (x_1, x_2, \dots, x_n)$, the k th elimination ideal is $I_k = I \cap \mathbb{C}[x_{k+1}, \dots, x_n]$.

So I_k consists of all polynomials in I for which the first k variables have been eliminated.

Theorem (The Elimination Theorem)

Let g be a Gröbner basis for an ideal I with respect to the pure lexicographical order $x_1 > x_2 > \dots > x_n$. Then the set $g_k = g \cap \mathbb{C}[x_{k+1}, \dots, x_n]$ is a Gröbner basis of the k th elimination ideal I_k .

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Proof. To prove this theorem, we must show that $\langle \text{LT}(I_k) \rangle = \langle \text{LT}(g_k) \rangle$. By construction, $\langle \text{LT}(g_k) \rangle \subset \langle \text{LT}(I_k) \rangle$, so what remains to show is that $\langle \text{LT}(I_k) \rangle \subset \langle \text{LT}(g_k) \rangle$.

For any $f \in I_k$, we must then show that $\text{LT}(f)$ is divisible by $\text{LT}(p)$ for some $p \in g_k$.

As $f \in I$: $\text{LT}(f)$ is divisible by $\text{LT}(p)$ for some $p \in g$.
Since $f \in I_k$, the only variables in f are x_{k+1}, \dots, x_n .

Because of the lexicographic order: if $\text{LT}(p) \in \mathbb{C}[x_{k+1}, \dots, x_n]$, then all other terms of p also $\in \mathbb{C}[x_{k+1}, \dots, x_n]$.

Thus the p for which $\text{LT}(p)$ divides $\text{LT}(f)$ belongs to g_k . □

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We gave a definition for the Gröbner basis, explained Buchberger's criterion and algorithm.

Exercises:

- 1 Solve the system for filter design. Use Maple or Sage to create a lexicographical Gröbner basis. Verify that by adding one more equation, the resulting Gröbner basis is more compact. How many real solutions do you find?
- 2 Apply Buchberger's algorithm by hand (you can use a Maple worksheet to compute all S-polynomials) to the ideal generated by the equations $\{x_1^2 + x_2^2 - 1, x_1 x_2 - 1\}$ using a pure lexicographical monomial order.
- 3 Show that for two systems $f(\mathbf{x}) = \mathbf{0}$ and $g(\mathbf{x}) = \mathbf{0}$: if $\langle f \rangle = \langle g \rangle$, then their solutions are the same. Give an example of a case for which the opposite direction does hold.

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4 Consider the example

$$f(x, y) = \begin{cases} x^2 + \epsilon xy + y^2 - 1 = 0 \\ y^3 - 3x^2y = 0 \end{cases} \quad \text{for } \epsilon \approx 0.$$

Although the solution set varies continuously with ϵ , we will verify that a Gröbner basis cannot be a continuous function of ϵ . Use Maple or Sage for the following calculations:

- 1 Make a plot of the two curves defined by the polynomials in the system. Justify why all intersection points are well conditioned roots.
- 2 Compute Gröbner bases for various values of ϵ and examine the growth of the coefficients as ϵ gets smaller.
- 3 Compute a Gröbner basis where ϵ is a parameter. Interpret the results.

and more exercises

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- 5 The twisted cubic is a curve in 3-space defined by $(x_1 = t, x_2 = t^2, x_3 = t^3)$, for a parameter t .

Equivalently, the equations $x_1^2 - x_2 = 0$ and $x_1^3 - x_3 = 0$ defined the twisted cubic in implicit form. The surface of all lines tangent to points on the twisted cubic is

$$\begin{cases} x_1 = t + s \\ x_2 = t^2 + 2ts \\ x_3 = t^3 + 3t^2s, \end{cases} \quad (1)$$

for parameters s and t . Compute a lexicographical Gröbner basis using a monomial order that eliminates s and t . Find an equation for the surface that defines all tangent lines to the twisted cubic.

one last exercise

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- 6 With a lexicographical Gröbner basis and a solver for polynomials in one variable we can solve zero dimensional polynomial systems, systems that have only isolated solutions. Write a procedure in a computer algebra system that takes on input a lexicographical Gröbner basis and computes all solutions by applying the univariate solver repeatedly and substituting the solutions into the remaining equations. For a numerical solver, show that the working precision must be sufficiently high enough as the solver progresses, considering the example of exercise 4.