

## Approximate Factorization

Ruppert gave in [6] a criterion for a polynomial to be irreducible. In [3] this criterion was applied to factor polynomials with approximate coefficients, based on the exact algorithms in [2].

### 1 The Ruppert Matrix

In deriving Ruppert's criterion, we follow the first observation made in [1]. Consider  $f = f(x, y)$  and suppose  $f$  is reducible and factors as  $f = f_1 f_2$ . Applying the product rule for derivatives gives

$$\frac{\partial f}{\partial x} = \frac{\partial f_1}{\partial x} f_2 + f_1 \frac{\partial f_2}{\partial x} = g_1 + g_2 \quad \text{and} \quad \frac{\partial f}{\partial y} = \frac{\partial f_1}{\partial y} f_2 + f_1 \frac{\partial f_2}{\partial y} = h_1 + h_2. \quad (1)$$

defining  $g_1 = \frac{\partial f_1}{\partial x} f_2$ ,  $g_2 = f_1 \frac{\partial f_2}{\partial x}$ ,  $h_1 = \frac{\partial f_2}{\partial y} f_2$ , and  $h_2 = f_1 \frac{\partial f_2}{\partial y}$ . Then we write the derivatives of  $\log(f_1)$  as

$$\frac{\partial}{\partial x} (\log(f_1)) = \frac{1}{f_1} \frac{\partial f_1}{\partial x} = \frac{g_1}{f} \quad \text{and} \quad \frac{\partial}{\partial y} (\log(f_1)) = \frac{1}{f_1} \frac{\partial f_1}{\partial y} = \frac{h_1}{f}. \quad (2)$$

For any  $p$  with continuous derivatives, the identity  $\frac{\partial}{\partial x} \left( \frac{\partial}{\partial y} p \right) = \frac{\partial}{\partial y} \left( \frac{\partial}{\partial x} p \right)$  holds and we apply it to  $p = \log(f_1)$  and  $\log(f_2)$  to find

$$\frac{\partial}{\partial x} \left( \frac{h_1}{f} \right) = \frac{\partial}{\partial y} \left( \frac{g_1}{f} \right) \quad \text{and} \quad \frac{\partial}{\partial x} \left( \frac{h_2}{f} \right) = \frac{\partial}{\partial y} \left( \frac{g_2}{f} \right). \quad (3)$$

Degree bounds on  $g_1$ ,  $g_2$ ,  $h_1$ , and  $h_2$  will lead to the Ruppert matrix. We denote  $\deg_x(f)$  as the degree of  $f$  when viewed as a polynomial only in  $x$ . Similarly,  $\deg_y(f)$  is the degree of  $f$  as a polynomial in  $y$  only.

The criterion in [6] for  $f$  to be irreducible as a partial differential equation is formulated in Theorem 1.1.

**Theorem 1.1** *A polynomial  $f(x, y) \in \mathbb{C}[x, y]$  is irreducible if and only if*

$$\frac{\partial}{\partial y} \left( \frac{g}{f} \right) = \frac{\partial}{\partial x} \left( \frac{h}{f} \right) \quad (4)$$

*has no nonzero solutions for all polynomial  $g, h \in \mathbb{C}[x, y]$ , with  $\deg_x(g) \leq \deg_x(f) - 1$ ,  $\deg_y(g) \leq \deg_y(f)$ , and  $\deg_x(h) \leq \deg_x(f)$ ,  $\deg_y(h) \leq \deg_y(f) - 2$ .*

Note that if the condition  $\deg_y(h) \leq \deg_y(f) - 2$  on  $h$  is changed into  $\deg_y(h) \leq \deg_y(f) - 1$ , then  $g = f_x$  and  $h = f_y$  is a solution to (4), regardless whether  $f$  is irreducible or not.

Consider for example  $f(x, y) = x^2 + y^2 - 1$ . Then  $g(x, y) = a_{00} + a_{10}x + a_{01}y + a_{11}xy + a_{02}y^2 + a_{12}xy^2$  and  $h(x, y) = b_{00} + b_{10}x + b_{20}x^2$  are the general forms of the polynomials to satisfy (4). The sequence of commands in Maple generates the Ruppert matrix for  $f$ :

```
[> f := x^2 + y^2 - 1;
> g := sum(sum(a[i,j]*x^i*y^j,i=0..degree(f,x)-1),j=0..degree(f,y));
> h := sum(sum(b[i,j]*x^i*y^j,i=0..degree(f,x)),j=0..degree(f,y)-2);
> eq := diff(g/f,y) - diff(h/f,x);
> nq := normal(eq); p := numer(nq); s := coeffs(p,[x,y]);
> sys := {seq(s[i]=0,i=1..nops([s]))}; var := indets(sys);
> R := LinearAlgebra[GenerateMatrix](sys,var)[1];
> LinearAlgebra[Rank](R);
```

The rank of the matrix  $R$  equals 9, which equals the number of columns, so  $f$  is indeed irreducible.

## 2 An Open Problem in Symbolic-Numeric Computing

As stated in [1], polynomial factorization is one of the main chapters in computer algebra. In [4], the following problem is stated:

“Given is a polynomial  $f(x, y) \in \mathbb{Q}[x, y]$  and  $\epsilon \in \mathbb{Q}$ . Decide in polynomial time in the degree and coefficient size if there is a factorizable  $\bar{f}(x, y) \in \mathbb{C}[x, y]$  with  $\|f - \bar{f}\| \leq \epsilon$ , for a reasonable coefficient vector norm  $\|\cdot\|$ .”

In Figure 1 we see plots of an example of [4], once plotted just as given  $p$  and once after first executing `factor(p, sqrt(2))` and then plotting the factors.

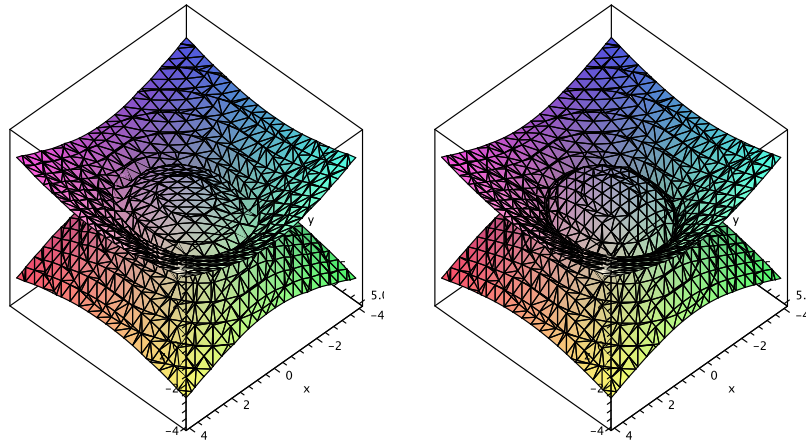


Figure 1: Exported plots of `implicitplot3d` with Maple of  $81x^4 + 16y^4 - 648z^4 + 72x^2y^2 - 648x^2 - 288y^2 + 1296$  and  $(9x^2 + 4y^2 + 18\sqrt{2}z^2 - 36)(9x^2 + 4y^2 - 18\sqrt{2}z^2 - 36)$ .

## 3 The Kernel of the Ruppert Matrix

Like in [3], we assume that the polynomial  $f$  we have to factor is square free, i.e.:  $\text{GCD}(f, f_x) = 1$ . In [2], the condition on  $h$  is relaxed to  $\deg_y(h) \leq \deg_y(f) - 1$  and (4) is rewritten into

$$f \cdot \left( \frac{\partial g}{\partial y} - \frac{\partial h}{\partial x} \right) + h \cdot \frac{\partial f}{\partial x} - g \cdot \frac{\partial f}{\partial y} = 0. \quad (5)$$

The relaxation of the condition on  $h$  implies that system of linear equations (5) will always have one solution, also if  $f$  is irreducible. Moreover, the dimension of the solution space equals the number of irreducible factors of  $f$ . Abusing notation,  $R(f)$  will still be called the Ruppert matrix, for the matrix resulting of the relaxation on the degree of  $h$ .

Once we have a basis of the null space of the Ruppert matrix, how do we then recover the irreducible factors? Solving [1, Exercise 9.2.11], Proposition 3.1 suggests using the GCD.

**Proposition 3.1** Let  $f = f(x, y)$ ,  $f = f_1 f_2 \cdots f_s$ , and  $g_i = \frac{\partial f_i}{\partial x} \frac{f}{f_i}$ ,  $i = 1, 2, \dots, s$ .

$$v = \sum_{i=1}^s \gamma_i g_i, \quad \gamma_i \neq \gamma_j, i \neq j \quad \Rightarrow \quad f_i = \text{GCD} \left( f, v - \gamma_i \frac{\partial f}{\partial x} \right), \quad i = 1, 2, \dots, s. \quad (6)$$

*Proof.* To avoid dot dot dots, we assume  $s = 3$ . The  $g_i$ 's are defined as  $g_1 + g_2 + g_3 = \frac{\partial f}{\partial x}$ . Then:

$$v - \gamma_1 \frac{\partial f}{\partial x} = \gamma_1 g_1 + \gamma_2 g_2 + \gamma_3 g_3 - \gamma_1 (g_1 + g_2 + g_3) \quad (7)$$

$$= (\gamma_2 - \gamma_1) g_2 + (\gamma_3 - \gamma_1) g_3 \quad (8)$$

$$= (\gamma_2 - \gamma_1) \frac{\partial f_2}{\partial x} f_1 f_3 + (\gamma_3 - \gamma_1) \frac{\partial f_3}{\partial x} f_1 f_2. \quad (9)$$

Because  $\gamma_2 \neq \gamma_1$  and  $\gamma_3 \neq \gamma_1$  we find

$$\text{GCD} \left( f, v - \gamma_1 \frac{\partial f}{\partial x} \right) = \text{GCD} \left( f_1 f_2 f_3, (\gamma_2 - \gamma_1) \frac{\partial f_2}{\partial x} f_1 f_3 + (\gamma_3 - \gamma_1) \frac{\partial f_3}{\partial x} f_1 f_2 \right) = f_1. \quad (10)$$

The derivations are similar for  $f_2$  and  $f_3$ .  $\square$

Before we can apply the GCD to the basis elements of the null space we must ensure that these basis elements have the desired form.

**Proposition 3.2** Consider  $f = f(x, y)$  and  $f = f_1 f_2 \cdots f_s$ . Denote by  $R(f)$  the Ruppert matrix of the system (5) linear in the coefficient vectors of the polynomials  $g$  and  $h$  with  $\deg(g) \leq (\deg_x(f) - 1, \deg_y(f))$  and  $\deg(h) \leq (\deg_x(f), \deg_y(f) - 1)$ . Let  $\mathbf{u} : R(f)\mathbf{u} = \mathbf{0}$ , then  $\mathbf{u} = (\mathbf{v}, \mathbf{w})$ , where  $\mathbf{v}$  and  $\mathbf{w}$  are coefficient vectors of the respective polynomials  $g$  and  $h$ . Identifying the coefficient vector  $\mathbf{v}$  with the polynomial  $v(x, y)$  we have:

$$v(x, y) = \sum_{i=1}^s \gamma_i g_i(x, y), \quad g_i = \frac{\partial f_i}{\partial x} \frac{f}{f_i}, \quad i = 1, 2, \dots, s, \quad (11)$$

for some constants  $\gamma_i \in \mathbb{C}$ .

*Proof.* Assuming  $f$  is monic, we write  $f$  as a function of  $y$ , expressing the values for the  $x$ -coordinates of  $f$  as  $x_i(y)$ ,  $i = 1, 2, \dots, d$ , where  $d = \deg_x(f)$ :

$$f(x(y), y) = \prod_{i=1}^d (x - x_i(y)). \quad (12)$$

Since  $\deg_x(v) < \deg_x(f)$ , we have a partial fraction decomposition

$$\frac{v}{f} = \sum_{i=1}^d \frac{a_i(y)}{x - x_i(y)}, \quad a_i(y) = \frac{v(x_i(y), y)}{\prod_{j \neq i} (x - x_j(y))} = \frac{v(x_i(y), y)}{\frac{\partial f}{\partial x}(x_i(y), y)}. \quad (13)$$

We obtain the expression for  $a_i(y)$  by equating numerators in the partial fraction decomposition identity for  $v/f$ . For the polynomial  $w(x, y)$  with coefficient vector  $\mathbf{w}$ , corresponding to the coefficient vector  $\mathbf{v}$  of  $v$ , we also set up a partial fraction decomposition:

$$\frac{w}{f} = \sum_{i=1}^d \frac{b_i(y)}{x - x_i(y)} + b_0, \quad b_0 \in \mathbb{C}. \quad (14)$$

Because  $\mathbf{u} = (\mathbf{v}, \mathbf{w})$  belongs to the kernel of  $R(f)$ :  $\frac{\partial}{\partial y} \left( \frac{v}{f} \right) = \frac{\partial}{\partial x} \left( \frac{w}{f} \right)$ . Applying this property to the partial fraction decompositions in (13) and (14):

$$\frac{\partial}{\partial y} \left( \frac{v}{f} \right) = \sum_{i=1}^d \frac{-b_i^2}{(x - x_i(y))^2} \quad (15)$$

$$\frac{\partial}{\partial x} \left( \frac{v}{f} \right) = \sum_{i=1}^d \frac{1}{x - x_i(y)} \frac{\partial a_i}{\partial y} + \sum_{i=1}^d \frac{a_i}{(x - x_i(y))^2} \left( -\frac{\partial x_i}{\partial y} \right). \quad (16)$$

So we find that  $\frac{\partial}{\partial y} \left( \frac{v}{f} \right) = \frac{\partial}{\partial x} \left( \frac{w}{f} \right)$  implies  $\frac{\partial a_i}{\partial y} = 0$ .

The constant coefficients  $a_i$  belonging to the same factor  $f_k$  of  $f$  are all conjugated and are all equal, say to  $\gamma_k$ . So we may write

$$\frac{v}{f} = \sum_{k=1}^s \frac{\gamma_k}{\prod_j (x - x_j(y))} = \sum_{k=1}^s \gamma_k \frac{\partial f_k}{\partial x} \frac{1}{f_k}. \quad (17)$$

Therefore  $v = \sum_{k=1}^s \gamma_k \frac{\partial f_k}{\partial x} \frac{f}{f_k} = \sum_{k=1}^s \gamma_k g_k$ .  $\square$

Although we now know that a basis of the kernel of  $R(f)$  gives linear combinations of the  $g_i$ 's, to apply Proposition 3.1, we need the actual  $g_i$ 's itself. Our third proposition brings us there.

**Proposition 3.3** *Let the matrix  $V = [\mathbf{v}_1 \mathbf{v}_2 \cdots \mathbf{v}_s]$  collect the components of the basis vectors of the kernel of the Ruppert matrix  $R(f)$ , i.e.  $R(f)\mathbf{u} = \mathbf{0}$ ,  $\mathbf{u} = (\mathbf{v}, \mathbf{w})$ ,  $\mathbf{v}$  contains the coefficient vectors of the polynomials  $g$  of Ruppert's criterion. For any  $\mathbf{v}$  in the span of  $V$ , there is a unique matrix  $A \in \mathbb{C}^{s \times s}$ :*

$$\mathbf{v}\mathbf{v}_i = \sum_{j=1}^s a_{ij} \mathbf{v}_j \frac{\partial f}{\partial x} \pmod{f} \text{ in } \mathbb{C}(y)[x]. \quad (18)$$

Moreover:

$$f = \prod_{\lambda \in \mathbb{C}} \text{GCD} \left( f, v - \lambda \frac{\partial f}{\partial x} \right), \quad (19)$$

$$\det(A - \lambda I) = 0$$

i.e.: the  $i$ th irreducible factor of  $f$  is  $f_i = \text{GCD} \left( f, v - \lambda_i \frac{\partial f}{\partial x} \right)$ , where  $\lambda_i$  the  $i$ th eigenvalue of  $A$ .

*Proof.* Because  $\mathbf{v} = \gamma_1 g_1 + \gamma_2 g_2 + \cdots + \gamma_s g_s$ , with  $g_i = \frac{f}{f_i} \frac{\partial f}{\partial x}$ , the second statement of the proposition follows immediately if  $\gamma_i = \lambda_i$ , as  $f_i$  divides  $\mathbf{v} - \lambda_i \frac{\partial f}{\partial x}$ .

Since  $V$  is a basis for the null space of the Ruppert matrix, there exists an  $s$ -by- $s$  matrix  $B$  such that

$$\begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \vdots \\ \mathbf{v}_s \end{bmatrix} = B \begin{bmatrix} g_1 \\ g_2 \\ \vdots \\ g_s \end{bmatrix}. \quad (20)$$

We have that  $g_i g_j = \left( \frac{\partial f_i}{\partial x} \prod_{\substack{k=1 \\ k \neq i}}^s f_k \right) \left( \frac{\partial f_j}{\partial x} \prod_{\substack{k=1 \\ k \neq j}}^s f_k \right)$  is a multiple of  $f$  for  $i \neq j$ , so  $g_i g_j \equiv 0 \pmod{f}$ . Then we can write

$$\mathbf{v} \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \vdots \\ \mathbf{v}_s \end{bmatrix} \equiv B \begin{bmatrix} \mathbf{v} g_1 \\ \mathbf{v} g_2 \\ \vdots \\ \mathbf{v} g_s \end{bmatrix} \equiv B \begin{bmatrix} \lambda_1 g_1^2 \\ \lambda_2 g_2^2 \\ \vdots \\ \lambda_s g_s^2 \end{bmatrix} \equiv B \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_s \end{bmatrix} \begin{bmatrix} g_1^2 \\ g_2^2 \\ \vdots \\ g_s^2 \end{bmatrix} \pmod{f}. \quad (21)$$

The multiplication of  $\frac{\partial f}{\partial x}$  with  $V$  leads to

$$\frac{\partial f}{\partial x} \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \vdots \\ \mathbf{v}_s \end{bmatrix} \equiv B \begin{bmatrix} \frac{\partial f}{\partial x} g_1 \\ \frac{\partial f}{\partial x} g_2 \\ \vdots \\ \frac{\partial f}{\partial x} g_s \end{bmatrix} \equiv B \begin{bmatrix} g_1^2 \\ g_2^2 \\ \vdots \\ g_s^2 \end{bmatrix} \pmod{f}, \quad \text{as } \frac{\partial f}{\partial x} = \sum_{i=1}^s g_i. \quad (22)$$

So we substitute

$$\begin{bmatrix} g_1^2 \\ g_2^2 \\ \vdots \\ g_s^2 \end{bmatrix} \equiv B^{-1} \frac{\partial f}{\partial x} \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \vdots \\ \mathbf{v}_s \end{bmatrix} \pmod{f} \quad (23)$$

into (21) and find that the matrix

$$A = B \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_s \end{bmatrix} B^{-1} \quad (24)$$

has eigenvalues  $\lambda_i$ ,  $i = 1, 2, \dots, s$ . □

The three propositions lead to Gao's theorem [1] and his algorithm to factor polynomials, described in [2].

## 4 SVD and Approximate GCD

In [3], the authors propose to use the singular value decomposition (SVD) to compute a basis for the null space of the linear system defined by (5). This basis is formed by the last  $r$  right singular vectors of the coefficient matrix of the linear system. The rank  $r$  of the null space occurs at the biggest gap  $\max_i(\sigma_{i+1}/\sigma_i)$  in the singular values  $\sigma_i$ .

Once a basis for the null space is computed, a random combination  $p$  of the polynomials corresponding to the basis vectors is taken. Fixing  $y = \alpha \in \mathbb{C}$ , where  $\alpha$  is random, the roots  $\lambda_i$  of  $p$  determine the factors of  $f$ :  $f_i = \text{GCD}(f, v - \lambda_i f_x)$ , for  $i = 1, 2, \dots, r$ , for  $v$  a basis vector in the null space of the Ruppert matrix. The algorithm ends with a computation of the backward error. In [5], Gauss-Newton is applied to improve the accuracy of the computed factors.

The algorithm below is an adaptation from [3].

### Algorithm 4.1 (Approximate Bivariate Factorization)

Input:  $f \in \mathbb{C}[x, y]$ ,  $\text{GCD}(f, \frac{\partial f}{\partial x}) = 1$ ,  $f$  has no approximate factors in  $\mathbb{C}[y]$ ;

$S \subset \mathbb{C}$  and  $\#S \geq \deg_x(f) \times \deg_y(f)$ .

Output: list of approximate factors of  $f$ .

**Stage 1:** form the Ruppert matrix  $R(f)$ ;

find the last  $\deg(f) + 1$  singular values  $\sigma_i$  of  $R(f)$ ,  $\sigma_n \geq \sigma_{n-1} \geq \cdots \geq \sigma_2 \geq \sigma_1$ ;

let  $s$  be the index so  $\sigma_{s+1}/\sigma_s$  is maximal;

if  $s = 1$ , then return  $f$ ;

form a basis  $\mathbf{v}_1, \mathbf{v}_1, \dots, \mathbf{v}_s$  from the last  $s$  right singular vectors of  $R(f)$ ;

**Stage 2:**  $\mathbf{v} := \sum_{s_i \in S} s_i \mathbf{v}_i$ , with coefficients  $s_i$  selected uniformly and independently;

for  $y = \alpha$ , compute  $a_{ij}$  that minimize  $\left\| \text{remainder} \left( \mathbf{v} \mathbf{v}_i - \sum_{j=1}^s a_{ij} \mathbf{v}_j \frac{\partial f}{\partial x}, f \right) \right\|_2$ ;  
 compute the eigenvalues  $\lambda_i$  of  $A = [a_{ij}]$ ;

**Stage 3:**  $f_i := \text{GCD} \left( f, \mathbf{v} - \lambda_i \frac{\partial f}{\partial x} \right)$ , for  $i = 1, 2, \dots, s$ , where GCD is an approximate GCD.

We end with some comments on the algorithm. The algorithm in [3] chooses another selection of the values  $s_i$  of  $S$  if the computed eigenvalues are clustered. The matrix  $A$  is formed reducing  $\mathbf{v} \mathbf{v}_i$  and  $g_j \frac{\partial f}{\partial x}$  with respect to  $y = \alpha$  via a least squares problem. The algorithm in [3] ends with a backward error computation and iterative refinement of the approximate factors.

## 5 Exercises

1. Find a general formula for the size of the Ruppert matrix, in terms of the degrees  $\deg_x(f)$  and  $\deg_y(f)$ .
2. Show that for  $f = f(x, y)$ ,  $f = f_1 f_2$ ,  $g_1 = \frac{\partial f_1}{\partial x} f_2$ ,  $g_2 = f_1 \frac{\partial f_2}{\partial x}$ ,  $h_1 = \frac{\partial f_2}{\partial y} f_2$ , and  $h_2 = f_1 \frac{\partial f_2}{\partial y}$ :

$$f \left( \frac{\partial g_1}{\partial y} - \frac{\partial h_1}{\partial x} \right) + h_1 \frac{\partial f}{\partial x} - g_1 \frac{\partial f}{\partial y} = 0. \quad (25)$$

3. Download the Maple code at [http://www4.ncsu.edu/~kaltofen/software/appfac/issac04\\_mws/multifac\\_1.3.mpl](http://www4.ncsu.edu/~kaltofen/software/appfac/issac04_mws/multifac_1.3.mpl) and use it to factor (example from [2]):

$$f(x, y) = 9 + 23y^2 + 13yx^2 + 6y + 7y^3 + 13y^2x^2 + x^4 + 6yx^4 + x^6. \quad (26)$$

4. Download `ApaTools` available via [7] and use it to factor the example (26) from the previous exercise. Instead of (or in addition to) `ApaTools`, you may also consider `NAClab` at [www.neiu.edu/~nacalab](http://www.neiu.edu/~nacalab) to solve the exercise.
5. Consider  $f$  in (26), but now add some random errors to the coefficients, of magnitude  $10^{-k}$ , for  $k$  ranging from 1 to 14. For  $k = 1$ ,  $f$  is irreducible, while for  $k = 14$ , the numerical algorithm should return the same factorization as in the exact case. For which  $k$  is  $f$  no longer irreducible?

## References

- [1] G. Chèze and A. Galligo. Four lectures on polynomial absolute factorization. In A. Dickenstein and I.Z. Emiris, editors, *Solving Polynomial Equations. Foundations, Algorithms and Applications*, volume 14 of *Algorithms and Computation in Mathematics*, pages 339–394. Springer–Verlag, 2005.
- [2] S. Gao. Factoring multivariate polynomials via partial differential equations. *Mathematics of Computation*, 72(242):801–822, 2002.
- [3] S. Gao, E. Kaltofen, J. May, Z. Yang, and L. Zhi. Approximate factorization of multivariate polynomials via differential equations. In J. Gutierrez, editor, *Proceedings of the 2004 International Symposium on Symbolic and Algebraic Computation (ISSAC 2004)*, pages 167–174. ACM, 2004.

- [4] E. Kaltofen. Challenges of symbolic computation: my favorite open problems. *J. Symbolic Computation*, 29(6):891–919, 2000.
- [5] E. Kaltofen, J.P. May, Z. Yang, and L. Zhi. Approximate factorization of multivariate polynomials using singular value decomposition. *Journal of Symbolic Computation*, 43(5):359–376, 2008.
- [6] W.M. Ruppert. Reducibility of polynomials  $f(x, y)$  modulo  $p$ . *Journal of Number Theory*, 77(1):62–70, 1999.
- [7] Z. Zeng. ApaTools: a software toolbox for approximate polynomial algebra. In M.E. Stillman, N. Takayama, and J. Verschelde, editors, *Software for Algebraic Geometry*, volume 148 of *The IMA Volumes in Mathematics and Its Applications*, pages 149–167. Springer-Verlag, 2008.