

Elementary Matrices

①

$$\begin{pmatrix} 1 & 0 \\ r & 1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a & b \\ c+ra & d+rb \end{pmatrix}$$

$$\begin{pmatrix} 3 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 3a & 3b \\ c & d \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ s & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & k \end{pmatrix} = \begin{pmatrix} a & b & c \\ d+sa & e+sb & f+sc \\ g & h & k \end{pmatrix}$$

Let $E_{ij} = \begin{pmatrix} \ddots & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \ddots \end{pmatrix}$ one entry s in the ij place, $i \neq j$

$$\Rightarrow E_{ij} \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_n \end{pmatrix} = \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_i + s\vec{r}_j \\ \vdots \\ \vec{r}_n \end{pmatrix}$$

When $i=j$, we assume $s \neq \phi$.

For example, $E_{32} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & s & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad (4 \times 4)$

$$E_{32} \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vec{r}_3 \\ \vec{r}_4 \end{pmatrix} = \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vec{r}_3 + s\vec{r}_2 \\ \vec{r}_4 \end{pmatrix}$$

$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vec{r}_3 \end{pmatrix} = \begin{pmatrix} \vec{r}_2 \\ \vec{r}_3 \\ \vec{r}_1 \end{pmatrix}$
Permutation Matrices are also elementary.

All row operations can be accomplished by multiplication (on the left) by elementary matrices.

Example: $\begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix} \xrightarrow{r_2 \mapsto r_2 - 2r_1} \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}$ (B)

$$\begin{pmatrix} 1 & 0 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}$$

$$\begin{matrix} \parallel \\ E_1 \\ E_2 \\ \parallel \end{matrix} \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} \xrightarrow{r_1 \mapsto r_1 - 2r_2} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Note $E_2 E_1 = \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

$$\begin{pmatrix} 1 & -2 \\ -2 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix}^{-1}$$

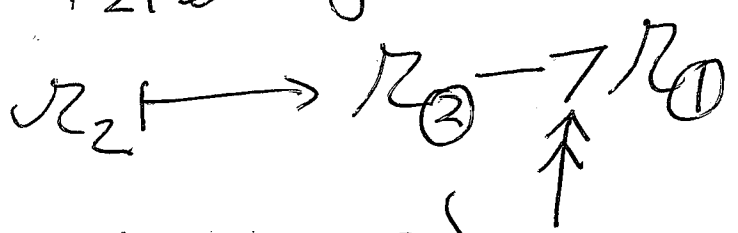
If a sequence of elementary matrices E_1, E_2, \dots, E_k transform M into row echelon form R ,

then $(E_k E_{k-1} \dots E_1) M = R$.

If $R = I$, then $(E_k \dots E_1) = M^{-1}$.

$$E = \begin{pmatrix} 1 & 0 & 0 \\ -7 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

21 entry



$$EM = \begin{pmatrix} 1 & 0 & 0 \\ -7 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 7 & 9 & 11 \\ 4 & 5 & 6 \end{pmatrix}$$

What is E^{-1} ?

$$E^{-1}E = I$$

$$E^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 7 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 7 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ -7 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Example

$$M = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} \xrightarrow{r_2 \rightarrow r_2 - r_1} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = E_1$$

$$r_3 \rightarrow r_3 - r_1 \quad \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} = E_2$$

$$\Rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}$$

$$r_3 \rightarrow r_3 - r_2 \quad \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} = E_3$$

$$\Rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow M^{-1} = E_3 E_2 E_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix}$$

Check: $\begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \checkmark$

Exercise: What row operation is encoded by?

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} ?$$

$$A = \begin{pmatrix} 2 & 4 & 2 \\ 1 & 5 & 2 \\ 4 & -1 & 9 \end{pmatrix}$$

(c)

$$E_3 E_2 E_1 A = \begin{pmatrix} 2 & 4 & 2 \\ 0 & 3 & 1 \\ 0 & 0 & 8 \end{pmatrix} = U$$

$$E_1 = \begin{pmatrix} 1 & 0 & 0 \\ -\frac{1}{2} & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad R_2 \rightarrow R_2 - \frac{1}{2}R_1$$

$$E_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix} \quad R_3 \rightarrow R_3 - 2R_1$$

$$E_2 E_1 A = \begin{pmatrix} 2 & 4 & 2 \\ 0 & 3 & 1 \\ 0 & -5 & 5 \end{pmatrix} \xrightarrow{R_3 \rightarrow R_3 + 3R_2} \begin{pmatrix} 2 & 4 & 2 \\ 0 & 3 & 1 \\ 0 & 0 & 8 \end{pmatrix}$$

$$E_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 3 & 1 \end{pmatrix}$$

$$E_3 E_2 E_1 A = U$$

$$A = E_1^{-1} E_2^{-1} E_3^{-1} U$$

$$E_3 E_2 E_1 A = U \quad \textcircled{c''}$$

$$\Rightarrow E_2 E_1 A = E_3^{-1} U$$

$$E_1 A = E_2^{-1} E_3^{-1} U$$

$$A = E_1^{-1} E_2^{-1} E_3^{-1} U$$

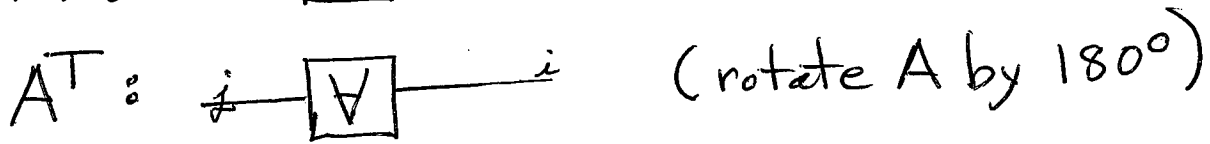
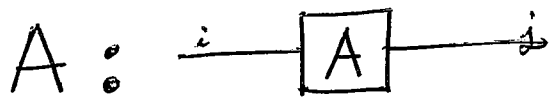
$$E_1^{-1} E_2^{-1} E_3^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -3 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ 2 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -3 & 1 \end{pmatrix}$$

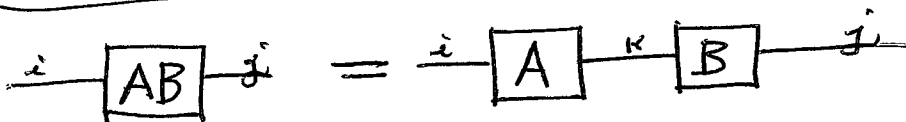
$$= \begin{pmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ 2 & -3 & 1 \end{pmatrix} = L$$

$$\text{Then } \begin{pmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ 2 & -3 & 1 \end{pmatrix} \begin{pmatrix} 2 & 4 & 2 \\ 0 & 3 & 1 \\ 0 & 0 & 8 \end{pmatrix} = \begin{pmatrix} 2 & 4 & 2 \\ 1 & 5 & 2 \\ 4 & -1 & 9 \end{pmatrix} = A$$

More Diagrammatics

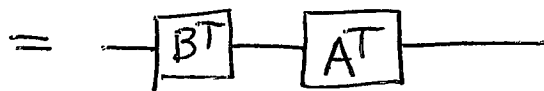
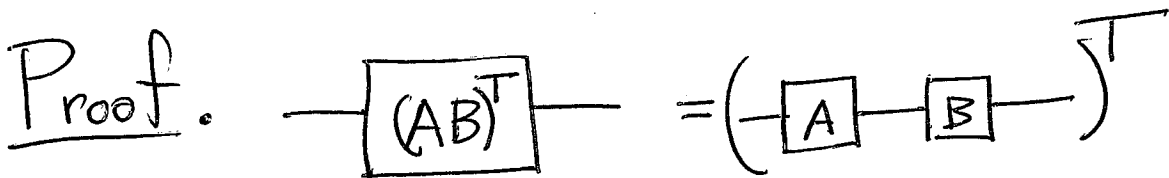


$$(A^T)_{ij} = A_{ji}, (A^T)_{ji} = A_{ij}$$



$$(AB)_{ij} = \sum_k A_{ik} B_{kj}$$

Theorem. $(AB)^T = (B^T)(A^T)$.



$\Rightarrow (AB)^T = B^T A^T$ QED

Compare with

$$(AB)^T_{ij} = (AB)_{ji} = \sum_k A_{jk} B_{ki}$$

$$= \sum_k A^T_{kj} B^T_{ik} = \sum_k B^T_{ik} A^T_{kj} = (B^T A^T)_{ij}$$

$\therefore (AB)^T = B^T A^T$ //

$|AB| = |A||B|$
For 2x2 Matrices

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, B = \begin{pmatrix} e & f \\ g & h \end{pmatrix}$$

$$AB = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} e & f \\ g & h \end{pmatrix} = \begin{pmatrix} ae+bg & af+bh \\ ce+dg & cf+dh \end{pmatrix}$$

$$|AB| = (ae+bg)(cf+dh) - (af+bh)(ce+dg)$$

$$= \begin{matrix} \downarrow & & \downarrow \\ aecf + aedh & - & afce - afdg \\ + bgcf + bgdh & - & bhce - bhdg \end{matrix}$$

$$= aedh + bgcf - afdg - bhce$$

$$|A||B| = (ad-bc)(eh-fg)$$

$$= \begin{matrix} \downarrow & & \downarrow \\ adeh + bcfg & - & bceh - adfg \end{matrix}$$

$\therefore |AB| = |A||B|$

Determinants :

$$\text{dets defined by } \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc \quad \textcircled{1}$$

Computational definition.

Suppose $(n-1) \times (n-1)$ dets already defined. If M is $n \times n$ then the minors $M(i, j)$ are the matrices obtained from M by eliminating row i & col j .

$$M = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 7 & 9 \\ 3 & 4 & 5 \end{pmatrix} : \quad M(1,1) = \begin{pmatrix} \cancel{1} & \cancel{2} & \cancel{3} \\ 2 & 7 & 9 \\ 3 & 4 & 5 \end{pmatrix} = \begin{pmatrix} 7 & 9 \\ 4 & 5 \end{pmatrix}$$

$$M(2,2) = \begin{pmatrix} 1 & \cancel{2} & \cancel{3} \\ 2 & 7 & 9 \\ \cancel{3} & 4 & 5 \end{pmatrix} = \begin{pmatrix} 1 & 3 \\ 3 & 5 \end{pmatrix}$$

$$M(2,3) = \begin{pmatrix} 1 & 2 & \cancel{3} \\ 2 & 7 & 9 \\ 3 & 4 & 5 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$$

etc.

$$\text{Then } |M| = m_{11}|M(1,1)| - m_{12}|M(1,2)| + m_{13}|M(1,3)| - m_{14}|M(1,4)| \pm \dots + (-1)^{n+1}|M(1,n)|$$

$(M \text{ } n \times n)$

Using $\begin{pmatrix} + & - & + & - & + & - & + & \dots \\ - & + & - & + & - & + & - & \dots \\ + & - & + & - & + & - & + & \dots \\ \dots & & & & & & & \end{pmatrix}$

(2)

you can compute the det by expanding any row by minors.

Example. $\begin{vmatrix} 1 & 2 & 3 \\ 2 & 7 & 9 \\ 3 & 4 & 5 \end{vmatrix} = 1 \cdot \begin{vmatrix} 7 & 9 \\ 4 & 5 \end{vmatrix} - 2 \begin{vmatrix} 2 & 9 \\ 3 & 5 \end{vmatrix} + 3 \begin{vmatrix} 2 & 7 \\ 3 & 4 \end{vmatrix}$

$$= (35 - 36) - 2(10 - 27) + 3(8 - 21)$$

$$= -1 - 2(-17) + 3(-13)$$

$$= -1 + 34 - 39$$

$$= -6$$

or

$$\begin{vmatrix} 1 & 2 & 3 \\ 2 & 7 & 9 \\ 3 & 4 & 5 \end{vmatrix} \xrightarrow{\text{(2nd row)}} -2 \begin{vmatrix} 2 & 3 \\ 3 & 5 \end{vmatrix} + 7 \begin{vmatrix} 1 & 3 \\ 3 & 5 \end{vmatrix} - 9 \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix}$$

$$= -2(10 - 12) + 7(5 - 9) - 9(4 - 6)$$

$$= -2(-2) + 7(-4) - 9(-2)$$

$$= 4 - 28 + 18$$

$$= -6$$

There is a better definition of determinants. Think of the matrix $(n \times n)$ as n rows of vectors of size n .

$$M = \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_n \end{pmatrix}$$

$$\text{then } |M| = \text{Det}(M) = D \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_n \end{pmatrix}$$

is a function of the n -rows that satisfies the following properties:

1) $D \begin{pmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{pmatrix} = 1$ (Det(I_n) = 1)

2) If you interchange any two rows, the det changes sign.

e.g. $D \begin{pmatrix} \vec{r}_2 \\ \vec{r}_1 \\ \vec{r}_3 \\ \vdots \\ \vec{r}_n \end{pmatrix} = -D \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vec{r}_3 \\ \vdots \\ \vec{r}_n \end{pmatrix}$

3) D is a linear function of each row. (go to next page)

(4)

A function $F(\vec{v})$ defined on vectors is said to be linear

if (a) $F(\vec{v} + \vec{w}) = F(\vec{v}) + F(\vec{w})$

(b) $F(k\vec{v}) = kF(\vec{v})$

where \vec{v}, \vec{w} are vectors and k is a constant.

Thus we mean that e.g.

$$D \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 + k\vec{r}_2' \\ \vec{r}_3 \end{pmatrix} = D \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vec{r}_3 \end{pmatrix} + kD \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2' \\ \vec{r}_3 \end{pmatrix}$$

These 3 rules allow us to calculate any det.

e.g. $D \begin{pmatrix} a & b \\ c & d \end{pmatrix} = D \begin{pmatrix} a(1,0) + b(0,1) \\ c & d \end{pmatrix}$
 $= aD \begin{pmatrix} 1 & 0 \\ c & d \end{pmatrix} + bD \begin{pmatrix} 0 & 1 \\ c & d \end{pmatrix}$

$$= a \left[cD \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} + dD \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right] + b \left[dD \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + cD \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} \right]$$

But consider $\begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} \xrightarrow{\text{Interchange}} \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} \Rightarrow D \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} = 0$
and $D \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} = 0$ also.

$$\text{So } D \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad D \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + bc D \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

(5)

$$\text{But } D \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = 1$$

$$\text{and } D \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = -D \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

(by interchange),

$$\text{So } D \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc /$$

as expected!

Note: Interchange \Rightarrow If M has two equal rows, then $|M| = \phi$.

Why?
Because $D = -D$
 $\Rightarrow D = \phi$.

Linearity \Rightarrow If M has a zero row, then $|M| = \phi$.

(Why?)

(because $F(\vec{0}) = F(\vec{0} + \vec{0}) = F(\vec{0}) + F(\vec{0})$
 $\Rightarrow \phi = F(\vec{0})$ if
 F is linear.)

Row Operations

$$D \begin{pmatrix} k\vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_n \end{pmatrix} = k D \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_n \end{pmatrix} \quad (\text{+ same for any row})$$

$$\begin{aligned}
 D \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 + k\vec{r}_1 \\ \vec{r}_3 \\ \vdots \\ \vec{r}_n \end{pmatrix} &\stackrel{\text{linearity}}{=} D \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vec{r}_3 \\ \vdots \\ \vec{r}_n \end{pmatrix} + D \begin{pmatrix} \vec{r}_1 \\ k\vec{r}_1 \\ \vec{r}_3 \\ \vdots \\ \vec{r}_n \end{pmatrix} \\
 &= D \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vec{r}_3 \\ \vdots \\ \vec{r}_n \end{pmatrix} + k D \begin{pmatrix} \vec{r}_1 \\ \vec{r}_1 \\ \vec{r}_3 \\ \vdots \\ \vec{r}_n \end{pmatrix} \quad \left(\begin{array}{l} \text{same} \\ \text{same} \end{array} \right) \\
 &= D \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_n \end{pmatrix}
 \end{aligned}$$

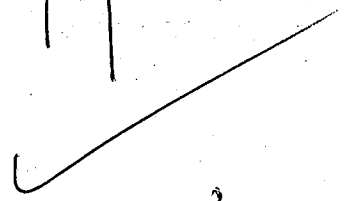
The basic row operation of replacing a row by a multiple of another row does not change the determinant.

Using the Rules

(6)

$$\begin{vmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 3 \end{vmatrix} = 2 \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 1/2 \\ 0 & 0 & 3 \end{vmatrix} = 2 \cdot 3 \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 1/2 \\ 0 & 0 & 1 \end{vmatrix}$$

$$= 6 \begin{vmatrix} 1 & 0 & 1/2 \\ 0 & 1 & 1/2 \\ 0 & 0 & 1 \end{vmatrix} = 6 \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 6$$



$$\begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & -1 & 2 \end{vmatrix}$$

$$= \begin{vmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{vmatrix} = 2 = \checkmark (6 - 2 - 2)$$

$$= \cancel{12} \begin{vmatrix} 1 & 1 \\ 0 & 3 \end{vmatrix} - \begin{vmatrix} 1 & 1 \\ 1 & 3 \end{vmatrix} + \begin{vmatrix} 1 & 2 \\ 1 & 0 \end{vmatrix}$$

eg.
$$\begin{vmatrix} 0 & 1 & 0 \\ d & e & f \\ g & h & k \end{vmatrix} = \begin{vmatrix} 0 & 1 & 0 \\ d & 0 & f \\ g & 0 & k \end{vmatrix}$$

Then it is not hard to see that the above will calculate to $\begin{vmatrix} d & f \\ g & k \end{vmatrix} \cdot \begin{vmatrix} 0 & 1 & 0 \\ \square & 0 & \square \\ \square & 0 & \square \end{vmatrix}$

$$\neq \begin{vmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{vmatrix} = - \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = -1.$$

This is the source of the minor determinant and the sign in the row-expansion formula.

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & k \end{vmatrix} = a \begin{vmatrix} 1 & 0 & 0 \\ d & e & f \\ g & h & k \end{vmatrix} + b \begin{vmatrix} 0 & 1 & 0 \\ d & e & f \\ g & h & k \end{vmatrix} + c \begin{vmatrix} 0 & 0 & 1 \\ d & e & f \\ g & h & k \end{vmatrix}$$

$$= a \begin{vmatrix} 1 & 0 & 0 \\ 0 & e & f \\ 0 & h & k \end{vmatrix} + b \begin{vmatrix} 0 & 1 & 0 \\ d & 0 & f \\ g & 0 & k \end{vmatrix} + c \begin{vmatrix} 0 & 0 & 1 \\ d & e & 0 \\ g & h & 0 \end{vmatrix} = \text{next page}$$

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & k \end{vmatrix} = a \begin{vmatrix} e & f \\ h & k \end{vmatrix} - b \begin{vmatrix} d & f \\ g & k \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$

Adjoint Matrix

$$Ad(A) = B, \quad A_{n \times n}$$

$$B_{ij} = (-1)^{i+j} |M(A)(i,j)|$$

e.g. $A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 7 & 9 \\ 3 & 4 & 5 \end{pmatrix}; \quad B = Ad(A)$

$$B = \begin{pmatrix} + \begin{vmatrix} 7 & 9 \\ 4 & 5 \end{vmatrix} & - \begin{vmatrix} 2 & 9 \\ 3 & 5 \end{vmatrix} & + \begin{vmatrix} 2 & 7 \\ 3 & 4 \end{vmatrix} \\ - \begin{vmatrix} 2 & 3 \\ 4 & 5 \end{vmatrix} & + \begin{vmatrix} 1 & 3 \\ 3 & 5 \end{vmatrix} & - \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} \\ + \begin{vmatrix} 2 & 3 \\ 2 & 7 \end{vmatrix} & - \begin{vmatrix} 1 & 3 \\ 2 & 9 \end{vmatrix} & + \begin{vmatrix} 1 & 2 \\ 2 & 7 \end{vmatrix} \end{pmatrix}$$

$$= \begin{pmatrix} -1 & 17 & -13 \\ 2 & -4 & 2 \\ -3 & -3 & 3 \end{pmatrix}$$

$$AB^T = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 7 & 9 \\ 3 & 4 & 5 \end{pmatrix} \begin{pmatrix} -1 & 2 & -3 \\ 17 & -4 & -3 \\ -13 & 2 & 3 \end{pmatrix}$$

$$\begin{pmatrix} -6 & 0 & 0 \\ 0 & -6 & 0 \\ 0 & 0 & -6 \end{pmatrix}$$

$$\stackrel{||}{=} (-6) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = -6I_3$$

Theorem. $B = Ad(A), A_{n \times n}$, then $AB^T = \det(A) I_n$.

$$A \operatorname{Ad}(A)^T = \operatorname{Det}(A) \mathbf{I}_n.$$

(9)

Thus if $\operatorname{Det}(A) \neq 0$, then

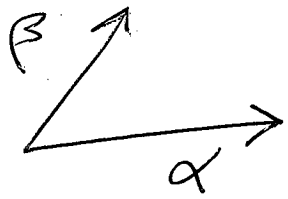
$$A^{-1} = \frac{1}{\operatorname{Det}(A)} \operatorname{Ad}(A)^T.$$

Thus we have an explicit formula for the inverse of an $n \times n$ matrix.

So why is this correct that $A B^T = \operatorname{Det}(A) \mathbf{I}$?

Exercise. Let $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$. Find A^{-1} by using $\operatorname{Ad}(A)$.

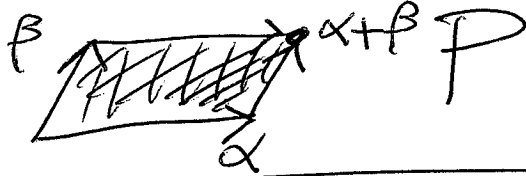
Hermann Grassmann (≈ 1880) ⑩



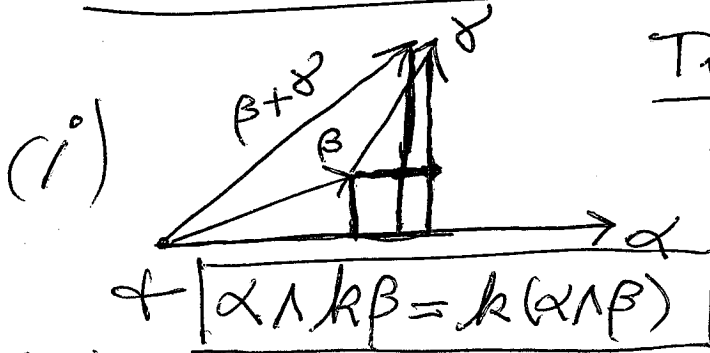
Invent a product for vectors

$$\alpha \wedge \beta$$

that will calculate the area of the parallelogram spanned by them.

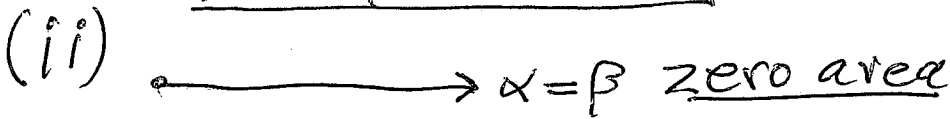


$$\text{Area}(P) = h \times \|\alpha\| \quad (\text{why?})$$



Triangle Areas Add.

$$S_0 \quad \alpha \wedge (\beta + \gamma) = \alpha \wedge \beta + \alpha \wedge \gamma$$



$$\alpha \wedge \alpha = 0$$

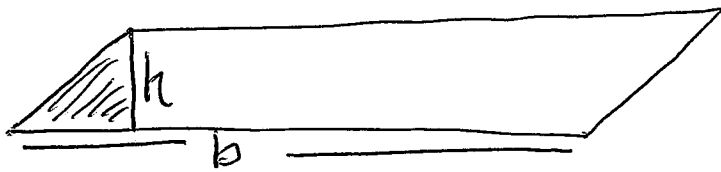
But then:

$$\begin{aligned} 0 &= (\alpha + \beta) \wedge (\alpha + \beta) \\ &= (\alpha + \beta) \wedge \alpha + (\alpha + \beta) \wedge \beta \\ &= \alpha \wedge \alpha + \beta \wedge \alpha + \alpha \wedge \beta + \beta \wedge \beta \\ &= 0 + \beta \wedge \alpha + \alpha \wedge \beta + 0 \end{aligned}$$

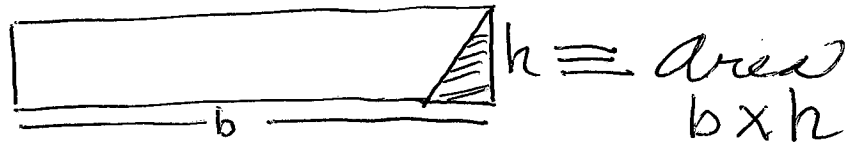
$$0 = \beta \wedge \alpha + \alpha \wedge \beta$$

So

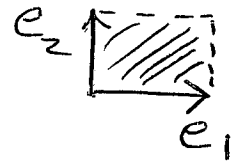
$$\alpha \wedge \beta = -\beta \wedge \alpha$$



||| same area



Suppose $e_1 = (1, 0)$
 $e_2 = (0, 1)$.



Then we want $e_1 \wedge e_2 = 1$.

Now. $(ae_1 + be_2) \wedge (ce_1 + de_2)$

$$= (ae_1 + be_2) \wedge (ce_1) + (ae_1 + be_2) \wedge (de_2)$$

$$= ac(e_1 \wedge e_1) + bc(e_2 \wedge e_1) + ad(e_1 \wedge e_2) + ad(e_2 \wedge e_2)$$

$$= 0 + bc(e_2 \wedge e_1) + ad(e_1 \wedge e_2) + 0$$

$$= bc(-e_1 \wedge e_2) + ad(e_1 \wedge e_2)$$

$$= (ad - bc)(e_1 \wedge e_2)$$

$$= ad - bc.$$

So Grassmann's method works! And it is "the same" as our theory of determinants.