

Depth-first Search in Digraphs — examples

\Rightarrow denotes a tree edge.

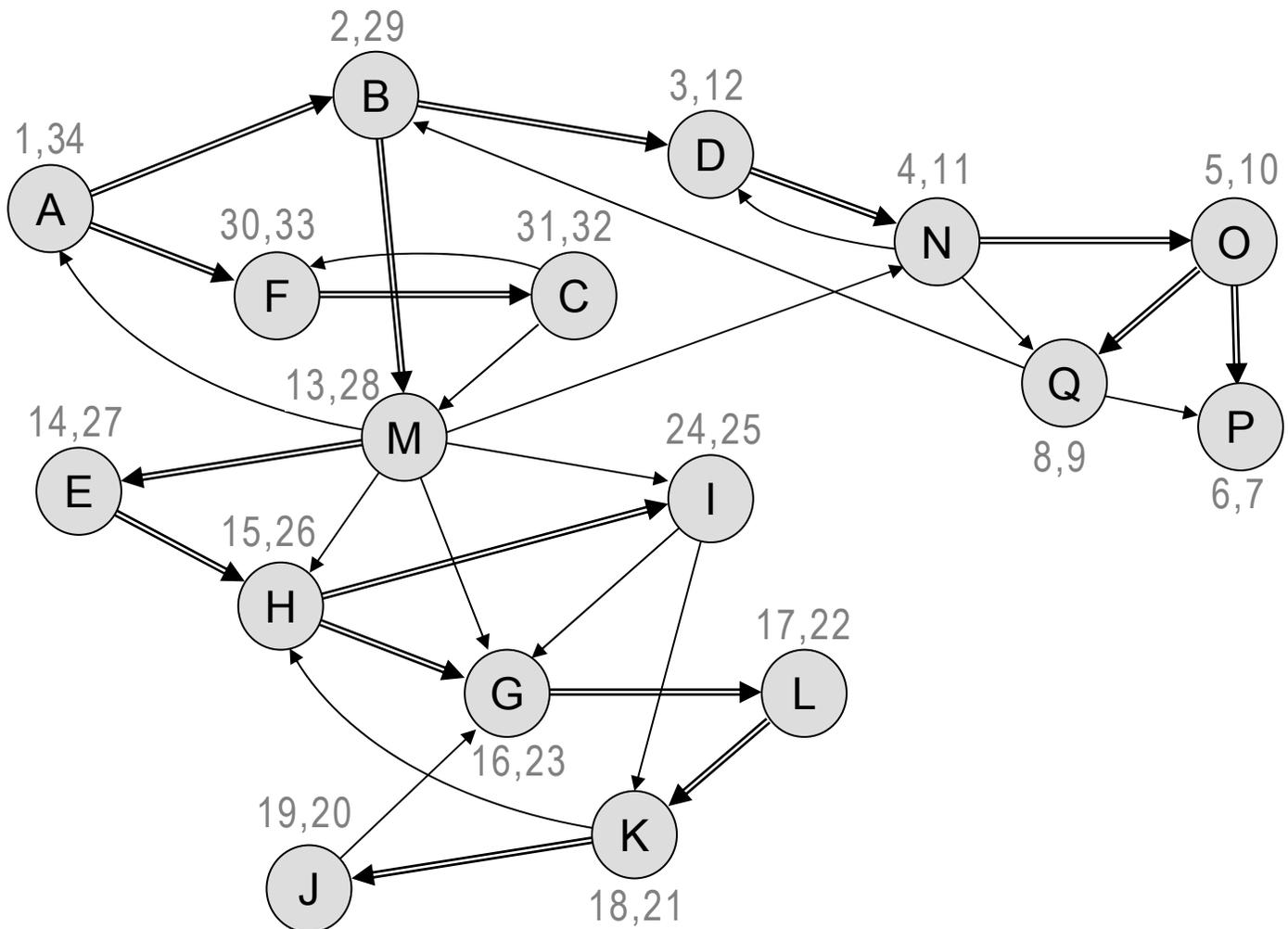
$d(v), f(v)$ appears above or below each node v :

$d(v)$ = *discovery time* of node v . The time at which node v is first reached. The time of *preorder processing*.

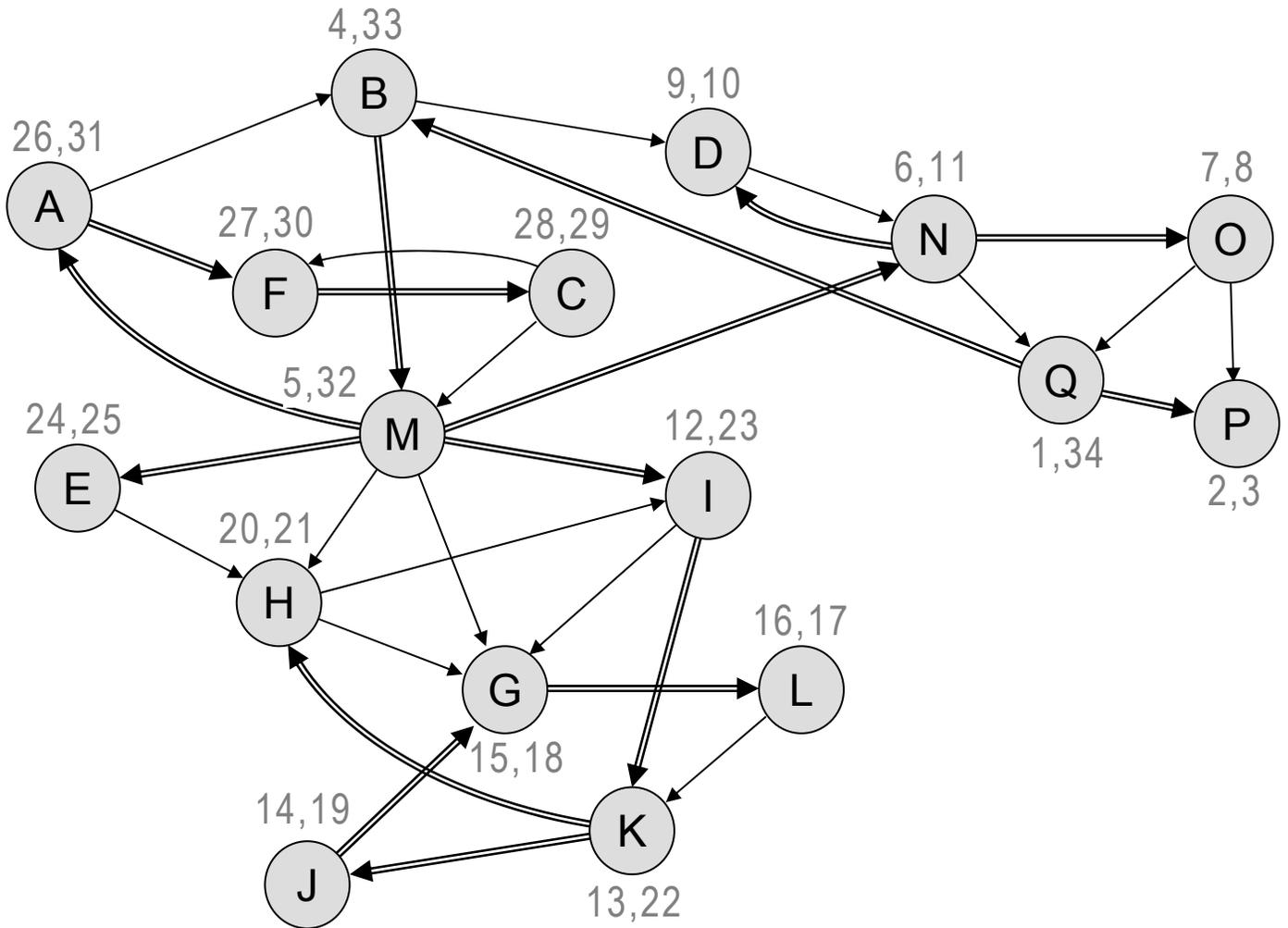
$f(v)$ = *finish time* of node v . The time at which node v is exited for the last time. The time of *postorder processing*.

For a node v , $active(v)$ = time interval $d(v)$ to $f(v)$ (inclusive).

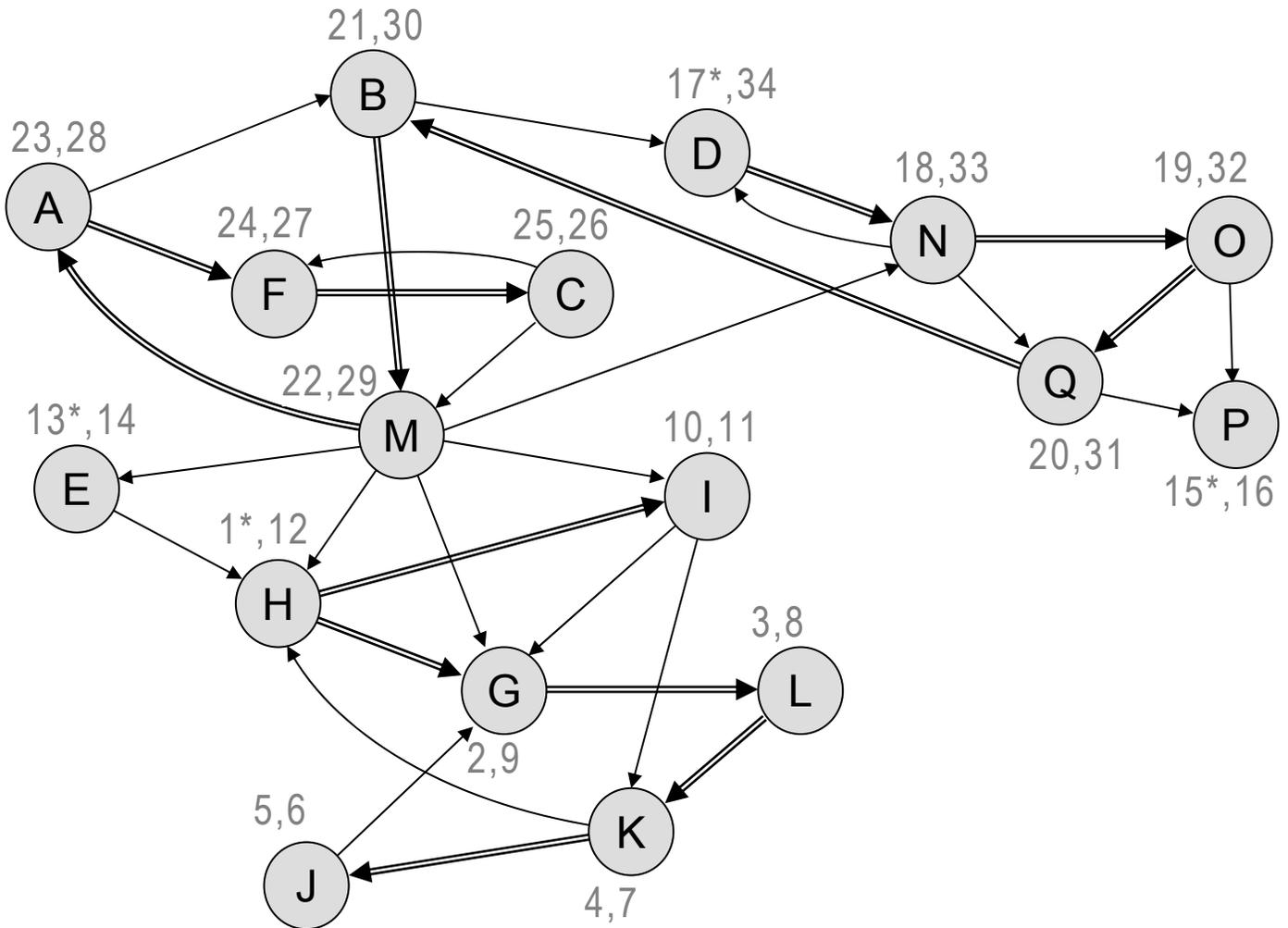
Example 1: In this particular depth-first search, the alphabetically-first node is chosen, whenever an arbitrary choice is made.



Example 2: Depth-first search of the same digraph. The alphabetically-last node is chosen, whenever an arbitrary choice is made.



Example 3: Depth-first search of the same digraph. In choosing among adjacent vertices not yet discovered, the alphabetically-first vertex is chosen. However, we choose H as the starting vertex, and when the stack becomes empty (which didn't occur in Example 1 or 2), we choose E, then P, and then D as the next vertex to discover.



Depth-first Search in Digraphs — edges classified

Edge (u,v) is

a *tree edge* if $active(u) \supset active(v)$, and there is no vertex x with $active(u) \supset active(x) \supset active(v)$,

a *forward edge* if $active(u) \supset active(v)$, but (u,v) is not a tree edge,

a *back edge* if $active(u) \subset active(v)$,

a *cross edge* if $active(u) \cap active(v) = \emptyset$ (in which case $active(v)$ entirely precedes $active(u)$).

\Rightarrow denotes a *tree edge*.

$---\rightarrow$ denotes a *back edge*.

$- \cdot - \cdot - \rightarrow$ denotes a *forward edge*.

$\cdots\cdots\cdots\rightarrow$ denotes a *cross edge*.

} In an undirected graph,
these two types are not
distinguishable

Here depth-first search of Example 1, with edges classified.

